

EGT2  
ENGINEERING TRIPOS PART IIA

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Monday 1 May 2023 14.00 to 15.40

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**Module 3M1**

**MATHEMATICAL METHODS**

*Answer all the questions.*

*All questions carry the same number of marks.*

*The **approximate** percentage of marks allocated to each part of a question is indicated in the right margin.*

*Write your candidate number **not** your name on the cover sheet.*

**STATIONERY REQUIREMENTS**

Write on single-sided paper.

**SPECIAL REQUIREMENTS TO BE SUPPLIED FOR THIS EXAM**

CUED approved calculator allowed.

Engineering Data Books.

**10 minutes reading time is allowed for this paper at the start of the exam.**

**You may not start to read the questions printed on the subsequent pages of this question paper until instructed to do so.**

**You may not remove any stationery from the Examination Room.**

- 1 (a) For a function  $f : \mathbb{R}^n \rightarrow \mathbb{R}$ , consider its Taylor series expansion about  $\mathbf{x} \in \mathbb{R}^n$ ,

$$f(\mathbf{x} + \mathbf{v}) = f(\mathbf{x}) + (\nabla f)^T \mathbf{v} + \frac{1}{2} \mathbf{v}^T \mathbf{H} \mathbf{v} + O(\|\mathbf{v}\|^3),$$

where the matrix  $\mathbf{H} := \partial^2 f / \partial x_i \partial x_j$  is known as the *Hessian* of  $f$ .

- (i) Show that the Hessian is symmetric. [5%]  
 (ii) At a stationary point of  $f$  we have  $(\nabla f)^T \mathbf{v} = 0$  for all  $\mathbf{v}$ . Explain how the nature of a stationary point can be characterised in terms of properties of  $\mathbf{H}$ . [15%]  
 (iii) For a constant Hessian, consider  $\|\mathbf{x}\|_{\mathbf{H}}^2 := \mathbf{x}^T \mathbf{H} \mathbf{x}$ . Under what conditions is  $\|\mathbf{x}\|_{\mathbf{H}}$  a norm? Explain why. [10%]

- (b) A particular iterative scheme for finding approximate solutions to  $\mathbf{A}\mathbf{x} = \mathbf{b}$  uses the update:

$$\mathbf{x}_{k+1} = \mathbf{x}_k + w(\mathbf{b} - \mathbf{A}\mathbf{x}_k)$$

where  $w > 0$ .

- (i) Find an expression for the residual  $\mathbf{r}_k := \mathbf{b} - \mathbf{A}\mathbf{x}_k$  in terms of the initial residual  $\mathbf{r}_0$ . [20%]  
 (ii) Find an expression for the error  $\mathbf{e}_k := \mathbf{x}_k - \mathbf{x}$  in terms of  $\mathbf{e}_0$ . [20%]  
 (iii) For symmetric positive-definite  $\mathbf{A}$ , what range of values for  $w$  guarantees convergence, and what is the optimal value of  $w$  for convergence in the 2-norm? [30%]

2 For  $D$ -dimensional column vector  $\mathbf{x} = [x_1, x_2, \dots, x_D]^T \in \mathbb{R}^D$  consider the product of logistic functions

$$s(\mathbf{x}) = \prod_{d=1}^D \frac{1}{1 + \exp(-x_d)}$$

In addition consider the Gaussian distribution over  $\mathbf{x} \in \mathbb{R}^D$

$$\mathcal{N}(\mathbf{x}|\boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{\sqrt{(2\pi)^D |\boldsymbol{\Sigma}|}} \exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x} - \boldsymbol{\mu})\right)$$

with mean vector  $\boldsymbol{\mu} \in \mathbb{R}^D$  and  $D \times D$  covariance matrix  $\boldsymbol{\Sigma}$ . Consider the probability

$$P(\mathbf{x}|\boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{\mathcal{Z}(\boldsymbol{\mu}, \boldsymbol{\Sigma})} s(\mathbf{x}) \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}, \boldsymbol{\Sigma})$$

where  $\mathcal{Z}(\boldsymbol{\mu}, \boldsymbol{\Sigma}) = \int_{\mathbb{R}^D} s(\mathbf{x}) \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}, \boldsymbol{\Sigma}) d\mathbf{x}$

(a) Show that the point  $\mathbf{x}^* \in \mathbb{R}^D$  yielding the maximum value of  $P(\mathbf{x}|\boldsymbol{\mu}, \boldsymbol{\Sigma})$  can be obtained by minimising the function

$$f(\mathbf{x}) = \mathbf{1}^T \mathbf{g}(\mathbf{x}) + \frac{1}{2} \mathbf{x}^T \boldsymbol{\Sigma}^{-1} \mathbf{x} - \mathbf{x}^T \boldsymbol{\Sigma}^{-1} \boldsymbol{\mu}$$

where the  $D$ -dimensional vector of ones is denoted as  $\mathbf{1} = [1, 1, \dots, 1]^T$  and  $\mathbf{g}(\mathbf{x})$  is an element-wise application of the function  $g(\cdot)$  which acts on each component of the vector  $\mathbf{x}$  such that  $\mathbf{g}(\mathbf{x}) = [g(x_1), g(x_2), \dots, g(x_D)]^T$  with each  $g(\cdot)$  defined appropriately. [15%]

(b) Derive and justify the necessary condition for a point  $\mathbf{x}^* \in \mathbb{R}^D$  to be a strong local minimum of the function  $f(\mathbf{x})$ . [15%]

(c) Derive and justify the sufficient condition for a point  $\mathbf{x}^* \in \mathbb{R}^D$  to be a strong local minimum of the function  $f(\mathbf{x})$ . [15%]

(d) Derive a Newton optimisation method for the function  $f(\mathbf{x})$  acting on  $\mathbf{x} \in \mathbb{R}^D$ . [20%]

(e) For the specific case where  $D = 2$ , and  $\boldsymbol{\Sigma}$  is a diagonal covariance matrix, assess whether  $f(\mathbf{x})$  is convex in  $\mathbb{R}^2$  and state the implication on the nature of the point  $\mathbf{x}^*$ . [30%]

3 The transitions in a finite state space Markov chain are governed by an  $N \times N$  matrix,  $\mathbf{P}$ , with the following form

$$\mathbf{P} = \begin{bmatrix} \mathbf{P}_{11} & \mathbf{P}_{12} \\ \mathbf{0} & \mathbf{P}_{22} \end{bmatrix}$$

where element  $i, j$  of the matrix  $\mathbf{P}$  is the probability of transitioning to state  $j$  if the system is in state  $i$ .  $\mathbf{P}_{11}$  is a square  $m \times m$  matrix. The elements of  $\mathbf{P}_{11}$ ,  $\mathbf{P}_{12}$  and  $\mathbf{P}_{22}$  are non-zero.

(a) What constraints must be satisfied by  $\mathbf{P}$  for it to be a valid transition matrix for a finite state-space Markov chain? [10%]

(b) What equation must the *stationary distribution*,  $\pi$ , satisfy?  $\pi$  is a row vector where

$$\pi = \begin{bmatrix} \pi_1 & \pi_2 \end{bmatrix}$$

and  $\pi_1$  is an  $m$ -dimensional row vector. The simplest form of the expression should be given and clearly motivated. Does the stationary distribution depend on the initial state? [20%]

(c) If all elements of  $\mathbf{P}_{12}$  are zero, how does this change the answer to Part (b)? [10%]

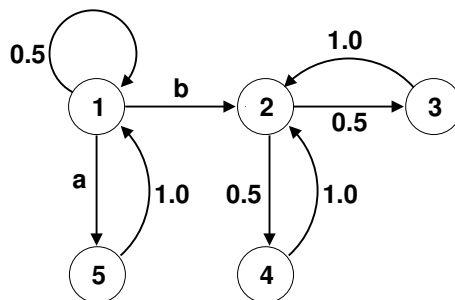


Fig. 1

(d) Figure 1 shows the state-diagram for a particular process.

(i) Write down the transition matrix for this process. [15%]

(ii) Find an expression for all stationary distributions for this process when  $a = 0.5$ . Does the stationary distribution depend on the initial state in the context of your answers to Parts (b) and (c)? [25%]

(iii) The network is now modified so that  $b = 0.1$ . Discuss the periodicity of this network. Give two eigenvalues of the transition matrix, justifying your answer. [20%]

**END OF PAPER**