

**Engineering Tripos, Part IA, 2015**

**Paper 3 Electrical and Information Engineering**

**Solutions**

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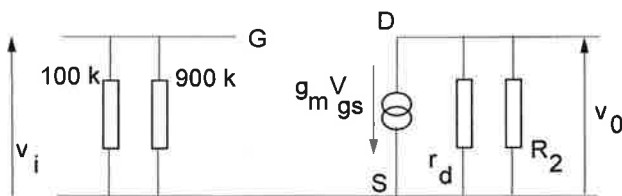
## SECTION A

### 1 (long)

(a) The 900k and 100k act as voltage divider to set the gate voltage. Source-drain current through R1 sets the source voltage, and thus  $V_{gs} = V_g - V_s$ .

(b)  $V_g = 0.1 * 20 = 2V$ . For operating point of  $V_{gs} = -2V$ , need  $V_s = 4V$ . Also,  $V_{ds} = 8V$  means  $20 - 8 - 4 = 8V$  across R2. If  $I_d = 4mA$ ,  $R_1 = 1k\Omega$ ,  $R_2 = 2k\Omega$ .

(c)



At mid-band capacitors are short circuits.

$$v_o = -g_m v_{gs} \frac{r_d R_2}{r_d + R_2}, \quad v_i = v_{gs}$$

Hence, gain 
$$\frac{v_o}{v_i} = -g_m \frac{r_d R_2}{r_d + R_2}$$

Or gain =  $-5 \times 10 \times 2 / (10 + 2) = -8.33$

Output impedance =  $R_2 // r_d = 1.67 k\Omega$ .

(d)  $R' = 1.67 + 5 = 6.67$

$f = 1/2\pi CR'$ ,  $C = 1/(2 \times 3.14 \times 6.67 \cdot 10^3 \times 10) = 2.39 \times 10^{-6} F$

(e)  $V_{ds} = 12V$  allows +ve swing of  $12 - 20V = 8$ , and -ve swing of  $12 - 4 = 8V$ , symmetric.

## 2 (long)

- (a) gain =  $R_2/R_1 = 300$ . So  $R_2 = 3 \text{ M}\Omega$  .
- (b) point v. is virtual earth, so  $R_{in} = 10 \text{ k}\Omega$ .
- (c)  $f = 1/(2\pi R_2 \times C_1)$ , so  $C_1 = 1/(2\pi \times 3 \times 10^6 \times 10^4) = 5.3 \text{ pF}$ .
- (d)  $G = A/(1 + A \times b)$ , where  $b = R_1/(R_1 + R_2)$   
So  $G = 2 \times 10^4 / (1 + 2 \times 10^4 / 300) = 296$  .

## 3 (short)

Lump the 6.37 mH inductor and the 2  $\Omega$  resistor into a single impedance,  $Z_1$ .

$$Z_1 = (2 + j\omega L) \Omega = 2 + j \times 2\pi \times 50 \times 6.37 \times 10^{-3} \Omega = 2 + 2j \Omega$$

The second set of impedances, the 4  $\Omega$  resistor and the 796  $\mu\text{F}$  capacitor are in parallel, and can be combined into a single impedance,  $Z_2$ .

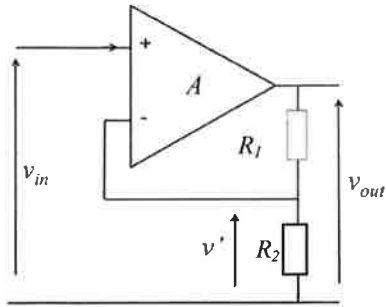
$$1/Z_2 = (1/4 + j\omega C) \Omega \Rightarrow Z_2 = 2 - 2j \Omega$$

Therefore, the total impedance,  $Z_{tot} = Z_1 + Z_2 = 4 \Omega$

The Input current is the input voltage divided by the circuit impedance,  
i.e.  $I = V / Z_{tot} = 60 \text{ A}$  .

#### 4 (short)

The circuit we are dealing with is as follows:



Now,  $v_{out} = A(v_{in} - v')$ .

We can treat the resistors  $R_1$  &  $R_2$  as a potential divider, as no current flows through the op-amp input (it is ideal with an infinite input resistance).

$$\Rightarrow v' = \frac{R_2}{R_1 + R_2} \times v_{out}$$

Using the expression for  $v_{out}$  from above, we find that:

$$\begin{aligned} v_{out} &= A\left(v_{in} - \frac{R_2}{R_1 + R_2} \times v_{out}\right) \\ &= \frac{A((R_1 + R_2) \times v_{in} - R_2 \times v_{out})}{R_1 + R_2} \end{aligned}$$

$$\Rightarrow v_{out} \times (R_1 + R_2) = Av_{in} \times (R_1 + R_2) - Av_{out}R_2$$

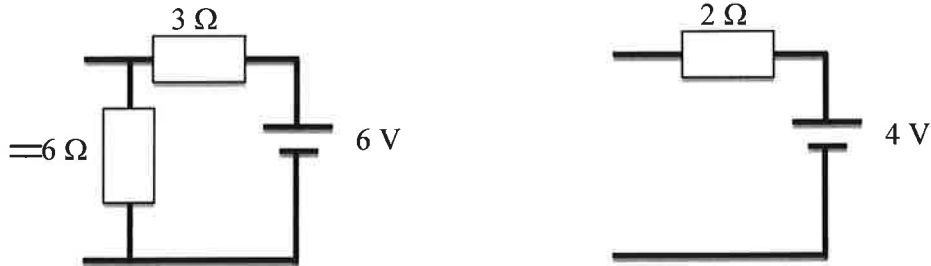
$$v_{out} \times (AR_2 + R_1 + R_2) = Av_{in} \times (R_1 + R_2)$$

$$\Rightarrow \text{the voltage gain, } \frac{v_{out}}{v_{in}} = \frac{A(R_1 + R_2)}{AR_2 + R_1 + R_2}$$

As  $A \rightarrow \infty$ , then the gain tends towards  $\frac{A(R_1 + R_2)}{AR_2} = 1 + \frac{R_1}{R_2}$

**5 (short)**

Starting at the right hand side, convert the first loop into its Thévenin equivalent:

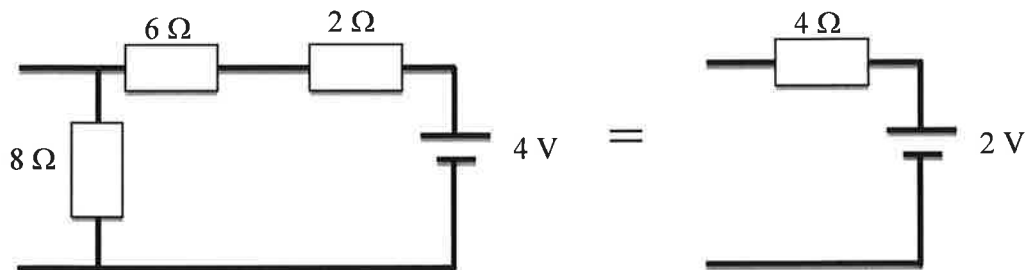


(The open circuit voltage from the circuit on the left  $= 6 \times \frac{6}{6+3} = 4 \text{ V}$

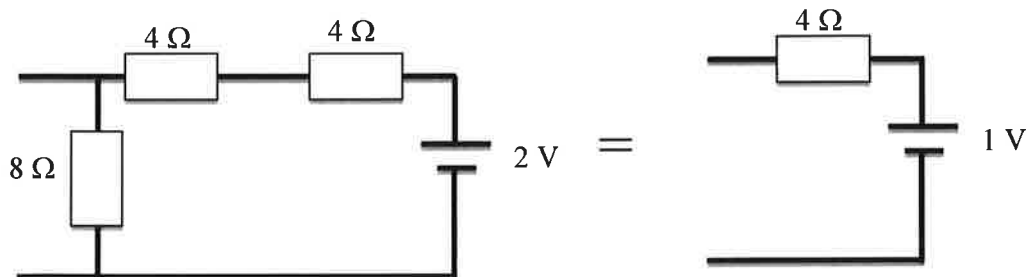
The equivalent resistance is the open circuit voltage divided by the short-circuit current.

The short-circuit current  $= 6\text{V}/3\Omega = 2 \text{ A} \Rightarrow \text{resistance} = 4\text{V}/2\text{A} = 2 \Omega$ .

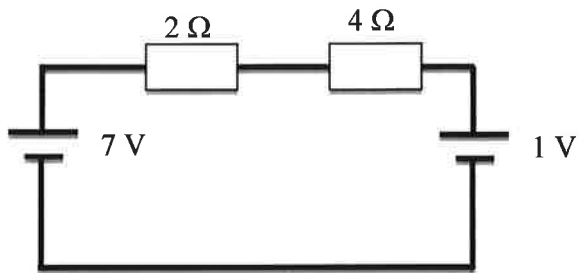
The next part of the circuit then becomes:



The next part of the circuit then becomes:



Finally, adding in the last bit:



The current flowing in the circuit is the total potential difference divided by the total resistance around the circuit

$$= \frac{7\text{ V} - 1\text{ V}}{2\Omega + 4\Omega} = 1\text{ A.}$$

# Section B

6 (short)

(a) 2's complement is a coding of a binary number that allows the representation of negative numbers for an 8 bit word

0<sub>H</sub> → 7FH represent 0 → 127 (stay the same in 2's complement form)

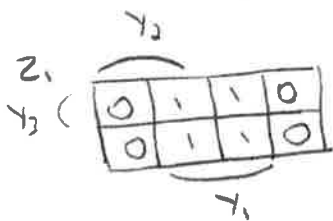
80<sub>H</sub> → FFH represent -128 → -1 (are converted to 2's complement form by inverting the number and adding 1)

Significance: normal binary arithmetic can be used (no need for separate circuits to add negative numbers)

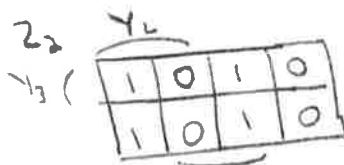
(b)

| X(decimal) | X              |                |                | -X             |                |                |                |
|------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|
|            | Y <sub>3</sub> | Y <sub>2</sub> | Y <sub>1</sub> | Z <sub>4</sub> | Z <sub>3</sub> | Z <sub>2</sub> | Z <sub>1</sub> |
| 0          | 0              | 0              | 0              | 0              | 0              | 0              | 0              |
| 1          | 0              | 0              | 1              | 1              | 1              | 1              | 1              |
| 2          | 0              | 1              | 0              | 1              | 1              | 1              | 0              |
| 3          | 0              | 1              | 1              | 1              | 1              | 0              | 1              |
| -4         | 1              | 0              | 0              | 0              | 1              | 0              | 0              |
| -3         | 1              | 0              | 1              | 0              | 0              | 1              | 1              |
| -2         | 1              | 1              | 0              | 0              | 0              | 1              | 0              |
| -1         | 1              | 1              | 1              | 0              | 0              | 0              | 1              |

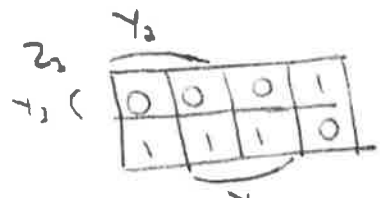
Answers that perceived the negation of -4 as an invalid operation, and thus used only three bits, were also marked as correct



$Z_1 = Y_1$

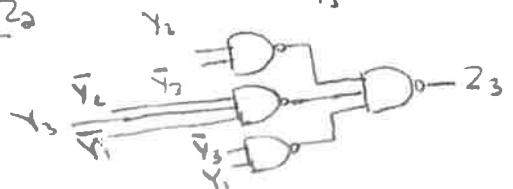
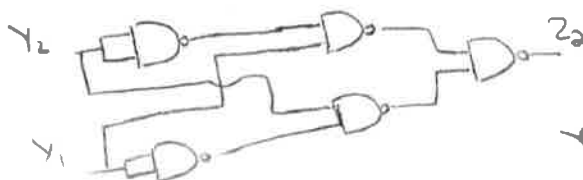


$Z_2 = Y_2 \bar{Y}_1 + \bar{Y}_2 Y_1$

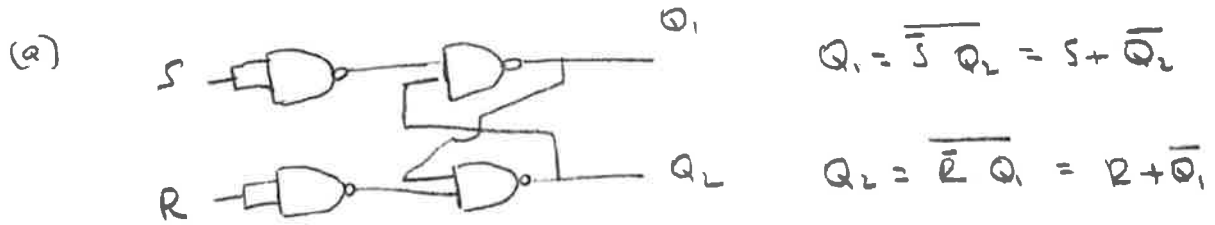


$Z_3 = Y_2 \bar{Y}_3 + Y_1 \bar{Y}_3 + Y_3 \bar{Y}_2 \bar{Y}_1$

$Z_4 = Y_2 \bar{Y}_3 + Y_1 \bar{Y}_3$



7 (short)



(b) - master-slave configuration with clock  
 (clock must switch from low to high for input to affect output)  
 This avoids propagation of hazards

- $S = R = 1$  forbidden state in SR bistable
- $J = K = 1$  toggles the output in JK bistable (additional functionality)
- presence of  $\overline{\text{preset}}$  and  $\overline{\text{clear}}$ :  
 output can be changed irrespective of inputs

(c)  $S = R = 1 \Rightarrow Q_1 = Q_2 = 1$  (irrespective of the initial values of  $Q_1, Q_2$ )

$$S = R = 0, Q_1 = Q_2 = 1 \Rightarrow Q_1 = Q_2 = 0$$

$$S = R = 0, Q_1 = Q_2 = 0 \Rightarrow Q_1 = Q_2 = 1$$

Hence when  $S = R = 0$  and  $Q_1 = Q_2$  the  $Q_1, Q_2$  oscillate between 1 and 0

In practice one of  $Q_1, Q_2$  will switch first

$$S = R = 0, Q_1 = 1, Q_2 = 0 \Rightarrow Q_1 = 1, Q_2 = 0$$

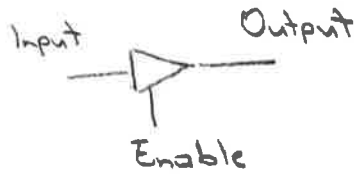
$$S = R = 0, Q_1 = 0, Q_2 = 1 \Rightarrow Q_2 = 1, Q_1 = 0$$

and the bistable stays in either of the two states without changing.



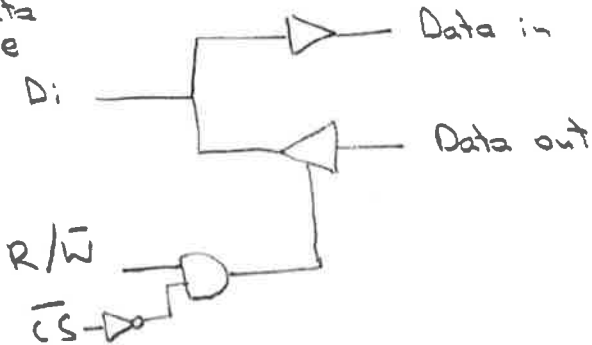
8 (short)

(a) Tri-state buffer



| E | I | Output   |
|---|---|----------|
| 1 | 0 | 0        |
| 1 | 1 | 1        |
| 0 | 0 | floating |
| 0 | 1 | floating |

One data bus wire



When  $\overline{CS}$  is low and  $R/\overline{W}$  is low the memory writes the data on the data bus

|       |         |       |           |      |       |      |   |
|-------|---------|-------|-----------|------|-------|------|---|
| (b)   | movlw   | 0x AA | load      | 170  | into  | W    | (1 cycle)   |
|       | movwf   | 0x35  | load      | W    | into  | 0x35 | (1 <sup>-</sup> )   |
|       | decf    | 0x35  | decrement | 0x35 |       |      | (1 <sup>-</sup> )   |
| label | dec fsz | 0x35  | decrement | 0x35 |       |      | (1 <sup>-</sup> for first 168,<br>2 <sup>-</sup> for final) |
|       | goto    | label | jump      | to   | label |      | (2 <sup>-</sup> )   |

$$\text{Run time : } 1 + 1 + 1 + 168(1+2) + 2 = 509$$

Second case

$$\text{Run time : } 1 + 1 + (170/2 - 1)(1+1+2) + (1+2) = 341$$

9 (long)

(a)

| X     |       | Y     |       | P     |       |       |       |
|-------|-------|-------|-------|-------|-------|-------|-------|
| $x_2$ | $x_1$ | $y_2$ | $y_1$ | $P_4$ | $P_3$ | $P_2$ | $P_1$ |
| 0     | 0     | 1     | 0     | 0     | 0     | 1     | 0     |
|       |       | 1     | 1     | 0     | 0     | 1     | 1     |
| 0     | 1     | 1     | 0     | 0     | 0     | 1     | 1     |
|       |       | 1     | 1     | 0     | 1     | 0     | 0     |
| 1     | 0     | 1     | 0     | 0     | 1     | 1     | 0     |
|       |       | 1     | 1     | 0     | 1     | 1     | 1     |
| 1     | 1     | 1     | 0     | 1     | 0     | 1     | 1     |
|       |       | 1     | 1     | 1     | 1     | 0     | 0     |

$P_4$

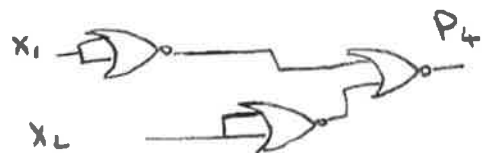
| $x_2$ | $x_1$ |   |
|-------|-------|---|
| 0     | 1     | 0 |
| 0     | 1     | 0 |

$Y_1$

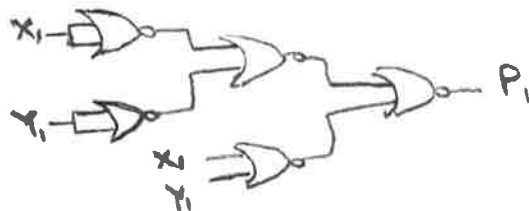
$P_1$

|   |   |   |   |
|---|---|---|---|
| 0 | 0 | 1 | 1 |
| 1 | 1 | 0 | 0 |

$$\bar{P}_4 = \bar{x}_1 + \bar{x}_2$$

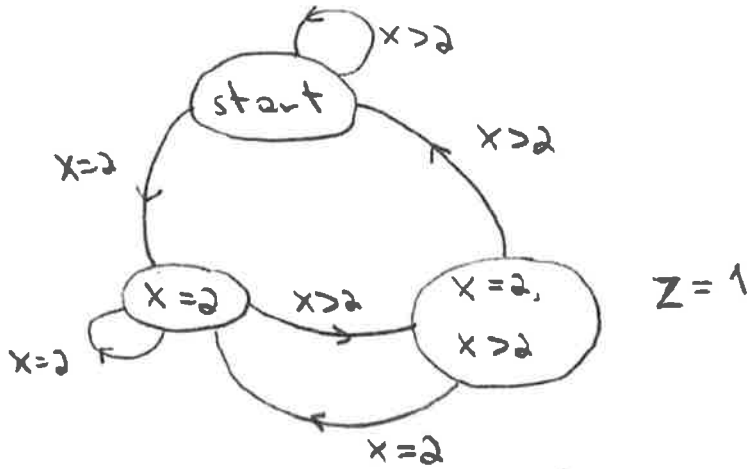


$$\bar{P}_1 = x_1 y_1 + \bar{y}_1 \bar{x}_1 = \overline{\bar{x}_1 + y_1} + \overline{x_1 + \bar{y}_1}$$



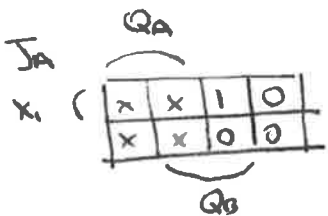
(b)

| states     | bistable allocation |       |
|------------|---------------------|-------|
|            | $Q_A$               | $Q_B$ |
| start      | 0                   | 0     |
| $x=2$      | 0                   | 1     |
| $x=2, x>2$ | 1                   | 0     |

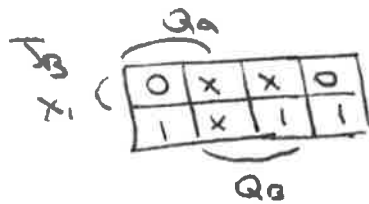


$x>2$  ( $x_1 = 1$ )  
 $x=2$  ( $x_1 = 0$ )

| Current state | Input | Next State  | $J_A$ | $K_A$ | $J_B$ | $K_B$ |
|---------------|-------|-------------|-------|-------|-------|-------|
| $Q_A$ $Q_B$   | $x_1$ | $Q_A$ $Q_B$ |       |       |       |       |
| 0 0           | 0     | 0 1         | 0     | x     | 1     | x     |
| 0 0           | 1     | 0 0         | 0     | x     | 0     | x     |
| 0 1           | 0     | 0 1         | 0     | x     | x     | 0     |
| 0 1           | 1     | 1 0         | 1     | x     | x     | 1     |
| 1 0           | 0     | 0 1         | x     | 1     | 1     | x     |
| 1 0           | 1     | 0 0         | x     | 1     | 0     | x     |



$$J_A = x_1 Q_B$$



$$J_B = \bar{x}_1$$

## SECTION C

### 10 (short)

(a)  $C = \epsilon_r \epsilon_0 A/d$  is book-work, and straight out of the lecture notes.

(b) If the electric field is  $E$  in the dielectric, then the force on the charge  $Q$  is the lower electrode when attached to the dielectric is  $F = (1/2)V^2 dC/dx|_{x=d} = dC/Dx = eA/d^2$   
Weight of plate  $= \rho g A < (1/2) V^2 \epsilon_r \epsilon_0 A/d^2$  So  $V^2 > 2\rho g d^2 / \epsilon_r \epsilon_0$   
*i.e.*  $V > d [2\rho g / \epsilon_0]^{1/2}$

### 11 (long)

(a) The only thing that matters is the number of ampere turns, by Ampere's law, as the field lines are strongly confined inside the material, which has a very high permeability.

(b) From  $NI = HL$  we have  $H = 1000 \text{ A m}^{-1}$  at  $B = 1 \text{ T}$ , and so [Note: some used

$$NI = 1000 \times 0.6 = 600 \text{ A turns.}$$

Note this could be 100 turns with 6A or 1000 turns at 0.6A.

[Note: some used  $H = 1100 \text{ A m}^{-1}$  or  $1200 \text{ A m}^{-1}$ , within accuracy of drawing: no marks deducted for this, and the other numbers changed appropriately.]

(c) With the gap, we now have  $NI = H_i L + H_g g$

$$\text{or } NI = H_i L + Bg/\mu_0 = 1000 \times 0.598 + 1 \times 0.002 / 4\pi \times 10^{-7} = 2188 \text{ A turns.}$$

The very high permeability of the steel means a small  $H$  in the steel, but a very large  $H$  in the air-gap.

(d) In opening up the gap an extra energy is required being the volume of the gap times the change in energy density in the iron and in the gap.

$$\Delta E = A g [B^2/2\mu_0 - B^2/2\mu_0\mu_r] = Fg \text{ the work force by the force at the pole pieces.}$$

$$F = 10^{-3} (0.5) (1 - 1/795) / [4\pi \times 10^{-7}] = 398 \text{ N.}$$

Note one can do this because the B-H curve is still essentially linear in the regimes we are working in.

(e) One uses a strengthened steel rather than soft cast steel to support the gap, or a frame to support the magnet of the material is too soft.

### 12 (short)

(a)  $B = \mu_0 I / 2\pi a$  by bookwork

(b) The magnitude of the magnetic field a distance  $d$  from one wire is  $B_d = \mu_0 I / 2\pi d$ , and the direction of the field is given by the right hand rule with respect to the direction of the current and the shortest distance to the wire.

This for the four points asked for the magnetic field is:

|            |   |                           |
|------------|---|---------------------------|
| (d,d,d)    | $\mathbf{B} = B_d (0, 0, 0)$                    | Magnitude: 0              |
| (-d,-d,-d) | $\mathbf{B} = B_d (0, 0, 0)$                    | Magnitude: 0              |
| (d,d,0)    | $\mathbf{B} = B_d (-1/\sqrt{2}, 1/\sqrt{2}, 0)$ | Magnitude: $B_d/\sqrt{2}$ |
| (-d,-d,0)  | $\mathbf{B} = B_d (1/\sqrt{2}, -1/\sqrt{2}, 0)$ | Magnitude: $B_d/\sqrt{2}$ |