

EGT2
ENGINEERING TRIPOS PART IIA

Tuesday 9 May 2023 9.30 to 11.10

Module 3D4

STRUCTURAL ANALYSIS AND STABILITY

*Answer not more than **three** questions.*

All questions carry the same number of marks.

*The **approximate** percentage of marks allocated to each part of a question is indicated in the right margin.*

*Write your candidate number **not** your name on the cover sheet.*

STATIONERY REQUIREMENTS

Single-sided script paper

Graph Paper

SPECIAL REQUIREMENTS TO BE SUPPLIED FOR THIS EXAM

CUED approved calculator allowed

Attachment: Data Sheet for Question 2 (2 pages)

Engineering Data Book

10 minutes reading time is allowed for this paper at the start of the exam.

You may not start to read the questions printed on the subsequent pages of this question paper until instructed to do so.

You may not remove any stationery from the Examination Room.

1 The thin-walled channel-like cross-section shown in Fig. 1 has a uniform thickness t and elastic modulus E .

(a) Determine the St. Venant torsion constant of the cross-section and explain whether restrained warping torsion is important or not. [15%]

(b) Calculate the principal second moments of area of the cross-section. [40%]

(c) Estimate the approximate position of the shear-centre of the cross-section and explain your reasoning. Provide a sketch indicating the relative position of the shear-centre in relation to the cross-section. [15%]

(d) A simply supported beam with length l and the given cross-section carries a concentrated force of magnitude F . The force acts in the negative y -direction at the shear-centre at midspan of the beam. Calculate the maximum deflection of the shear-centre of the beam. [30%]

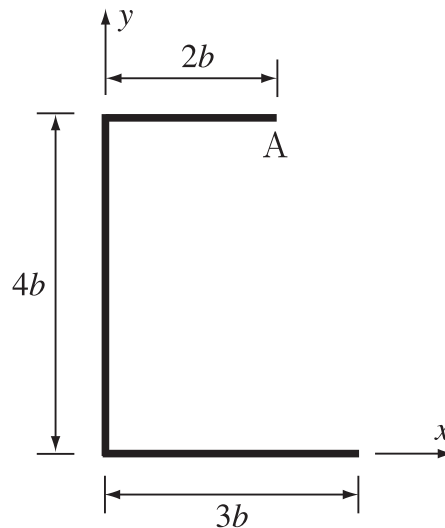


Fig. 1

2 (a) The three-span beam shown in Fig. 2(a) has a uniform stiffness EI . The left support is clamped and the centre span carries a uniformly distributed load w .

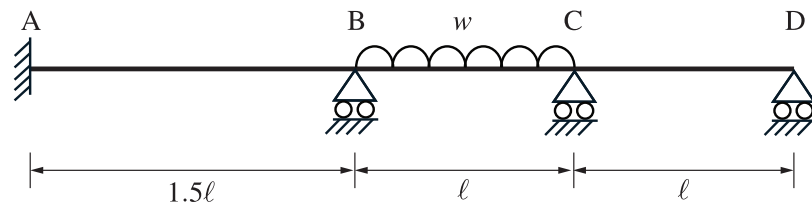
(i) Sketch the bending moment diagram while marking salient features. [10%]

(ii) Estimate the largest sagging moment at the centre span by providing a maximum and a minimum value. Explain your reasoning. [15%]

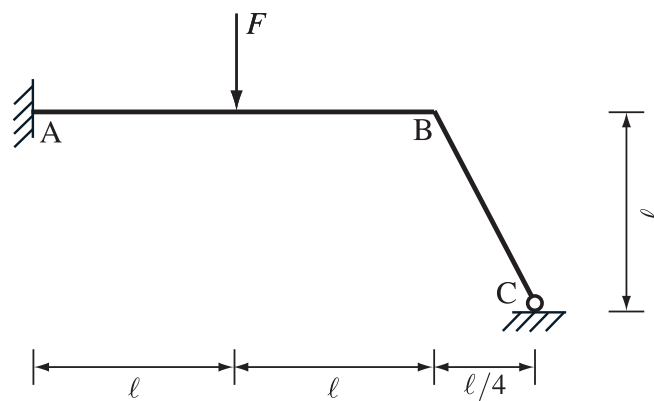
(b) Figure 2(b) shows a frame consisting of two beams that are rigidly connected at B. The beam AB carries a concentrated vertical load F at its mid-span and the flexural stiffness of the two beams is EI .

(i) Assume that the axial displacements in both beams can be neglected. Calculate the moment at the joint B. (Datasheet attached.) [35%]

(ii) Assume that the axial stiffness of the beam BC can be neglected and the axial stiffness of the beam AB is EA . Calculate the stiffness matrix of the structure. [40%]



(a)



(b)

Fig. 2

3 (a) Assuming a lateral deflected shape $w(x) = x^2(L - x)$, use Rayleigh's quotient to estimate the axial load that will cause flexural buckling of a cantilever of length L , clamped at $x = 0$, propped at $x = L$ and flexural rigidity EI . [30%]

(b) Do you expect your answer in part a) to be an over-estimate or an under-estimate of the true buckling load? Explain your reasoning. [10%]

(c) According to your estimate in part a), what is the effective length of a propped cantilever? [10%]

(d) Explain briefly how the Perry-Robertson formula deals with inelastic material behaviour. [10%]

(e) The Perry-Robertson formula for column buckling is

$$(\sigma_Y - \sigma_{cr})(\sigma_E - \sigma_{cr}) = \eta \sigma_{cr} \sigma_E$$

where σ_Y is the material yield stress, σ_E is the Euler stress, σ_{cr} is the stress at the section centroid when the column carries the critical buckling load P_{cr} and η is a dimensionless imperfection parameter.

Assume that $\eta = 0.003L/r$, where L is the column length and r is the radius of gyration of the column section with respect to bending about its minor axis. Determine the axial design load of an Euler column of length $L = 4$ m which has a circular hollow section of 168.3 mm external diameter and 12.5 mm wall thickness made of steel with yield stress of 275 MPa. [40%]

4 (a) The slope of a graph of load against deflection often corresponds to a stiffness. Explain why this might not always be the case and give an example. [20%]

(b) Figure 3 shows a frame ABC carrying a vertical load P applied at C. The support conditions are as shown in the diagram. Members AB and BC each have length L . Each may be considered to be axially rigid. The flexural rigidities of members AB and BC with respect to bending within the plane of the diagram are $2EI$ and EI respectively. Bending out of the plane of the diagram is prevented.

(i) Derive an expression for the rotational stiffness at B in terms of the s and c stability functions. [30%]

(ii) Using the table of s and c functions provided, estimate the smallest value of P that will cause in-plane flexural buckling of the frame. [30%]

(iii) Provide a clear sketch of the buckling mode, and indicate the magnitudes of the rotations of all joints expressed as a proportion of the rotation at B. [20%]

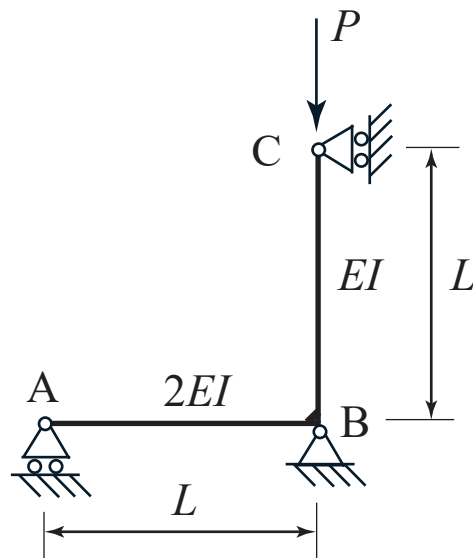


Fig. 3

Table 1. s and c stability functions for an Euler column. P is the axial load and P_E is the Euler load.

P/P_E	s	c
0.0	4.0000	0.5000
0.2	3.7297	0.5550
0.4	3.4439	0.6242
0.6	3.1403	0.7136
0.8	2.8159	0.8330
1.0	2.4674	1.0000
1.2	2.0901	1.2487
1.4	1.6782	1.6557
1.6	1.2240	2.4348
1.8	0.7170	4.4969
2.0	0.1428	24.6841
2.2	-0.5194	-7.5107
2.4	-1.3006	-3.3703
2.6	-2.2490	-2.2312
2.8	-3.4449	-1.7081
3.0	-5.0320	-1.4157

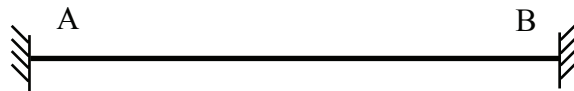
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Data Sheet for Question 2: Stiffness Matrices.

Notation and sign convention

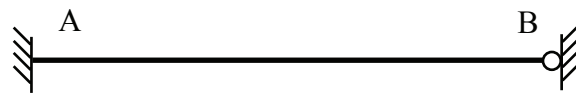


Beam type I



$$\begin{bmatrix} P_A \\ S_A \\ M_A \\ P_B \\ S_B \\ M_B \end{bmatrix} = \begin{bmatrix} \frac{EA}{L} & 0 & 0 & -\frac{EA}{L} & 0 & 0 \\ 0 & \frac{12EI}{L^3} & -\frac{6EI}{L^2} & 0 & -\frac{12EI}{L^3} & -\frac{6EI}{L^2} \\ 0 & -\frac{6EI}{L^2} & \frac{4EI}{L} & 0 & \frac{6EI}{L^2} & \frac{2EI}{L} \\ -\frac{EA}{L} & 0 & 0 & \frac{EA}{L} & 0 & 0 \\ 0 & -\frac{12EI}{L^3} & \frac{6EI}{L^2} & 0 & \frac{12EI}{L^3} & \frac{6EI}{L^2} \\ 0 & -\frac{6EI}{L^2} & \frac{2EI}{L} & 0 & \frac{6EI}{L^2} & \frac{4EI}{L} \end{bmatrix} \begin{bmatrix} u_A \\ w_A \\ \phi_A \\ u_B \\ w_B \\ \phi_B \end{bmatrix}$$

Beam type II



$$\begin{bmatrix} P_A \\ S_A \\ M_A \\ P_B \\ S_B \\ M_B \end{bmatrix} = \begin{bmatrix} \frac{EA}{L} & 0 & 0 & -\frac{EA}{L} & 0 & 0 \\ 0 & \frac{3EI}{L^3} & -\frac{3EI}{L^2} & 0 & -\frac{3EI}{L^3} & 0 \\ 0 & -\frac{3EI}{L^2} & \frac{3EI}{L} & 0 & \frac{3EI}{L^2} & 0 \\ -\frac{EA}{L} & 0 & 0 & \frac{EA}{L} & 0 & 0 \\ 0 & -\frac{3EI}{L^3} & \frac{3EI}{L^2} & 0 & \frac{3EI}{L^3} & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} u_A \\ w_A \\ \phi_A \\ u_B \\ w_B \\ \phi_B \end{bmatrix}$$