

EGT3
ENGINEERING TRIPOS PART IIB

Tuesday 30 April 2024 2 to 3.40

Module 4F8

IMAGE PROCESSING AND IMAGE CODING

*Answer not more than **three** questions.*

All questions carry the same number of marks.

*The **approximate** percentage of marks allocated to each part of a question is indicated in the right margin.*

*Write your candidate number **not** your name on the cover sheet.*

STATIONERY REQUIREMENTS

Single-sided paper.

SPECIAL REQUIREMENTS TO BE SUPPLIED FOR THIS EXAM

CUED approved calculator allowed.

Engineering Data Book

10 minutes reading time is allowed for this paper at the start of the exam.

You may not start to read the questions printed on the subsequent pages of this question paper until instructed to do so.

You may not remove any stationery from the Examination Room.

1 (a) If the 2D Fourier transform of a function $f(u_1, u_2)$ is $F(\omega_1, \omega_2)$, find the Fourier transform of the translated function $f(u_1 - a, u_2 - b)$, where a and b are constants.

[15%]

(b) Similarly, if the (u_1, u_2) coordinate system is rotated by a constant angle ϕ to give new coordinates

$$u'_1 = u_1 \cos \phi + u_2 \sin \phi, \quad u'_2 = -u_1 \sin \phi + u_2 \cos \phi$$

find the Fourier transform of the rotated function $f(u'_1, u'_2)$. In particular show that this new transform corresponds to a rotated version of the original transform in the (ω_1, ω_2) plane. Is the sense of rotation of the transform in the (ω_1, ω_2) plane the same as, or the negative of, the sense of rotation of the image in the (u_1, u_2) plane?

[20%]

(c) Now consider an image consisting of a thin line along the u_1 -axis in the (u_1, u_2) plane, which we can approximate as being the delta function $f(u_1, u_2) = \delta(u_2)$. Note we are taking the image plane to be infinite, and we are assuming the line is infinitely long.

Find the Fourier transform of this line in the (ω_1, ω_2) plane, and show that it is itself another 'line' in the delta function approximation. What is the angle between this line in the (ω_1, ω_2) plane and the original line in the (u_1, u_2) plane?

[20%]

(d) Take the general line $u_2 = mu_1 + c$ in the (u_1, u_2) plane. Note that we can represent this by the function

$$f(u_1, u_2) = \delta(u_2 - (mu_1 + c))$$

(i) By carrying out a direct Fourier transform, show that this transforms to a function with values confined to another line in the (ω_1, ω_2) plane. Find the explicit equation for the location of this new line and an expression for how the phase varies along the line. Both answers should be given in terms of ω_1, ω_2, m and c .

[10%]

(ii) Show that the answers to Part (d)(i) can also be derived by rotating and translating the result for the transform of a line along the u_1 -axis that you found in Part (c).

[10%]

(e) Explain, qualitatively, the effects on the transform if the line being transformed has only a finite, rather than infinite length. You may still assume the image plane itself is infinite.

[5%]

- (f) Consider the image in Fig. 1, in which the background (white) has image values of 0, and the lines themselves (black) have image values of 1.

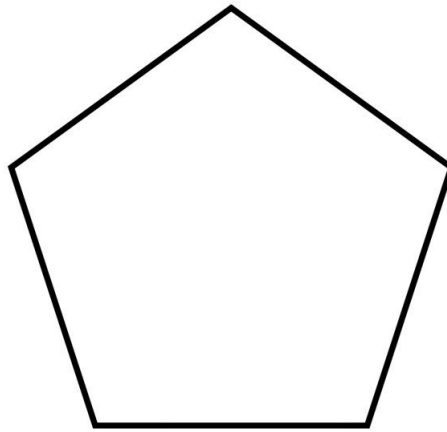


Fig. 1

Draw a sketch of what you think the amplitude of the Fourier transform of this image would look like, giving written justifications for the main features. [20%]

2 (a) Consider the ideal bandpass filter shown in Fig. 2, with $H = 1$ in the shaded regions and $H = 0$ otherwise. Sampling is carried out on a rectangular grid with spacings of Δ_1 and Δ_2 in the u_1 and u_2 directions respectively.

Using standard results or otherwise, form the ideal impulse response, $h(n_1\Delta_1, n_2\Delta_2)$, of this filter by taking an *alternative ideal bandpass filter* and letting Ω_{L1} be zero (where Ω_{L1} is the lower limit in the ω_1 direction).

Check that this gives the same result as forming the filter by subtracting two lowpass filters and describe these lowpass filters. [25%]

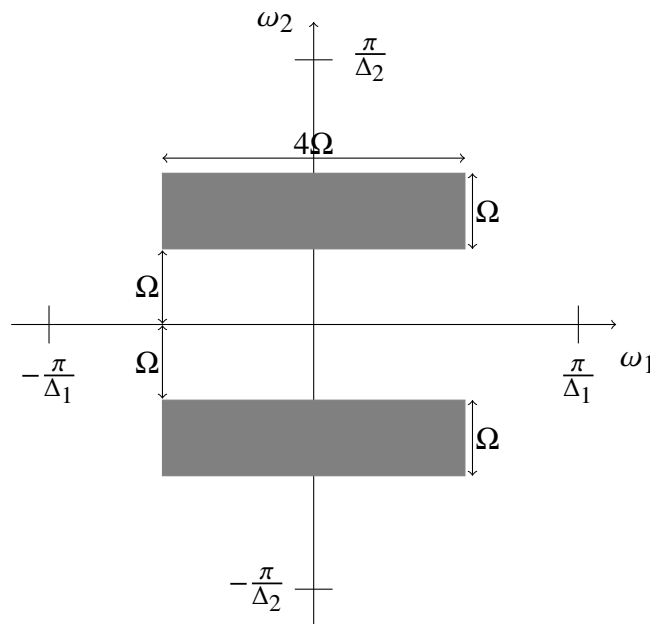


Fig. 2

(b) Assume that an observed image \mathbf{y} can be modelled as a linear distortion, \mathbf{L} , of the true image \mathbf{x} plus additive noise \mathbf{d} .

(i) If \mathbf{L} is known and we neglect noise, explain how the *inverse filter* can be used to estimate the true image. [15%]

(ii) More sophisticated deconvolution techniques will attempt to estimate the *posterior*, $P(\mathbf{x}|\mathbf{y})$, via Bayes theorem, $P(\mathbf{x}|\mathbf{y}) \propto P(\mathbf{y}|\mathbf{x})P(\mathbf{x})$.

Give the form of the S in the *prior*, $P(\mathbf{x}) = e^{\alpha S}$, for the *Maximum Entropy* deconvolution method and derive, by differentiation, the global maximum of S . Explain why this is useful. Describe all terms you use in your expressions and any assumptions made. [20%]

(c) (i) $G(\omega_1, \omega_2)$ is the Fourier transform of an image g , and $G_s(\omega_1, \omega_2)$, is the Fourier transform of the corresponding *sampled* image g_s . Using the form of G_s in terms of G , explain the phenomenon of *aliasing*. [15%]

(ii) A 512×256 unaliased image $x(u_1, u_2)$ has a Discrete Fourier Transform $X(\omega_1, \omega_2)$ which is a 512×256 array of complex numbers. We find that the highest frequencies of X occur at the points $\pm(10, 120)$ and $\pm(200, 20)$, where we are taking $(0, 0)$ to be in the centre of the 512×256 array.

Sketch these frequencies in the (ω_1, ω_2) plane. If we now wish to downsample our image to an $n_1 \times n_2$ image, find the minimum values of n_1 and n_2 that will still produce an *unaliased* image. [25%]

3 (a) Sketch the main blocks of an image coding/decoding system. [5%

(b) The Haar matrix T , given below, is applied (by acting on 2×2 blocks) to a 4×4 image X to give a resulting image Y :

$$T = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \quad X = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 2 & 2 & 2 & 2 \\ 3 & 3 & 3 & 3 \end{bmatrix}$$

Evaluate Y and then regroup components to form an image Y' , where blocks in Y' consist of corresponding elements from the blocks in Y . Comment on the form of Y' . Is this what you would expect from looking at the original image X . [35%

(c) Comment on the energy content of each 2×2 sub-block of Y' found in Part (b). Explain, qualitatively, how the nature of the sub-blocks (or sub-bands) allow us to compress the image. [15%

(d) If the 2×2 Haar transform is applied to a typical natural image, sketch the energies and entropies of each of the 4 sub-bands (Lo-Lo, Hi-Lo, Lo-Hi, Hi-Hi), assuming some fixed quantisation step. [15%

(e) The *Approximate Entropy* H_a of a sub-band (other than Lo-Lo) in Part (d), which has been uniformly quantised, is given by

$$H_a = \log_2 \left(\frac{2ex_0}{Q} \right)$$

Explain what the quantities x_0 and Q are by reference to the probability density function used to approximate the entropy of the quantised samples. [15%

(f) The $n \times n$ *Discrete Cosine Transform* (DCT) has better image compression properties than the Haar transform (for $n > 2$). Explain why this is and give a brief overview of how the properties of the DCT enable efficient computation. [15%

4 (a) For a lowpass filter $H_0(z)$ and a highpass filter $H_1(z)$, sketch a 1D 4-level binary filter tree. If our input vector has N samples, and f_s is the sampling frequency, indicate the sizes and bandwidths of each of the highpass outputs at each level. [20%]

(b) Sketch the *inverse tree* which takes the output of the binary tree in Part (a) and reconstructs the input signal using another pair of lowpass, $G_0(z)$, and highpass, $G_1(z)$, filters. For *perfect reconstruction* (PR) give the two conditions that must be satisfied by H_0, H_1, G_0, G_1 . [15%]

(c) A lowpass product filter $P_0(z)$ is defined by:

$$P_0(z) = H_0(z)G_0(z)$$

Consider the following expressions for forming highpass filters:

$$H_1(z) = z^{-k}G_0(-z) \quad \text{and} \quad G_1(z) = z^kH_0(-z)$$

If the PR conditions in Part (b) are to be satisfied, derive the condition, $P_0(z) + P_0(-z) = 2$, that $P_0(z)$ must satisfy. What restrictions does this put on the powers of z in $P_0(z)$? [15%]

(d) Define $Z = \frac{1}{2}(z + z^{-1})$. It can be shown that smoother wavelet filters require multiple factors of $(1 + Z)$. If $P_0(z)$ is given by:

$$P_0(z) = (1 + Z)^2(1 + aZ)$$

find the value of a if the conditions in Part (c) are to be satisfied. Suggest a possible split of this P_0 to give H_0 and G_0 . [20%]

(e) For the LeGall(3,5) filters given below:

$$H_0(z) = \frac{1}{2}(z + 2 + z^{-1}), \quad H_1(z) = \frac{1}{8}z^{-1}(-z^2 - 2z + 6 - 2z^{-1} - z^{-2})$$

sketch the impulse and frequency responses for the first three levels of the filter tree. [20%]

(f) To apply the techniques described in previous parts of this question to images, we first apply the 1D filter to rows and then to columns. Sketch 2 levels of a 2D filter tree with (H_0, H_1) as lowpass and highpass filters. [10%]

END OF PAPER

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