# IA Tripos Paper 4 – Mathematical Methods 2016 – CRIBS

Section A:

(1) (a) Use l'Hopital's rule: twice on  $f(x) = (x\cos x - \sin x)/x^3$ First =  $(\cos x - \sin x)/3x^2 = -\sin x/3x^2$ Second =  $[-\cos x/3 = -1/3]$ 

(b) Use l'Hopital's rule once on  $g(x) = \sin(\pi x)/(x^2-16)$ 

 $=\pi \cos(\pi x) / 2x = \pi \cos(-4\pi) / -8 = -\pi/8$ 



(3) (a) In any pairs, the vectors **a**, **b**, **c**, satisfy  $\mathbf{u}.\mathbf{v} = 0$  so they are orthogonal. Their magnitudes are  $3\sqrt{2}$ , 3,  $3\sqrt{2}$  respectively so the volume is 56. (b) by inspection the order they are in forms a right handed set as does any cyclic permutation.

(4) (a) By inspection **U** is a rotation of  $\theta$  about the origin. For  $\theta = \pi/4$  we get a 45° rotation.

 $[1,1] \rightarrow [\sqrt{2}, 0], \ [1,2] \rightarrow [3/\sqrt{2}, \ 1/\sqrt{2}], \ [2,2] \rightarrow [2\sqrt{2}, 0], \ [2,1] \rightarrow [3/\sqrt{2}, -1/\sqrt{2}]$ 

Plot points and observe they form a square of unit side.

(b)  $\mathbf{U}^4 = 4$  rotations of  $-45^\circ$  =one rotation of -1, so  $\mathbf{U}^4 = -\mathbf{I}$ , can do it by numbers and multiply out the matrices. By inspection, rotation of  $-\theta$  gives a transpose of  $\mathbf{U}$  so  $\mathbf{U}^{-1} = \mathbf{U}^T$ 

(c)  $||\mathbf{A}-\lambda\mathbf{I}||=0$  implies  $\lambda^3 - 3\lambda a^2 - 2a^3=0$  or  $\lambda = -a$ , -a, 2a.

largest eigenvalue:  $\lambda$  = 2a Eigenvector: (1/ $\sqrt{3}$ , 1/ $\sqrt{3}$ , 1/ $\sqrt{3}$ )

Other two eigenvectors in the plane perpendicular to {1,1,1}.

(5) (a)  $dN/dt = -\lambda N$  integrates up to  $N(t)=N_0exp(-\lambda t)$ 

After time  $T_{1/2}$  we have half the number of atoms left so  $N(T_{1/2})/N_0 = \exp(-\lambda T_{1/2}) = 0.5$  and

So :  $T_{1/2} = \ln(2)/\lambda$ .

(b) If the N<sub>1</sub> species is stable, i.e. has a very long lifetime, then the N<sub>1</sub>'s being produced are all those that decayed, N<sub>1</sub>(t) + N(t) = N<sub>0</sub>, so N<sub>1</sub>(t) = N<sub>0</sub> (1 - exp(- $\lambda$ t)). This satisfies the boundary conditions that there are no N<sub>1</sub> species at t=0 and they are all N<sub>1</sub> species at very large time.

(c) If the  $N_1$  species are unstable, then the rate of growth of  $N_1$  is determined by the rate of formation of  $N_1$  from  $N_0$  minus the loss of  $N_1$  to the daughter product  $N_2$ 

So:  $dN_1(t)/dt = \lambda N_0 exp(-\lambda t) - \lambda^* N_1(t) =$ 

Integrate  $dN_1(t)/dt + \lambda^* N_1(t) = \lambda N_0 exp(-\lambda t)$ 

Particular integral:  $N_1(t) = A \exp(-\lambda t)$ :  $-\lambda A + \lambda^* A = \lambda N_0$ , and so  $A = -\lambda N_0/(\lambda - \lambda^*)$ 

No: N1(t) = Aexp( $-\lambda t$ ) + B exp( $-\lambda^* t$ ), and given that N1(t=0) = 0, B=-A

 $N_1(t) = [N_0/(\lambda^* - \lambda)][\exp(-\lambda t) - \exp(-\lambda^* t)].$ 

(d)  $dN_1(t)/dt = 0$  when  $\lambda \exp(-\lambda t) = \lambda^* \exp(-\lambda * t)$  or  $t^* = \ln (\lambda/\lambda^*)/(\lambda - \lambda^*)$ 

Note that both numerator and denominator are positive if  $\lambda > \lambda^*$ , and both are negative if  $\lambda < \lambda^*$ , so t\* is always positive.



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(4)

Impulse response is the derivative of the 3 Step response.

$$g(t) = \dot{g}(t) = \frac{\sin 2t}{2} e^{-t}$$

(b) Now for  $f(t) = \begin{cases} 0 & t < 0 \\ e^{-\alpha t} & t > 0 \end{cases}$ 

$$y(t) = \int_{0}^{t} g(t-\tau) f(\tau) d\tau$$

$$=\frac{1}{2}\int_{0}^{t} e^{-(t-\tau)} \sin 2(t-\tau) e^{\alpha \tau} d\tau$$
$$=\frac{e^{-t}}{2}\int_{0}^{t} e^{(1-\alpha)\tau} \sin 2(t-\tau) d\tau$$

integrate by parts:

$$=\frac{e^{t}}{2}\int \frac{\sin 2(t-\tau)}{(1-\alpha)}d\left[\frac{e^{(1-\alpha)}\tau}{(1-\alpha)}\right]$$
  
$$=\frac{e^{t}}{2}\left\{\frac{e^{(1-\alpha)}\tau}{(1-\alpha)}\sin 2(t-\tau)\right]^{t}+\frac{2}{(1-\alpha)}\int e^{(1-\alpha)}\tau \cos 2(t-\tau)d\tau$$

$$=\frac{e^{-t}}{2}\left\{\frac{-\sin 2t}{(1-\alpha)}+\frac{2}{(1-\alpha)}\int_{0}^{t}\cos 2(t-\tau)e^{-\alpha}d\tau\right\}$$

$$= \frac{e^{-t}}{2} \left\{ \frac{-\sin 2t}{(1-\alpha)} + \frac{2}{(1-\alpha)} \int_{0}^{t} \cos 2(t-\tau) d\left[\frac{e^{(1-\alpha)}\tau}{(1-\alpha)}\right] \right\}$$

$$= \frac{-\frac{e^{t} \sin 2t}{2(1-\alpha)}}{2(1-\alpha)} + \frac{e^{t}}{2} \left\{ \frac{2}{(1-\alpha)^{2}} \left[ \frac{(1-\alpha)\tau}{e} \cos 2(t-\tau) \right] \right\}$$
$$- 2 \int \frac{t}{e} \sin 2(t-\tau) d\tau \right\}$$

$$= -\frac{\overline{e}^{t} \operatorname{Sin2t}}{2(1-\alpha)} + \frac{\overline{e}^{t}}{(1-\alpha)^{2}} \begin{bmatrix} (1-\alpha)t \\ e & - \cos 2t \end{bmatrix}$$
$$-\frac{4}{(1-\alpha)^{2}} = \frac{e^{t}}{2} \int e^{t} \operatorname{Sin2(t-t)} dt$$
$$\operatorname{Sin2(t-t)} dt$$
$$\operatorname{Y(t)}$$

$$= \left(1 + \frac{4}{(1-\alpha)^{2}}\right) y(t) = \frac{-e^{-t} \sin 2t}{2(1-\alpha)} + \frac{e^{-\alpha t} e^{t} \cos 2t}{(1-\alpha)^{2}}$$
  
$$: y(t) = \left[1 + \frac{4}{(1-\alpha)^{2}}\right] \left[\frac{e^{-\alpha t} e^{-t} \cos 2t}{(1-\alpha)^{2}} - \frac{e^{-t} \sin 2t}{2(1-\alpha)}\right]$$

or

$$Y(t) = \left[1 + \frac{(1-\alpha)^2}{4}\right] \left[\frac{e^{-e^t} - e^t \cos 2t}{4} - \frac{(1-\alpha)e^t \sin 2t}{8}\right]$$
  
It the integration by parts is done using  
$$Sin 2(t-\tau)$$

When 
$$\alpha' \to 0$$
  
both of the above Schobins give  
 $Y(t) = \frac{1}{5} - e^{t} \left[ \frac{corret}{5} + \frac{sinzt}{10} \right]$ 

$$\frac{Q_{g}(short)}{P_{o}} = 1 - (P_{1} + P_{2} + P_{3} + \cdots)$$

$$= 1 - (\alpha p' + \alpha p^{2} + \alpha p^{3} + \cdots)$$

$$P_{o} = 1 - \frac{\alpha p}{1 - p} \qquad (Ceometric Series - from data boots)$$

$$as reprined.$$

(b) 
$$(1-x)^{-(n+1)} = 1 - (n+1)(-x) + \frac{-(n+1)(-n-2)}{2!}(-x)^2$$
  
 $+ \cdots$   
(Binomial expansion  
from the data back)  
 $= 1 + (n+1)x + \frac{(n+1)(n+2)}{2!}x^2 + \cdots$   
 $(1-x)^{n+1} = {n \choose n} + {n+1 \choose n}x + {n+2 \choose n}x^2 + \cdots$   
as remard.

Qq (Short)				3
$f(x,y) = 5x^3$	-24 <sup>3</sup> -62	2 + 549		
$\frac{\partial f}{\partial x} = 15x^2 - \frac{12}{2x^2}$	12249 = -9	$3x(5x-4)$ $=) x = 0$ $x = \frac{4}{5}$	0 = (E	
$\frac{\partial f}{\partial y} = -6y^2 - 6$	9×2+54 =	$-6(x^{2}+y^{2})+$	54 20	
(د	$x^2+y^2=5$	$\frac{54}{6} = 3^2$	_ ①	
$\frac{\partial f}{\partial y^2} = -129$	<b>R</b> 2	to in D	=) 4=±	3
$\frac{\partial^2 f}{\partial x^2} = -12x$	<b>%</b> =	4 y in D	=> Y = 1	15 V41
	Stationary (0,3) (0,	$-3), \left(\frac{12}{\sqrt{12}}\right),$	$\frac{15}{V_{k_1}}$ ), (-1	温, 溢)
34	324/242	224 V	$=\frac{\partial^2 f}{\partial x^2} \frac{\partial^2 f}{\partial y^2} -$	[3 <sup>-</sup> t]
(0,3) -36	-36	0	- Ve	MA-ximum
(0, -3) 36	36	0	+Ve	Winnun
$\begin{pmatrix} 12\\ V_{4_1}, V_{4_1} \end{pmatrix} = \frac{180}{V_{4_1}}$	- <u>180</u> 181	-144 V41	_ V2	Saddle
$\left(\frac{12}{V_{4}}, \frac{-15}{V_{41}}\right) -\frac{180}{V_{41}}$	180 V41	144	_~e	Saddle.



$$T = 4$$
,  $(-2, to 2)$ 

(b)  $f(t) = \frac{a_0}{2} + \sum_{h=1}^{\infty} a_h \cos \frac{2\pi ht}{T} \quad (\text{even function})$   $a_h = \frac{2}{T} \int_{-2}^{2} f(t) \cos \left(\frac{2\pi ht}{T}\right) dt$   $a_0 = \frac{1}{2} \int_{-2}^{2} f(t) dt = \int_{0}^{2} f(t) dt$   $= \left[4t - \frac{t^3}{3}\right]^2 = \frac{16}{3}$   $a_0 = \frac{16}{3}$ 

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$$a_n = \frac{1}{2} \int_{-2}^{2} (4 - t^2) \cos(\frac{n\pi t}{2}) dt$$

integrate by parts:

$$=\frac{1}{2}\left[\frac{8}{\pi h}\sin\left(\frac{n\pi t}{2}\right)\right]^{2}-\frac{1}{2}\int_{-2}^{2}t^{2}\cos\left(\frac{n\pi t}{2}\right) dt$$

$$= -\frac{1}{2} \int_{-2}^{2} t^{2} d\left[\frac{\sin(n\pi t)_{2}}{nn/2}\right]$$

$$= -\frac{1}{n\pi} \left[t^{2} \sin(n\pi t)\right]_{2}^{2} + \frac{1}{n\pi} \int_{-2}^{2} \sin(n\pi t) (2t) dt$$

$$= \frac{2}{n\pi} \int_{-2}^{2} t d \left[ \frac{-\cos(n\pi t/2)}{n\pi/2} \right]$$
  
$$= -\frac{4}{n^{2}\pi^{2}} \left[ t \cos(\frac{n\pi t}{2}) \right]_{-2}^{2} + \frac{4}{n^{2}\pi^{2}} \int_{-2}^{2} \cos \frac{n\pi t}{2} dt$$
  
$$= -\frac{4}{n^{2}\pi^{2}} \left[ 2 \cos n\pi + 2 \cosh \pi \right] + \frac{4}{n^{2}\pi^{2}} \frac{2}{n\pi} \left[ \frac{\sin(n\pi t)}{2} \right]_{-2}^{2}$$

$$a_{n.} = -\frac{16}{h^2 \pi^2} (-1)^n = \frac{16}{h^2 \pi^2} (-1)^{n+1} n \neq 0.$$

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$$f(t) = \frac{8}{3} + \frac{16}{\pi^2} \sum_{n=1}^{\infty} \frac{(-1)^{n+1}}{n^2} \cos\left(\frac{n\pi t}{2}\right)$$

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(c) 
$$f(0) = 4 = \frac{8}{3} + \frac{16}{\pi^2} = \frac{60}{100} = \frac{(-1)^{n+1}}{n^2}$$

$$=) \sum_{\substack{n=1\\n=1}}^{\infty} \frac{(-1)^{n+1}}{n^2} = \frac{\pi}{12}^2$$

$$1 - \frac{1}{2^2} + \frac{1}{3^2} - \frac{1}{4^2} + \cdots = \frac{\pi^2}{12}$$

as

## 2016 Paper 4: Mathematical Methods

# Solutions to Section C

## 11. Data structures

(a) Any one of the following four lines is acceptable:

```
board[0][0].type = Rook; board[0][0].colour = White;
board[0][7].type = Rook; board[0][7].colour = White;
board[7][0].type = Rook; board[7][0].colour = White;
                                                                                  [2]
board[7][7].type = Rook; board[7][7].colour = White;
(b)
for (int i=0; i<8; i++)</pre>
 for (int j=0; j<8; j++)
  if (board[i][j].type == Pawn) cout << i << ' ' << j << endl;
                                                                                  [4]
(c)
int n = 0:
for (int i=0; i<8; i++)</pre>
 for (int j=0; j<8; j++)</pre>
  if ((board[i][j].type != None) and (board[i][j].colour == Black)) n = n+1;
cout << n << endl;</pre>
                                                                                  [4]
```

#### 12. Algorithmic complexity and numerical accuracy

(a) f1 is clearly O(n). The complexity of f2 depends on the implementation of exp, though we can expect this to be fast on common architectures. In fact, the standard x86 implementation of pow is O(1) and appears to use more or less this method (there are single x86 machine code instructions for exponentiation and scaled logarithms). [4]

(b) The program will display a small, non-zero number. This is because f1 will calculate  $7^2$  precisely, whereas f2 will lose some precision in the floating point representation of log(7.0). The main program does, in fact, display 7.62939e-06. [3]

(c) f1 will fail when n is negative, f2 will fail when a is zero or negative. Both will fail when a and/or n are sufficiently large to cause a floating point overflow. [3]

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