

HEMH/5

EGT2  
ENGINEERING TRIPOS PART IIA

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Friday 2 May 2014 9.30 to 11

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**Module 3C5**

**DYNAMICS**

*Answer not more than **three** questions.*

*All questions carry the same number of marks.*

*The **approximate** percentage of marks allocated to each part of a question is indicated in the right margin.*

*Write your candidate number **not** your name on the cover sheet.*

**STATIONERY REQUIREMENTS**

Single-sided script paper

**SPECIAL REQUIREMENTS TO BE SUPPLIED FOR THIS EXAM**

CUED approved calculator allowed

Attachment: 3C5 Dynamics and 3C6 Vibration data sheet (6 pages).

Engineering Data Book

**You may not start to read the questions printed on the subsequent pages of this question paper until instructed to do so.**

1 A circular cylindrical rotor of mass  $m$  and radius  $a$  spins freely on a light shaft BG. The centre of mass of the rotor is at G. The shaft is fixed at B to a light string OB of length  $L$  as shown in Fig. 1. The string is fixed at O. The distance BG is  $b$  and BG is aligned with the axis of the rotor. The rotor is spinning at a constant *fast* rate  $\omega$  and its polar moment of inertia can be taken as  $C = \frac{1}{2} ma^2$ . In steady-state precession the shaft BG remains horizontal and the angle  $\alpha$  between OB and the vertical is constant as shown in the figure. The plane OBG remains vertical and rotates at a steady rate  $\Omega$ .

(a) Draw a free-body diagram of the shaft and rotor and hence show that, given certain assumptions, the precession rate  $\Omega \approx \sqrt{\frac{g\alpha}{b}}$ , where  $g$  is the acceleration due to gravity. What assumptions have been made? [60%]

(b) Find an expression for the string angle  $\alpha$  in terms of  $g$ ,  $a$ ,  $b$  and  $\omega$ . [10%]

(c) Verify that the small- $\alpha$  assumption is consistent with the assumption of fast spin. [10%]

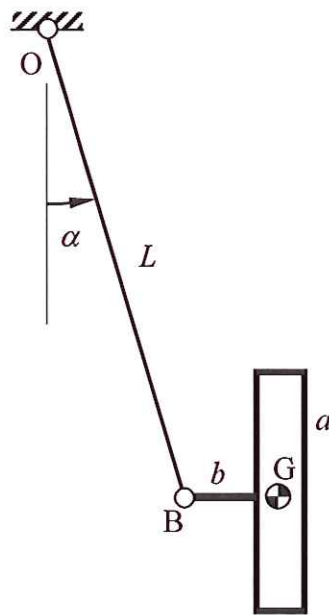


Fig. 1

2 An unbalanced ball comprises a solid uniform hemisphere of mass  $m$  and radius  $a$  fixed inside a light rigid spherical shell of the same radius as shown in Fig. 2. The centre of mass is at  $G$ , a distance  $\frac{3}{8}a$  from the centre of the ball which is at  $O$ . The ball rolls without slip on a horizontal plane.

There is a steady-state motion in which the centre of the ball moves at a constant speed  $v$  while following a circular path of radius  $R \gg a$ , centred on  $BB'$ . The line  $OG$  remains horizontal and directed at the centre of the circle as shown in the figure.

- (a) Use a no-slip condition to find an expression for the angular velocity of the ball during steady state motion [30%]
- (b) Find an expression for the path radius  $R$  in terms of  $v$  and  $g$ , where  $g$  is the acceleration due to gravity. [50%]
- (c) Show that the coefficient of friction between the ball and table must exceed  $\frac{15}{56}$ . [20%]

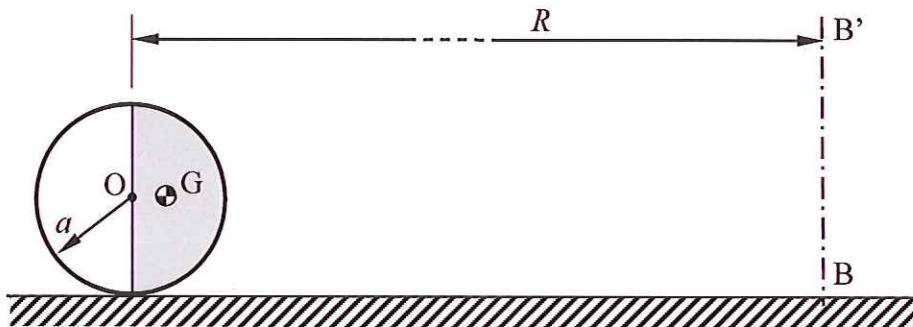


Fig. 2

3 (a) The puzzle shown in Fig. 3(a) is in the form of a cube of mass  $m$  and side  $a$ . It is assembled from 27 smaller solid cubes each of mass  $m/27$  and side  $a/3$ .

(i) Find the principal moments of inertia of the cube puzzle at the vertex A shown in Fig. 3(a). [25%]

(ii) The “top face” of the puzzle (comprising 9 cubes) is rotated through an angle of  $45^\circ$  as shown in Fig. 3(b). Find the principal moments of inertia of the face-rotated puzzle at point B. [25%]

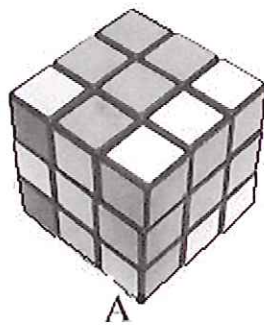


Fig. 3(a)

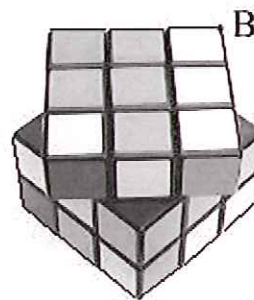


Fig. 3(b)

(b) (i) Explain briefly the conditions under which Lagrange’s equations can lead to conservation laws. [10%]

(ii) A GPS satellite of mass  $m$  orbits the Earth. Its position is described in terms of spherical polar coordinates  $(r, \theta, \phi)$  where  $r$  is distance from the centre of the Earth,  $\theta$  is polar angle measured downwards from the axis through the North pole, and  $\phi$  is angle of longitude. The gravitational potential of the Earth, allowing for the effect of the equatorial bulge, can be written

$$V = -\frac{GMm}{r} \left[ 1 - \frac{J_2 a^2}{2r^2} (3 \cos^2 \theta - 1) \right]$$

where  $a$  is the radius of the Earth and  $J_2$  is a dimensionless constant.

Find an expression for the kinetic energy of the satellite and use Lagrange’s equations to obtain a conservation law. Explain its physical interpretation. [40%]

4 A Porter governor, an early feedback device used on steam engines, is shown in Fig. 4. A mass  $M$  can slide freely on a massless vertical shaft  $OB$ , which rotates with constant angular velocity  $\Omega$  in response to an applied torque  $Q$ . Two equal masses  $m$  are joined to the mass  $M$  and to the top of the shaft by four massless bars of length  $a$ , freely hinged at all joints and inclined to the shaft by angle  $\theta$  as shown.

(a) Find expressions for the total kinetic and potential energies of the Porter governor. [20%]

(b) Use Lagrange's equation to show that the equation of motion governing  $\theta(t)$  is

$$(m + 2M \sin^2 \theta) \ddot{\theta} + 2M \sin \theta \cos \theta \dot{\theta}^2 - m \sin \theta \cos \theta \Omega^2 + (m + M) \frac{g}{a} \sin \theta = 0 . \quad [30\%]$$

(c) Find all possible equilibrium positions with  $\theta = \text{constant}$ , and investigate the stability of each. For any stable positions, find the frequency of small oscillations about the equilibrium. [50%]

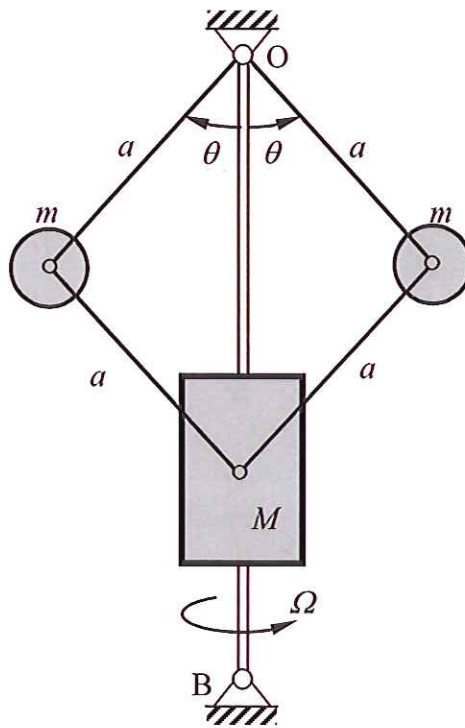


Fig. 4

**END OF PAPER**

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