4M12 Crib 2017 1 1 (a) For x = 0, $\nabla^{2} f^{(t)} = \frac{1}{r^{2}} \frac{\partial}{\partial r^{2}} r^{2} \frac{\partial}{\partial r} \left(\frac{1}{4\pi r} \right)$ $= \frac{1}{r^2} \frac{3}{3r^2} \left[r^2 \left(\frac{-1}{4rr^2} \right) \right]$ = 6 $\int \Xi^2 f^{(e)} dv = \begin{cases} \Xi F^{(e)} \cdot d\Sigma \\ \Xi F^{(e)} \cdot d\Sigma \end{cases}$ NR $= \oint \left(\frac{-\hat{\chi}_{r}}{4\pi r^{2}}\right) \cdot ds$ $=-\frac{9}{4\pi r^2}$ [30%] = -1 (b) Shift origin. Sol to $= \frac{1}{2}f = -\frac{5}{5}(2-\frac{1}{2})$ · vs $f(x) = \frac{s'}{4\pi (x - x')}$ Superportion : solution to = -S(x)1 5 $f(x) = \int \frac{S(x')}{4\pi i x - x' i} dv'$ [20 %]

2 (c)J.E= p/E., E=- JV $=) = - p | \epsilon$ Soln. is $V(\mathbf{k}) = \frac{1}{100} \left[\frac{P(\mathbf{z}')}{100 - \mathbf{z}'} \frac{1}{100} \right]$ (note 21 integration of 7) But $\nabla \left(\frac{1}{r}\right) = -\frac{2r}{r^2} = -\frac{r}{r^3}$ =) = $\left(\frac{1}{|x-x'|}\right) = -\frac{(x-x')}{|x-x'|^3}$ (change of origin) =) $E(x) = \frac{1}{4176} \int p(x') \frac{(x-x')}{1x-x'} dV'$ [25%] $|x - x||^{-1} = \int (x - x')^{2} \int \frac{1}{2} = [x^{2} - 2x - x' + x'^{2}]^{-1/2}$ (d) $= \frac{1}{124} \left[1 - \frac{2 \cdot x \cdot x'}{x^2} + \cdots \right]^{-1/2}$ $= \frac{1}{124} \left[1 + \frac{\chi_1 \chi_2}{\chi_2} + \cdots \right]$ $\Rightarrow V = \frac{1}{41TE} \int p(x') \left[\frac{1}{121} + \frac{x \cdot x'}{1213} + \cdots \right] dv'$ =) $V(x) = \frac{1}{4\pi\epsilon} \int \frac{1}{1\times 1} \int p(x') dv' + \frac{x}{1x+3} \cdot \int x' p(x') dv' + ...$ [25%]

$$\begin{array}{c} \textcircled{3} \\ \hline (a) \quad y = A_0 \left[\cos((k_1 z - \omega_1 z) + \cos(k_0 x - \omega_2 z)) \right] \\ = 2 A_0 \left[\cos((t_1(k_1, k_0) x - \frac{1}{2}(\omega_1, \omega_0) t) \cos((t_0(k_1 x - \omega_0 t)) \right] \\ = 2 A_0 \cos((t_0(k_1 x - \frac{k_0}{k_1} z)) \cos((k_0 x - \omega_0 t)) \\ = 2 A_0 \cos((t_0(k_1 x - \frac{k_0}{k_1} z)) \cos((k_0 x - \omega_0 t)) \\ = A(x, z) \exp[j(k_0 x - \omega_0 z)] \\ \hline (k_0 x - A(x, z)) \exp[j(k_0 x - \omega_0 z)] \\ \hline (k_1 x - \frac{k_0}{k_1} z) = \frac{1}{2} A_0 \cos[\frac{1}{2} \frac{k_0}{k_1} z - \frac{k_0}{k_1} z] \\ \hline (k_1 x - \frac{k_0}{k_1} z) = \frac{1}{2} A_0 \cos[\frac{1}{2} \frac{k_0}{k_1} z - \frac{k_0}{k_1} z] \\ \hline (k_1 x - \frac{k_0}{k_1} z) = \frac{1}{2} \alpha(k_1 x - \frac{k_0}{k_1} z) \left[\frac{k_1 k_0}{k_1} x + k_0 x - \omega_0 z - \frac{k_0}{k_1} (k - k_0) t \right] dk \\ \hline (k_1 x - \omega_0 z) \left[\frac{1}{2} \frac{k_0}{k_1} x + k_0 x - \omega_0 z - \frac{k_0}{k_1} (k - k_0) t \right] dk \\ \hline = \exp[j(k_0 x - \omega_0 z)] \int \alpha(k_0 x x p [j(k_0 - k_1) x - \frac{k_0}{k_1} t] dk \\ = 2 \exp[j(k_0 x - \omega_0 z)] \int \alpha(k_0 x p [j(k_0 - x) - \omega_0 z)] \\ \hline (k_0 x - \omega_0 z) \left[\frac{k_0}{k_1} z - \frac{k_0}{k_1} z - \frac{k_0}{k_1} z \right] \\ \hline amplitude function travels \\ \alpha z = spec_1 - d\omega/dk \\ \hline = 2 \operatorname{Op} u ve(\alpha_0 z y) = \frac{1}{2} \operatorname{K} [k_0 z] \\ \hline \end{array}$$

(5)

$$\frac{3}{3} (a) \left[\underbrace{a \times (b \times c]_{i}}_{i} = \varepsilon_{ijk} a_{j} \left[\underbrace{b \times c}_{k} \right]_{k} \\
= \varepsilon_{ijk} \varepsilon_{klm} a_{j} b_{l} c_{m} \\
= \left(\underbrace{s}_{il} \delta_{jm} - \delta_{im} \delta_{jl} \right) a_{j} b_{l} c_{m} \\
= a_{j} b_{i} c_{j} - a_{j} b_{j} c_{i} \\
= (\underline{a} \cdot \underline{c}) b_{i} - (\underline{a} \cdot \underline{b}) \underbrace{c}_{i} \\
a_{k} (\underline{b} \times \underline{c}) = (\underline{a} \cdot \underline{c}) \underbrace{b}_{i} - (\underline{a} \cdot \underline{b}) \underbrace{c}_{i} \\
\beta = \underline{a} \cdot \underline{c} , \ \delta = - \underline{a} \cdot \underline{b} . \quad [20\%]$$

(b)
$$Tr(\underline{A}, \underline{B}) = [\underline{A} \cdot \underline{B}]_{ii} = A_{ij} B_{ji}$$

 $= \frac{1}{2} (A_{ij} B_{ji} + A_{ij} B_{ji}) \qquad \underline{A} \qquad symmetric$
 $= \frac{1}{2} (A_{ij} B_{ji} - A_{ij} B_{ji}) \qquad \underline{B} \qquad anti symmetric$
 $A_{ji} B_{ij}$

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[25]]

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$$\begin{bmatrix} \nabla \times (\nabla \times \underline{F}) \end{bmatrix}_{i} = \mathcal{E}_{ijk} \frac{\partial}{\partial x_{i}} [\nabla \times \underline{F}]_{k}$$

$$= \mathcal{E}_{ijk} \frac{\partial}{\partial x_{j}} (\mathcal{E}_{klm} \frac{\partial F_{m}}{\partial x_{j} \partial x_{l}})$$

$$= \mathcal{E}_{ijk} \mathcal{E}_{klm} \frac{\partial^{2} F_{m}}{\partial x_{j} \partial x_{l}}$$

$$= (\delta_{il} \delta_{jm} - \delta_{im} \delta_{jl}) \frac{\partial^{2} F_{m}}{\partial x_{j} \partial x_{l}}$$

$$= \frac{\partial^{2} F_{m}}{\partial \mathcal{E}_{m} \partial x_{i}} - \frac{\partial^{2} F_{i}}{\partial x_{j} \partial x_{j}}$$

$$= \frac{\partial^{2} F_{m}}{\partial \mathcal{E}_{m} \partial x_{i}} - \frac{\partial^{2} F_{i}}{\partial x_{j} \partial x_{j}} = \frac{\partial}{\partial x_{j}} (\nabla \underline{F}) - \frac{\partial^{2}}{\partial x_{j} \partial x_{j}} (F_{i})$$

$$= \frac{\partial}{\partial x_{i}} (\frac{\partial F_{m}}{\partial x_{m}}) - \frac{\partial^{2} F_{i}}{\partial x_{j} \partial x_{j}} = \frac{\partial}{\partial x_{i}} (\nabla \underline{\nabla} \underline{F}) - \nabla^{2} \underline{F}$$

$$= \frac{\nabla (\nabla \times \underline{F}) = \nabla (\nabla \underline{F}) - \nabla^{2} \underline{F}$$

$$\begin{bmatrix} \nabla \times (\nabla \times \underline{F}) = \nabla (\nabla \underline{\nabla} \underline{F}) - \nabla^{2} \underline{F} \\ \nabla \times (\nabla \times \underline{F}) = \nabla (\nabla \underline{\nabla} \underline{F}) - \nabla^{2} \underline{F}$$

$$= \mathcal{E}_{ijk} \mathcal{E}_{jlm} \frac{\partial F_{m}}{\partial X_{l}} F_{k}$$

$$= \mathcal{E}_{ijk} \mathcal{E}_{jlm} \frac{\partial F_{m}}{\partial X_{l}} F_{k}$$

$$= \mathcal{E}_{ijk} \mathcal{E}_{jlm} \frac{\partial F_{m}}{\partial X_{l}} F_{k} = -\mathcal{E}_{ikk} \mathcal{E}_{jlm} \frac{\partial F_{m}}{\partial x_{l}} F_{k}$$

$$= \frac{\partial F_{i}}{\partial x_{k}} \mathcal{E}_{k} - \frac{\partial F_{k}}{\partial x_{i}} F_{k}$$

$$= \frac{\partial F_{i}}{\partial x_{k}} \mathcal{E}_{k} - \frac{\partial F_{k}}{\partial x_{i}} F_{k}$$

$$= \frac{\partial F_{i}}{\partial x_{k}} \mathcal{E}_{k} - \frac{\partial F_{k}}{\partial x_{i}} F_{k}$$

$$= \left[\underline{F} \nabla \underline{F} \right]_{i} - \left[\nabla \left(\frac{1}{2} \underline{F}^{2} \right) \right]_{i}$$

$$= \left[\underline{F} \nabla \underline{F} \right]_{i} - \left[\nabla \left(\frac{1}{2} \underline{F}^{2} \right) \right]_{i}$$

[30%]

G

$$\underline{\underline{4}} \quad (a) \qquad \text{Weak formulation, multiply Eqn(1) by test funder
$$\begin{array}{c} v \quad \text{and integrate on [o, T/c], with V(o)=o.} \\ \int_{0}^{T} \left(\frac{d^{2}u}{dx} - u + 1 \right) V \, dx = o \\ \text{integration by part, } \quad \frac{du}{dx} + \frac{dv}{dx} - \int_{0}^{T_{k}} \frac{du}{dx} \, \frac{dv}{dx} + uv - W \, dx = o \\ \text{apply boundary condition, } \int_{0}^{T_{k}} \frac{du}{dx} \, \frac{dv}{dx} + uv - W \, dx = 0 \\ \text{(b)} \quad \overline{u} = C_{1} \sin x \quad \text{is compatible with the boundary conditions at 0 and $\frac{1}{2}$, hence a compatible choice. Take test function $\overline{v} = \sin x$, we have

$$\int_{0}^{T_{k}} C_{1} (us^{2}x + \sin^{2}sc) \, dx = \int_{0}^{T_{k}} \sin x \, dx \\ T_{k} \quad C_{1} = A \Rightarrow C_{1} = 2/\pi, \quad \overline{u} = \frac{2}{\pi} \sin x \\ \text{(c)} \quad \text{From (a), we deduce the equivalent} \\ \text{Variational form of (1) is to dook for \\ \text{Stationary point of the functional} \\ L(u) = \int_{0}^{T_{k}} \left[\frac{d(u}{dx} + u^{2}) - u \, dx \\ \text{(d) Look for stationary point of, } \quad \overline{u} = \cos x \\ \text{(d)} \quad \text{Lock for stationary point of, } \quad \overline{u} = 2\sin x \\ \text{(d)} \quad \text{Look for stationary point of, } \quad \overline{u} = 2\sin x \\ \text{(d)} \quad \overline{u} = C_{2} \quad T_{k} - C_{2} \\ \frac{d\overline{L}}{dc_{2}} = \frac{\pi}{2} c_{2} - A = 0 \Rightarrow C_{2} = \frac{T_{k}}{2} \left[\frac{u}{u} = \frac{2\pi}{3} \sin x \, \sin x \, dx \\ = c_{2}^{2} \quad T_{k} - C_{2} \\ \frac{d\overline{L}}{dc_{k}} = \frac{\pi}{2} c_{k} - A = 0 \Rightarrow C_{k} = T_{k} \quad \overline{u} = \frac{2\pi}{3} \sin x \, \sin x \, dx \\ = c_{k}^{2} \quad T_{k} - C_{k} \\ \frac{d\overline{L}}{dc_{k}} = \frac{\pi}{2} c_{k} - A = 0 \Rightarrow C_{k} = T_{k} \quad \overline{u} = \frac{2\pi}{3} \sin x \, \sin x \, \sin x \, dx \\ = c_{k}^{2} \quad T_{k} - C_{k} \\ \frac{d\overline{L}}{dc_{k}} = \frac{\pi}{2} c_{k} - A = 0 \Rightarrow C_{k} = T_{k} \quad \overline{u} = \frac{2\pi}{3} \sin x \, \sin x \, \sin x \, dx \\ = c_{k}^{2} \quad T_{k} + c_{k} \\ \frac{d\overline{L}}{dc_{k}} = \frac{\pi}{2} c_{k} - A = 0 \Rightarrow C_{k} = T_{k} \quad \overline{u} = \frac{\pi}{3} \sin x \, \sin x \, \sin x \, dx \\ = c_{k}^{2} \quad T_{k} \quad$$$$$$

B



(e) The theoretical solution of Eqn (1)
is
$$U = 1 - \frac{e^{\pi - x} + e^{\pi x}}{e^{\pi} + 1}$$

Exact Approximate Error
 $\pi/8 \quad 0.291 \quad 0.244 \quad 16.4\%$
 $\pi/4 \quad 0.472 \quad 0.450 \quad 4.16\%$
 $\pi/8 \quad 0.570 \quad 0.588 \quad -3.13\%$
 $\pi/2 \quad 0.601 \quad 0.637 \quad -5.85\%$
(i) C.S. $q^2 - 4 = 0 \Rightarrow q = \pm 4$
 $u_c = A e^{\pi} + B e^{-\pi}$
(ii) P.T. $u_p = d$, $\frac{d^3u}{dx^2} = 0 \Rightarrow -d = -4 \Rightarrow a = 4$
(hii) general solution $u = Ae^{\pi} + Be^{-\pi}$
(iv) boundary conditions $u(0) = 0$, $\frac{du}{dx}(\pi/2) = 0$
 $\Rightarrow \qquad u = 1 - \frac{e^{\pi - \pi} + e^{\pi}}{e^{\pi} + 1}$
 (720%)

Engineering Parts IIA and IIB 2017 4M12 – Partial Differential Equations and Variational Methods

Assessor's Comments

General comments:

The examination was taken by 64 candidates, 23 in IIA and 41 in IIB.

Each question was marked out of 20 and three questions had to be attempted. The raw marks gave an average of 69.2% for IIA and 72.2% for IIB. The standard deviation is 17%.

The paper was relatively straightforward and the overall performance good. No scaling was applied.

Question 1: Greens function inversion of elliptic equations

A popular question with good performances from the students. Surprisingly, most students struggled somewhat with the power-law expansion at the end.

Question 2: Group velocity applied to wave-like PDEs

Another popular question with good performances from the students. Most marks were lost in part (b) where attempted to manipulate the integral were 'imaginative'.

Question 3: Index notation.

Another popular question. Index notation was taught in 2 hours. No question has been set on this subject for many years. It is good to see students did better than expected.

Question 4: Variational and weak formulation.

A less popular question. This question concerns the relationship between strong, weak and variational form of a PDF, and the numerical solution using Rayleigh-Ritz and Galerkin methods. Student did well with these concepts, but some of them were not able to find the correct analytic solution of a simple second order linear PDF.

P. A. Davidson, 14 May 2017