Module Leader

Prof MC Smith [1]

Lecturer

Prof M Smith [1]

Lab Leader

Prof M Smith [1]

Timing and Structure

Michaelmas term. 12 lectures + 2 examples classes + coursework. Assessment: 75% exam/25% coursework

Prerequisites

3F1 and 3F2 useful

Aims

The aims of the course are to:

- establish for the students a fundamental approach to the design of linear control systems.

Objectives

As specific objectives, by the end of the course students should be able to:

- understand the role and importance of feedback for the control of uncertain dynamical systems.
- demonstrate the information conveyed via root locus diagrams for transient behaviour and basic frequency response analysis using Nyquist (polar) and Bode plots.
- following its basic derivation, illustrate the use of the Nyquist stability criterion with both open loop stable and open loop unstable systems;
- understand factors which limit achievable performance in feedback systems.
- use analytical tools to understand trade-offs (e.g. Bode gain/phase relations, sensitivity integrals).
- translate general requirements for robustness and performance into specifications on the open-loop frequency response.
- use computer software for simple control system design and system simulation
- design simple compensators to achieve such specifications.

Content

Control system design (11L)

- System dynamics, stability and instability, principles and use of root locus plots, derivation of Nyquist
stability criterion, Bode theorems and plots.

- Two degree of freedom design.

**Introduction to Coursework (1L)**

Case studies and simulation.

**Coursework**

Case studies and design by simulation and computer software, e.g. use of Matlab. Four hours DPO time plus report (further four hours).

<table>
<thead>
<tr>
<th>Coursework</th>
<th>Format</th>
<th>Due date &amp; marks</th>
</tr>
</thead>
<tbody>
<tr>
<td>[Coursework activity #1 title / Interim]</td>
<td>Individual/group</td>
<td>day during term</td>
</tr>
<tr>
<td>Coursework 1 brief description</td>
<td>Report / Presentation</td>
<td>Thu week 3</td>
</tr>
<tr>
<td>Learning objective:</td>
<td>[non] anonymously marked</td>
<td>[x/60]</td>
</tr>
<tr>
<td>[Coursework activity #2 title / Final]</td>
<td>Individual Report</td>
<td>Wed week 9</td>
</tr>
<tr>
<td>Coursework 2 brief description</td>
<td>anonymously marked</td>
<td>[x/60]</td>
</tr>
<tr>
<td>Learning objective:</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Booklists**

Please see the Booklist for Group F Courses [2] for references for this module.

**Examination Guidelines**

Please refer to Form & conduct of the examinations [3].

**UK-SPEC**

The UK Standard for Professional Engineering Competence (UK-SPEC) [4] describes the requirements that have to be met in order to become a Chartered Engineer, and gives examples of ways of doing this.

UK-SPEC is published by the Engineering Council on behalf of the UK engineering profession. The standard has been developed, and is regularly updated, by panels representing professional engineering institutions, employers and engineering educators. Of particular relevance here is the Accreditation of Higher Education Programmes’ (AHEP) document [5] which sets out the standard for degree accreditation.
The Output Standards Matrices [6] indicate where each of the Output Criteria as specified in the AHEP 3rd edition document is addressed within the Engineering and Manufacturing Engineering Triposes.

Last modified: 28/05/2019 15:07

Source URL (modified on 28-05-19): http://teaching.eng.cam.ac.uk/content/engineering-tripos-part-iib-4f1-control-system-design-2019-20

Links
[1] mailto:mcs1000@cam.ac.uk