

ENGINEERING TRIBOS PART II B,

ADVANCED MACHINE DESIGN, 4C16

CRIB 2013/14 (M SUTCLIFFE)

Q1 (a) 
$$W^* = \frac{Wc^2}{\eta \omega L R^3}$$

So as  $c$  is reduced the value of  $w^*$  falls. But from table, if  $w^*$  falls so does eccentricity ratio  $\epsilon$ , i.e. bearing runs more concentrically.

(b) Petrov's law assumes bearing runs concentrically and that the oil film is continuous

then  $\tau = \eta \frac{R\omega}{c}$ ,  $M = 2\pi R \eta \frac{R\omega}{c} \cdot L \cdot R = 2\pi \eta \omega L R^3 \frac{1}{c}$

i.e.  $m^* = 2\pi$

Changes associated with variation of clearance around bearing tend to cancel out.

(c) Heat flow through bearing =  $2\pi R L k (\theta_{oil} - \theta_a)$

All work done by  $M$  flows this way

$\Rightarrow M\omega = \frac{2\pi R L k}{d} \delta\theta$  where  $\delta\theta = \theta_{oil} - \theta_a$

i.e.  $\delta\theta = \frac{m^* \eta \omega L R^3}{c} \frac{d\omega}{2\pi R L k}$

$\delta\theta = \frac{m^* \eta (R\omega)^2 d}{2\pi k c} = \frac{m^* \eta \omega^2 d}{2\pi k c}$

(d) shaft will be at uniform temperature, equal to that of oil film:

$\theta_{oil} = \theta_a + \delta\theta$

Bearing thin so average temperature =  $\frac{1}{2} (\theta_a + \theta_{oil}) = \theta_a + \frac{\delta\theta}{2}$

So clearance will be reduced from initial value  $c_0$

$c = c_0 - \frac{1}{2} \beta \delta\theta R$

1 (d) (cont) or  $\frac{c}{R} = \frac{C_0}{R} - \frac{1}{2} \beta \Delta \theta$

where  $\Delta \theta = \frac{m^*}{2\pi} \frac{\eta u^2}{\kappa} \frac{d}{c} = \lambda \frac{R}{c}$  where  $\lambda = \frac{m^*}{2\pi} \frac{\eta u^2}{\kappa} \frac{d}{R}$

then  $\frac{c}{R} = \frac{C_0}{R} - \frac{1}{2} \beta \lambda \frac{R}{c}$

or  $\left(\frac{c}{R}\right)^2 - \left(\frac{c}{R}\right) \left(\frac{C_0}{R}\right) + \frac{1}{2} \beta \lambda = 0$

$\frac{c}{R} = \frac{C_0}{2R} \pm \sqrt{\left(\frac{C_0}{2R}\right)^2 - \frac{1}{2} \beta \lambda}$

This part not done effectively - marks given for sensible attempts.

No solution if  $\frac{C_0}{2R} < \sqrt{\frac{1}{2} \beta \lambda}$  or  $\frac{C_0}{R} < \sqrt{2 \beta \lambda}$

So critical case  $\frac{C_0}{R} = \left(2 \beta \frac{m^*}{2\pi} \frac{\eta u^2}{\kappa} \frac{d}{R}\right)^{\frac{1}{2}}$

But as c falls  $m^*$  approaches 5.1

$\frac{C_0}{R} \approx \sqrt{\frac{5.1}{\pi}} \left(\beta \frac{\eta u^2}{\kappa} \frac{d}{R}\right)^{\frac{1}{2}} = 1.27 \left(\beta \frac{\eta u^2}{\kappa} \frac{d}{R}\right)^{\frac{1}{2}}$

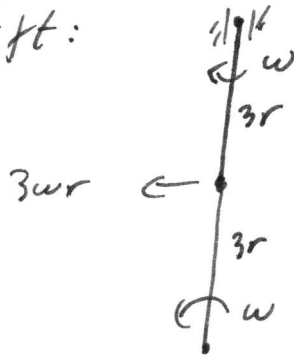
e)  $\frac{C_0}{R} = 1.27 \left(3 \times 10^{-5} \left(\frac{0.1 \times 25}{50}\right) \frac{0.02}{0.2}\right)^{\frac{1}{2}} = 4.9 \times 10^{-4}$

$\Delta \theta = \frac{m^*}{2\pi} \frac{\eta u^2}{\kappa} \frac{d}{c} = \frac{5.1}{2\pi} \cdot \frac{0.1 \times 25}{50} \cdot \frac{0.02}{4.9 \times 10^{-4} \times 0.2} = 8^\circ \text{C}$

As viscosity is rather sensitive to temperature this rise of  $8^\circ \text{C}$  may well be significant.

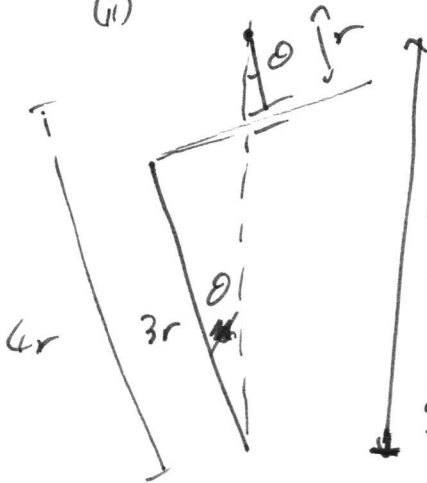
Q2 (i) Minimum lift: acceleration = zero (except as follower leaves base circle)

Maximum lift:



$$accn = 3rw^2 + 3rw^2 = 6rw^2 \downarrow$$

(ii)



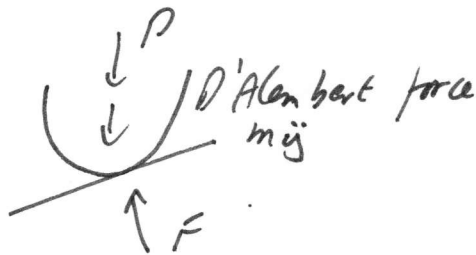
$$y = 4r / \cos \theta$$

$$\dot{y} = \frac{4r}{\cos^2 \theta} \sin \theta \dot{\theta}$$

$$\ddot{y} = 4r \dot{\theta}^2 \left( \frac{1}{\cos^3 \theta} + \frac{\sin^2 \theta}{\cos^3 \theta} \right) \quad [\ddot{\theta} = 0]$$

(iii)

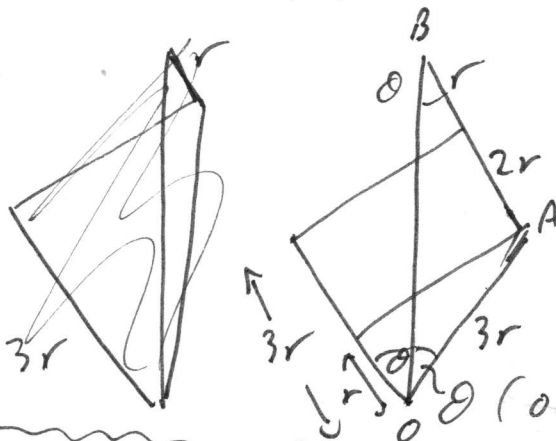
neglect gravity force



Minimum force corresponds to maximum negative (downward) acceleration.

For flank contact  $\ddot{y}$  is positive for small  $\pm \theta$

At limit of flank contact  $\cos 2\theta = \frac{1}{3} \Rightarrow \theta = 35.3^\circ$



$$\text{So } \frac{1}{\cos^3 \theta} + \frac{\sin^2 \theta}{\cos^3 \theta} > 0 \text{ on flanks}$$

So critical case is at maximum lift

$$P = 6mrw^2 = 6 \times 0.01 \times 200^2$$

$$P = 240 \text{ N}$$

Most candidates correctly assumed that the critical condition was at the tip.

2 (b)(i) To avoid significant metal-to-metal contact  
 choose  $h_{min} = 0$

On base circle  $\bar{u} = \omega \cdot \frac{3r}{2} = \frac{1}{2} \cdot 200 \cdot 0.3 = 3 \text{ m/s}$

$W = P = 240 \text{ N}$

$\frac{1}{R} = \frac{1}{r} + \frac{1}{3r} \Rightarrow R = 7.5 \times 10^{-3} \text{ m}$

$h_{min} = 10^{-6} = 2.65 \times 7.5 \times 10^{-3} \times (2 \times 2 \times 10^{-8} \times 115 \times 10^9)^{0.54} \times \left( \frac{3 \times 0.1}{2 \times 115 \times 10^9 \times 7.5 \times 10^{-3}} \right)^{0.7}$

[1.673 x 10<sup>-7</sup>]

$\times \left( \frac{240}{2 \times 115 \times 10^9 \times 7.5 \times 10^{-3} \times L} \right)^{-0.13}$

↑ 'x'

$10^{-6} = 2.78 \times 10^{-7} (x)^{-0.13}$

$x^{-0.13} = 3.59$

$\ln x = \ln(3.59) / 0.13$

$x = 5.26 \times 10^{-5}$

$L = \frac{240}{2 \times 115 \times 10^9 \times 7.5 \times 10^{-3} \times 5.26 \times 10^{-5}} = 2.65 \text{ mm}$

Method marks given  
 even without right  
 answer from a

(ii) Calculation not adequate. Need also to  
 consider much more <sup>extreme</sup> conditions (potentially) with  
 high accelerations in lift phase with smaller  
 tip radius.

$$3 \text{ (a)} \quad \omega_c r_c = \frac{1}{2}(\omega_A r_A + \omega_S r_S)$$

$$r_c = \frac{1}{2}(r_A + r_S)$$

$$\therefore \omega_c (r_A + r_S) = \omega_A r_A + \omega_S r_S$$

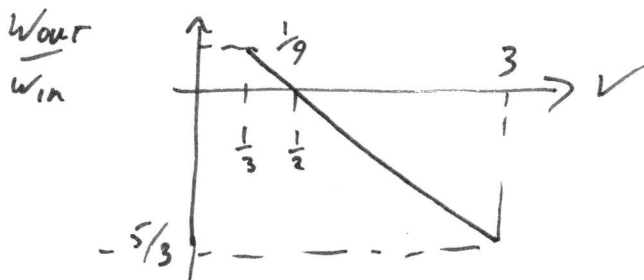
$$\omega_c (\beta + 1) = \omega_A \beta + \omega_S$$

$$\omega_S = \omega_{in}, \quad \omega_A = -V \omega_{in}, \quad \omega_c = \omega_{out}$$

$$\Rightarrow \omega_{out} (\beta + 1) = -\beta V \omega_{in} + \omega_{in} \Rightarrow \frac{\omega_{out}}{\omega_{in}} = \frac{1 - \beta V}{1 + \beta}$$

$$(b) \quad \beta = 2 \Rightarrow \frac{\omega_{out}}{\omega_{in}} = \frac{1 - 2V}{3} \quad \text{For } V = \frac{1}{3}, \frac{\omega_{out}}{\omega_{in}} = \frac{1}{9}$$

$$\text{For } V = 3, \frac{\omega_{out}}{\omega_{in}} = -\frac{5}{3}$$



$$(c) \text{ If } \beta V = 1, \text{ i.e. } V = \frac{1}{\beta} = \frac{1}{2} \text{ then } \frac{\omega_{out}}{\omega_{in}} = 0$$

So this is effectively an infinite gear ratio.

A vehicle with this transmission can pull away from stationary without the need for a slipping clutch.

$$(d) \text{ (i)} \quad T_{out} = -1 \text{ Nm}, \quad \omega_{in} = 1 \text{ rad/s}$$

$$P_{out} = T_{out} \omega_{out} = -1 \times \left( \frac{1 - 2V}{3} \right) = \frac{2}{3}V - 1 = -\frac{\omega_{out}}{\omega_{in}}$$

$$= -\omega_{out} \text{ Watts}$$

(ii) Virtual work ( $T_s, \omega_s$  all +ve)

$$T_A \omega_A' + T_c \omega_c' + T_s \omega_s' = 0$$

(for  $\omega_{out}$  in red/s)

Students tended to get bogged down in algebra in this question.

3 (d) (ii) (cont)

$$\text{Put } \omega_s' = 0 \Rightarrow \omega_A' = \omega_c' \frac{B+1}{B} = \frac{3}{2} \omega_c'$$

$$\therefore T_A \cdot \frac{3}{2} \omega_c' + T_c \omega_c' + 0 = 0$$

$$T_A = -\frac{2}{3} T_c \quad \text{but } T_c = -T_{out} = 1 \text{ Nm}$$

$$\therefore T_A = -\frac{2}{3} \text{ Nm}$$

$$\text{Power into annulus } P_A = T_A \omega_A = -\frac{2}{3} \times (-V \omega_{in}) = \frac{2}{3} V$$

$$\text{Hence power into CVT } P_{CVT} = \frac{P_A}{\eta} = \frac{2V}{3 \times 0.8}$$

$$\text{But } 2V = 1 - 3\omega_{out}$$

$$\Rightarrow P_{CVT} = \frac{1 - 3\omega_{out}}{2.4}$$

(iii) Power into sun  $P_s = T_s \omega_s$  ( $\omega_s = \omega_{in}$ )

$$\text{Let } \omega_A' = 0, \quad T_c \omega_c' + T_s \omega_s' (B+1) = 0$$

$$\Rightarrow T_s = -T_c/3 = -\frac{1}{3} \text{ Nm}$$

$$P_s = -\frac{1}{3} \omega_{in} = -\frac{1}{3} \text{ Watts} \quad (\text{Always -ve } P_{in} < P_{CVT})$$

$$P_{in} = P_{CVT} + P_s = \frac{1}{2.4} - \frac{\omega_{out}}{0.8} - \frac{1}{3} = \frac{1}{12} - 1.25 \omega_{out} \text{ Watts}$$

