

$$xy = 1 \rightarrow \text{curve } C_1$$

$$xy = 2 \rightarrow C_2$$

$$xy^3 = 3 \rightarrow C_3$$

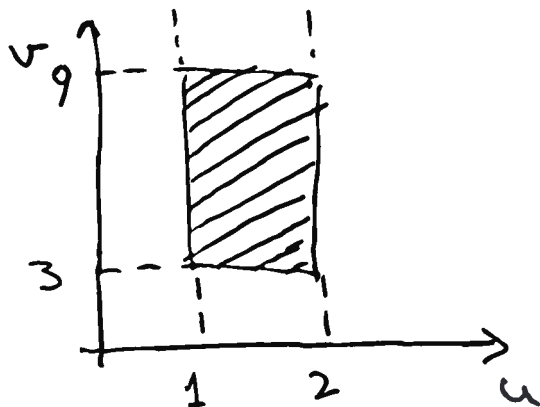
$$xy^3 = 9 \rightarrow C_4$$

(b) Required area  $A = \iint dx dy$  is difficult to integrate directly, as limits are quite complicated. We can use a transformation:

$$u = xy, \quad v = xy^3$$

$\Rightarrow$  Area becomes

$$\int_3^9 \int_1^2 \frac{1}{J} du dv$$



J: Jacobian

$$J = \begin{vmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{vmatrix} = \begin{vmatrix} y & x \\ y^3 & 3xy^2 \end{vmatrix} = 2xy^2 = 2v$$

Therefore required area is

$$\int_3^9 \int_1^2 \frac{1}{2\sqrt{v}} du dv = [u]_1^2 \cdot \int_3^9 \frac{1}{2\sqrt{v}} dv$$

$$= (2-1) \cdot \frac{1}{2} \cdot \ln \frac{9}{3} = \underline{\underline{\frac{1}{2} \ln 3}}$$

(c)  $\oint \underline{F} \cdot d\underline{e} = \iint_R \nabla \times \underline{F} \cdot d\underline{A}$  by Stokes Theorem.

$$\underline{F} = \frac{2}{5} (xy^5)^{1/2} \underline{i} + (xy)^{3/2} \underline{j}$$

$$\nabla \times \underline{F} = \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{2}{5} (xy^5)^{1/2} & (xy)^{3/2} & 0 \end{vmatrix} = -\frac{\partial}{\partial y} \left( \frac{2}{5} x^{1/2} y^{5/2} \right) + \frac{\partial}{\partial x} \left( x^{3/2} y^{3/2} \right)$$

$$= -x^{1/2} y^{3/2} + \frac{3}{2} x^{1/2} y^{3/2} = \frac{1}{2} (xy^3)^{1/2}$$

Integration is best done using the transformation of part (b)

$$\therefore \text{RHS} = \int_3^9 \int_1^2 \left( \frac{1}{2} \right) \frac{\sqrt{v}}{2\sqrt{v}} du dv$$

⇒ Required integral is

$$-\frac{1}{4} \int_3^9 v^{-1/2} dv \int_1^2 du = \left(-\frac{1}{4}\right) \cdot \left(2 \left[ v^{1/2} \right]_3^9\right) \cdot 1$$

$$= \underline{\underline{\frac{1}{2} (3 - \sqrt{3})}}$$

NOTES: Part (b) could also be done by direct integration, taking care of the various limits & curves. But in comparison to the transformation, it is quite laborious & prone to error.

Q2(a) The divergence theorem is written

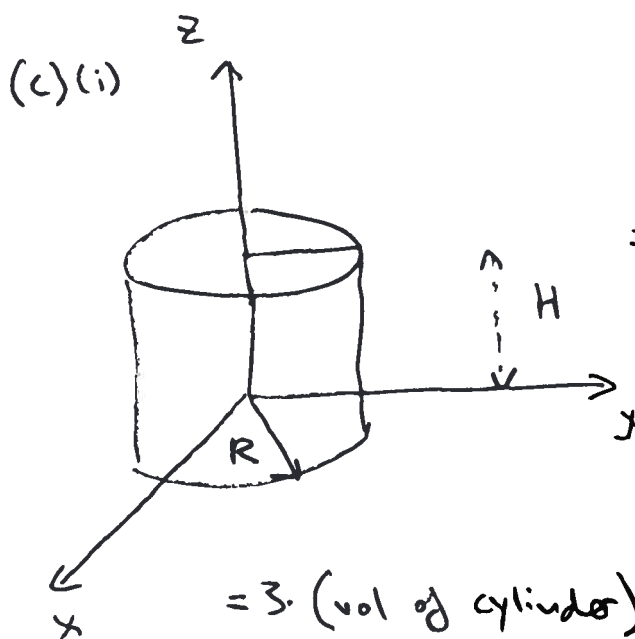
$$\text{as } \int_{\text{volume } V} \nabla \cdot \underline{F} \, dV = \oint_{\text{surface } S \text{ enclosing } V} \underline{F} \cdot \underline{n} \, dA$$

It is valid for any volume  $V$  enclosed by a closed surface  $S$ , and for any vector field  $\underline{F}$ , provided it is differentiable.

(b) The group  $\phi \nabla \psi$  can also be thought of as a vector field. Hence if  $\underline{F} = \phi \nabla \psi$  and using the divergence theorem, we get

$$\begin{aligned} \int \nabla \cdot (\phi \nabla \psi) &= \nabla \phi \cdot \nabla \psi + \phi \nabla \cdot \nabla \psi \\ &= \nabla \phi \nabla \psi + \phi \nabla^2 \psi \end{aligned}$$

$\therefore$  Green's identity is shown.



$$\underline{F} = x \underline{i} + y \underline{j} + z \underline{k}$$

$$\begin{aligned} \Rightarrow \nabla \cdot \underline{F} &= \frac{\partial x}{\partial x} + \frac{\partial y}{\partial y} + \frac{\partial z}{\partial z} \\ &= 3 \end{aligned}$$

$$\text{Hence } \oint \underline{F} \cdot \underline{n} \, dA = \int_V 3 \, dV$$

$$= 3 \cdot (\text{vol of cylinder}) = \underline{\underline{3\pi R^2 H}}$$

(4)

(c)(ii) We evaluate  $\oint \underline{F} \cdot \underline{n} \, dA$  directly.

For the top surface ( $z=H$ ),  $\underline{n}$  being pointing outwards  $z$  normal to the surface implies

$$\underline{n} = \underline{k} \Rightarrow \underline{F} \cdot \underline{n} = z \text{ at that location, i.e. } H.$$

$$\text{Hence } \int_{\text{top circular face}} \underline{F} \cdot \underline{n} \, dA = H \int dA = H \pi R^2$$

For the lower circular face at  $z=0$ ,  $\underline{n} = -\underline{k}$

$$\underline{F} \cdot \underline{n} = -z = 0. \text{ Hence, no contribution.}$$

On the curved surface, the vector normal to the surface is the unit vector in the direction

$$x\underline{i} + y\underline{j}, \text{ i.e. } \frac{x\underline{i} + y\underline{j}}{\sqrt{x^2 + y^2}} = \frac{x\underline{i} + y\underline{j}}{R}$$

$$\underline{F} \cdot \underline{n} \text{ now becomes } \frac{x^2 + y^2}{R} = \frac{R^2}{R} = R$$

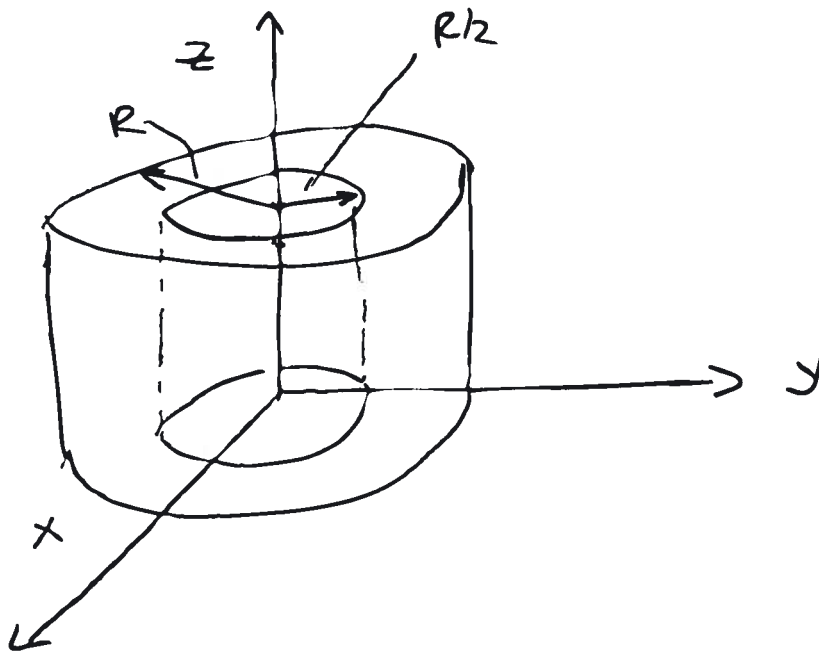
$$\text{Hence } \int_{\text{curved surface}} \underline{F} \cdot \underline{n} \, dA = R \int dA = R \cdot 2\pi R H = 2\pi R^2 H$$

Therefore total flux of  $\underline{F}$  out of the cylinder is  $\pi R^2 H + 2\pi R^2 H = 3\pi R^2 H$ , as before.

Divergence theorem is demonstrated.

(5)

(c)(iii)



From the result of Part (b), the flux of  $\underline{F}$  leaving a cylinder of height  $H$  & radius  $R$  is  $3\pi R^2 H$ . So, for the smaller cylinder, this is  $\frac{3\pi}{4} R^2 H$ . The contribution to this from

the top circular face is  $\pi H \left(\frac{R}{2}\right)^2 = \frac{1}{4} \pi R^2 H$ .

From the curved surface, it is  $2\pi H \left(\frac{R}{2}\right)^2 = \frac{2}{4} \pi R^2 H$

So, considering the new (tyre-looking) shape, the

total flux of  $\underline{F}$  outwards from the shape is

$$(3\pi R^2 H) - \left(\frac{1}{4}\pi R^2 H\right) - \left(\frac{2}{4}\pi R^2 H\right) = \underline{\underline{\frac{9}{4}\pi R^2 H}}$$

from Part (c)(i) if it were solid with radius  $R$

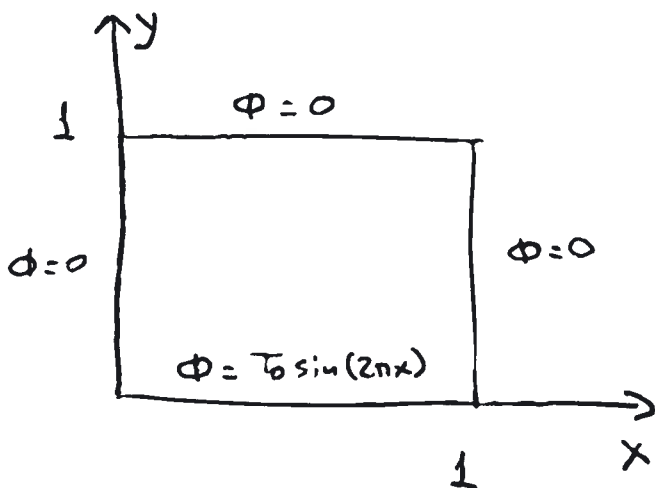
missing top surface, no flux contribution

from the curved surface at  $r = R/2$  (-ve because it comes in)

NOTE: It can also be done using divergence theorem on remaining volume.

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Q3(a)



If  $\Phi = T - T_0$ , then the equation for  $f(x,y) = 0$  becomes again 
$$\frac{\partial^2 \Phi}{\partial x^2} + \frac{\partial^2 \Phi}{\partial y^2} = 0$$

Separation of variables means we seek a solution

$$\Phi(x,y) = X(x) Y(y) \Rightarrow \frac{1}{X} \frac{d^2 X}{dx^2} = -\frac{1}{Y} \frac{d^2 Y}{dy^2} = C$$

where  $C$  is a constant.

Let us consider the b.c.'s first.

$$\text{At } x=1, \Phi=0 \Rightarrow \Phi(1,y) = X(1) \cdot Y(y) = 0$$

To avoid the trivial solution, it must be that

$$X(1) = 0.$$

At  $x=0$ ,  $\Phi=0$ . Similarly,  $X(0) = 0$ .

At  $y=1$ ,  $\Phi=0$ . Similarly,  $Y(1) = 0$ .

At  $y=0$ ,  $\Phi(x,0) = T_0 \sin(2n\pi x)$

$$\Rightarrow X(x) = T_0 \sin(2n\pi x) \quad \& \quad Y(0) = 1.$$

Writing the separation constant as  $-k^2$  ( $k>0$ )  
we get

$$\frac{1}{X} \frac{d^2 X}{dx^2} = -k^2 \quad \& \quad \frac{1}{Y} \frac{d^2 Y}{dy^2} = k^2$$

We suspect a sin dependence of  $X$  due to the boundary condition before, so it helps to keep the -ve in that part. Therefore, if

$$X = T_0 \sin(2\pi x), \quad k = 2\pi$$

$$\text{Hence, } Y = A e^{2\pi y} + B e^{-2\pi y}$$

$$\text{At } y=0, \quad Y=1 \Rightarrow A+B=1$$

$$\text{At } y=1 \quad Y=0 \Rightarrow A e^{2\pi} + B e^{-2\pi} = 0$$

Manipulating these gives

$$A = -\frac{e^{-2\pi}}{e^{2\pi} - e^{-2\pi}} \quad \& \quad B = \frac{e^{2\pi}}{e^{2\pi} - e^{-2\pi}}$$

$$\text{Final result: } \phi = T_0 \sin(2\pi x) (A e^{2\pi y} + B e^{-2\pi y})$$

$$\Rightarrow T = T_0 \left[ 1 + \sin(2\pi x) (A e^{2\pi y} + B e^{-2\pi y}) \right]$$

(b) Since  $f \neq 0$ , our previous solution does not hold any more. But we can progress using Gauss theorem:



$$\iint_{\text{over all 2D domain}} \nabla \cdot \underline{q} \, dA = \oint_{\text{over bounding curve}} \underline{q} \cdot d\underline{n}$$

$dA$ : area element  
 $\underline{n}$ : vector normal to bounding curve

$$\underline{q} = -\nabla T \Rightarrow \nabla \cdot \underline{q} = -\nabla^2 T$$

$$\Rightarrow \text{Required total flux} = \iint_{\text{0 0}} \underbrace{-\nabla^2 T}_{= f(x,y) \text{ from the PDE}} \, dx \, dy$$

$$= - \int_0^1 \sin(4\pi x) \, dx \int_0^1 \sin(4\pi y) \, dy$$

$$= \frac{1}{4\pi} \left[ \cos(4\pi x) \right]_0^1 \left( -\frac{1}{4\pi} \right) \left[ \cos(4\pi y) \right]_0^1$$

$$= 0$$

So the net flux of heat in and out is zero. From an energy conservation perspective, this is something we could have guessed given the symmetry about  $x=0.5$  for the b.c. at  $y=0$  but also the source term.

Q4.

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(a)

$$\begin{bmatrix} 3 & 4 & 0 & 1 \\ 6 & 4 & 2 & t \\ 9 & 0 & 6 & 1 \end{bmatrix} \begin{matrix} 3 & 4 & 0 & 1 \\ 1 \\ -2 \\ 3 \end{matrix} \begin{bmatrix} 3 & 4 & 0 & 1 \\ 6 & 8 & 0 & 2 \\ 9 & 12 & 0 & 3 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & -4 & 2 & t-2 \\ 0 & -12 & 6 & -2 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & -4 & 2 & t-2 \\ 0 & -12 & 6 & -2 \end{bmatrix} \begin{matrix} 0 & -4 & 2 & t-2 \\ 0 \\ 3 \end{matrix} \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & -4 & 2 & t-2 \\ 0 & -12 & 6 & 3t-6 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 6 & 4-3t \end{bmatrix}$$

$$L = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 3 & 3 & 1 \end{bmatrix} \quad U = \begin{bmatrix} 3 & 4 & 0 & 1 \\ 0 & -4 & 2 & t-2 \\ 0 & 0 & 0 & 4-3t \end{bmatrix}$$

IF  $t = \frac{4}{3}$  THEN  $A$  IS OF RANK 2.

(6)

$$A = \begin{vmatrix} 1 & b+1 & 1 \\ b-3 & 1 & 1 \\ 1 & 1 & 1-b \end{vmatrix} \quad b = \begin{vmatrix} b+5 \\ 1 \\ 5 \end{vmatrix}$$

$$\det(A) = 1 \begin{vmatrix} 1 & 1 \\ 1 & 1-b \end{vmatrix} - (b+1) \begin{vmatrix} b-3 & 1 \\ 1 & 1-b \end{vmatrix} + 1 \begin{vmatrix} b-3 & 1 \\ 1 & 1 \end{vmatrix} =$$

$$= 1-b-1 - (b+1)((b-3)(1-b) - 1) + b-3-1 =$$

$$= -4 - ((b-3)(1-b^2) - 1 - b) = -4 + b + 1 - b(1-b^2) + 3(1-b^2) = b - b(1-b^2) - 3b^2 = b^3 - 3b^2 = b^2(b-3)$$

IF  $b \neq 0$  AND  $b \neq 3$  THEN SOLUTION IS UNIQUE. FIND BY GAUSSIAN ELIMINATION.

$$\begin{vmatrix} 1 & b+1 & 1 \\ b-3 & 1 & 1 \\ 1 & 1 & 1-b \end{vmatrix} \begin{vmatrix} b+5 \\ 1 \\ 5 \end{vmatrix} \Rightarrow \begin{vmatrix} 0 & b & b \\ b-3 & 1 & 1 \\ 1 & 1 & 1-b \end{vmatrix} \begin{vmatrix} b \\ 1 \\ 5 \end{vmatrix} \Rightarrow$$

$$\Rightarrow \begin{vmatrix} 0 & 1 & 1 \\ b-3 & 1 & 1 \\ 1 & 1 & 1-b \end{vmatrix} \begin{vmatrix} 1 \\ 1 \\ 5 \end{vmatrix} \Rightarrow \begin{vmatrix} 0 & 1 & 1 \\ b-3 & 0 & 0 \\ 1 & 1 & 1-b \end{vmatrix} \begin{vmatrix} 1 \\ 0 \\ 5 \end{vmatrix} \Rightarrow \begin{vmatrix} 0 & 1 & 1 \\ b-3 & 0 & 0 \\ 1 & 0 & -b \end{vmatrix} \begin{vmatrix} 1 \\ 0 \\ 4 \end{vmatrix}$$

$$\text{HENCE } x=0, z = -\frac{4}{b}, y = 1 + \frac{4}{b}$$

(B-CONTINUED)

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IF  $k=0$  THEN

$$\left| \begin{array}{ccc|c} 1 & 1 & 1 & 5 \\ 3 & 1 & 1 & 1 \\ 1 & 1 & 1 & 5 \end{array} \right| \Rightarrow \left| \begin{array}{ccc|c} 1 & 1 & 1 & 5 \\ 2 & 0 & 0 & -4 \\ 0 & 0 & 0 & 0 \end{array} \right|$$

HENCE THERE IS A FAMILY OF SOLUTIONS:

$$x=1, y=4-z$$

IF  $k=3$  THEN

$$\left| \begin{array}{ccc|c} 1 & 4 & 1 & 8 \\ 0 & 1 & 1 & 1 \\ 1 & 1 & -2 & 5 \end{array} \right| \Rightarrow \left| \begin{array}{ccc|c} 0 & 3 & 3 & 3 \\ 0 & 1 & 1 & 1 \\ 1 & 1 & -2 & 5 \end{array} \right| \Rightarrow \left| \begin{array}{ccc|c} 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 1 & 0 & -3 & 4 \end{array} \right|$$

HENCE THERE IS A FAMILY OF SOLUTIONS:

$$x=4+3z, y=1-z$$

$$(c) \quad C - 2I = -C^2$$

Let  $\lambda, x$  be any eigen value and eigen vector.

We have  $Cx = \lambda x$ . Hence

$$(C - 2I)x = -C^2x$$

$\Downarrow$

$$Cx - 2Ix = -C^2x$$

$\Downarrow$

$$\lambda x - 2x = -C(2x)$$

$\Downarrow$

$$(\lambda - 2)x = -2x^2$$

$$(\lambda^2 + \lambda - 2)x = 0$$

$$\text{Hence } \lambda = \frac{-1 \pm \sqrt{1+8}}{2} = 1 \text{ OR } -2$$

(a)

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$$A = \begin{bmatrix} a & b & c \\ c & a & 0 \\ c & 0 & a \end{bmatrix}$$

$$A - \lambda I = \begin{bmatrix} a-\lambda & b & c \\ c & a-\lambda & 0 \\ c & 0 & a-\lambda \end{bmatrix}$$

$$\det(A - \lambda I) = (a-\lambda) \begin{vmatrix} a-\lambda & 0 \\ 0 & a-\lambda \end{vmatrix} - b \begin{vmatrix} c & 0 \\ c & a-\lambda \end{vmatrix}$$

$$+ b \begin{vmatrix} c & a-\lambda \\ c & 0 \end{vmatrix} = (a-\lambda)^3 - 2bc(a-\lambda)$$

$$- bc(a-\lambda) = (a-\lambda)(a-\lambda)^2 - 2bc$$

$$\begin{bmatrix} a & b & c \\ c & a & 0 \\ c & 0 & a \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = a \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

EIGEN VECTOR FOR EIGENVALUE  $a$

$$ax + by + cz = ax \quad \Rightarrow$$

$$cx + ay + 0 = ay \quad \Rightarrow x=0 \text{ AND } y=-2$$

$$cx + 0y + az = az \quad \Rightarrow$$

(a-CONTINUED)

OTHER EIGEN VALUES ARE:

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$$\lambda = a \pm \sqrt{2bc}$$

$$\begin{bmatrix} a & b & c \\ c & a & 0 \\ c & 0 & a \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = (a \pm \sqrt{2bc}) \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

$$ax + by + cz = ax \pm \sqrt{2bc}x \Rightarrow by + cz = \pm \sqrt{2bc}x$$

$$cx + ay = (a \pm \sqrt{2bc})y \Rightarrow y = \pm \frac{cx}{\sqrt{2bc}}$$

$$cx + az = (a \pm \sqrt{2bc})z \Rightarrow z = \pm \frac{cx}{\sqrt{2bc}}$$

$$by + cz = \pm \frac{bcx}{\sqrt{2bc}} + \pm \frac{bcx}{\sqrt{2bc}} = \pm \sqrt{2bc}x$$

$$\Downarrow \\ \pm \frac{2\sqrt{bc}}{\sqrt{2}} = \pm \sqrt{2bc}x$$

CORRECT FOR ALL X.

SO EIGEN VECTORS ARE  $\begin{bmatrix} \pm \sqrt{2b/c} \\ 1 \\ 1 \end{bmatrix}$

$$\text{FOR ANY } n = \text{DET}(A) = (a-\lambda)^{n-2} ((a-\lambda)^2 - (n-2)bc)$$

EIGENVECTORS:  $\begin{bmatrix} \pm \sqrt{(n-2)b/c} \\ 1 \\ \vdots \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix}, \dots, \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \\ -1 \end{bmatrix}$

$\underbrace{\hspace{10em}}_{n-2}$

Q5 (a) (i)

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$$A = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} \quad q_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \quad \tilde{a}_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix} - \frac{1}{2} \left( \begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix} \right) \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix} =$$

$$= \begin{bmatrix} 1/2 \\ 1 \\ 1/2 \\ 1 \end{bmatrix}$$

$$q_2 = \frac{\sqrt{2}}{\sqrt{5}} \begin{bmatrix} 1/2 \\ 1 \\ 1/2 \\ 1 \end{bmatrix} \quad \tilde{a}_3 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} - \frac{2}{5} \left( \begin{bmatrix} 1/2 \\ 1 \\ 1/2 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right) \begin{bmatrix} 1/2 \\ 1 \\ 1/2 \\ 1 \end{bmatrix} =$$

$$= \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} - \frac{2}{5} \begin{bmatrix} 1/2 \\ 1 \\ 1/2 \\ 1 \end{bmatrix} = \begin{bmatrix} -1/5 \\ 2/5 \\ -1/5 \\ 3/5 \end{bmatrix}$$

$$q_3 = \frac{1}{\sqrt{15}} \begin{bmatrix} -1 \\ -2 \\ -1 \\ 3 \end{bmatrix}$$

$$Q = \begin{bmatrix} -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{10}} & -\frac{1}{\sqrt{15}} \\ 0 & \frac{\sqrt{2}}{\sqrt{5}} & -\frac{2}{\sqrt{15}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{10}} & \frac{1}{\sqrt{15}} \\ 0 & \frac{\sqrt{2}}{\sqrt{5}} & \frac{3}{\sqrt{15}} \end{bmatrix} \quad R = \begin{bmatrix} -\frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{10}} & \frac{\sqrt{2}}{\sqrt{5}} & \frac{1}{\sqrt{10}} & \frac{\sqrt{2}}{\sqrt{5}} \\ -\frac{1}{\sqrt{15}} & -\frac{2}{\sqrt{15}} & \frac{1}{\sqrt{15}} & \frac{3}{\sqrt{15}} \end{bmatrix} \quad A = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} =$$

$$= \begin{bmatrix} \frac{2}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ 0 & \frac{\sqrt{2}}{\sqrt{2}} & \frac{\sqrt{2}}{\sqrt{5}} \\ 0 & 0 & \frac{3}{\sqrt{15}} \end{bmatrix}$$



(a-ii)

A - RANK 3

$$A^T A x = A^T b$$

$$(Q R^T) Q R x = (Q R)^T b$$

Hence  $R^T Q^T Q R x = R^T Q^T b$ ;

$$R^T R x = R^T Q^T b \quad (Q \text{ - ORTHOGONAL})$$

$$R x = Q^T b \quad (R \text{ - NOW SINGULAR})$$

$$\begin{bmatrix} 2 \\ \frac{1}{\sqrt{2}} \\ 0 \\ 0 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{\sqrt{2}}{\sqrt{5}} \\ \frac{\sqrt{2}}{\sqrt{15}} \\ \frac{2}{\sqrt{15}} \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -\frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{10}} & \frac{\sqrt{2}}{\sqrt{5}} & \frac{1}{\sqrt{10}} & \frac{\sqrt{2}}{\sqrt{5}} \\ -\frac{1}{\sqrt{15}} & -\frac{2}{\sqrt{15}} & \frac{1}{\sqrt{15}} & \frac{3}{\sqrt{15}} \end{bmatrix} \begin{bmatrix} -1 \\ 0 \\ 1 \\ 2 \end{bmatrix}$$

$$z = \frac{\sqrt{15}}{3} \left( \frac{1 - 2 - 0 - 1 + 6}{\sqrt{15}} \right) = 2$$

$$\frac{\sqrt{5}}{\sqrt{2}} y + \frac{2\sqrt{2}}{\sqrt{5}} = -\frac{1}{\sqrt{10}} + \frac{1}{\sqrt{10}} + \frac{2\sqrt{2}}{\sqrt{5}} \Rightarrow y = 0$$

$$x = 1$$

$$\text{SO } x = \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}$$

(6)

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$$A = \begin{pmatrix} a & 0 \\ 1 & -a \end{pmatrix}$$

WHEN  $a \neq 0$  EIGEN VALUES ARE DISTINCT:  $a$  AND  $-a$  (DIAGONAL) SINCE  
 $A$  IS LOWER TRIANGULAR

EIGEN VECTORS ARE: FOR  $\lambda = a$

$$Ax = ax \Rightarrow \begin{bmatrix} ax_1 \\ x_1 - ax_2 \end{bmatrix} = \begin{bmatrix} ax_1 \\ ax_2 \end{bmatrix} \Rightarrow x_2 = \frac{1}{2a}x_1 \Rightarrow \begin{bmatrix} 2a \\ 1 \end{bmatrix} \frac{1}{\sqrt{4a^2+1}}$$

FOR  $\lambda = -a$

$$\begin{bmatrix} a & 0 \\ 1 & -a \end{bmatrix} x = -ax \Rightarrow \begin{bmatrix} ax_1 \\ x_1 - ax_2 \end{bmatrix} = \begin{bmatrix} -ax_1 \\ -ax_2 \end{bmatrix} \Rightarrow \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$A$  CAN BE DIAGONALISED AS

$$D = P^{-1}AP, \text{ WHERE } D = \begin{bmatrix} a & 0 \\ 0 & -a \end{bmatrix}, P = \begin{bmatrix} \frac{2a}{\sqrt{4a^2+1}} & 0 \\ \frac{1}{\sqrt{4a^2+1}} & 1 \end{bmatrix}$$

HENCE  $A = PDP^{-1}$ . SO  $A^{20} = P D^{20} P^{-1} =$

$$= P \begin{bmatrix} a & \\ & -a \end{bmatrix}^{20} P^{-1} = a^{20} P \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} P^{-1} = a^{20} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}.$$

IF  $a=0$  THEN

$$\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ a & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \text{ HENCE } A^{20} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}.$$

① SINCE  $x_1$  AND  $x_2$  ARE ON A PLANE.

(C) NORMAL OF A PLANE IS  $\vec{n} = \begin{bmatrix} 2 \\ -3 \\ 1 \end{bmatrix}$

SINCE FOR ANY TWO POINTS  $x_1 = \begin{bmatrix} x_1 \\ y_1 \\ z_1 \end{bmatrix}$ ,  $x_2 = \begin{bmatrix} x_2 \\ y_2 \\ z_2 \end{bmatrix}$

WE HAVE A VECTOR  $\vec{c} = x_1 - x_2$ .

$$\vec{n} \cdot \vec{c} = \begin{bmatrix} 2 \\ -3 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} x_1 - x_2 \\ y_1 - y_2 \\ z_1 - z_2 \end{bmatrix} = 2x_1 - 3y_1 + z_1 - (2x_2 - 3y_2 + z_2) = 0 - 0 = 0 \quad \text{①}$$

(C - CONTINUED)

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LET  $u = \begin{bmatrix} 3 \\ 2 \\ 0 \end{bmatrix}$  AND  $v = \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix}$  TWO LINEARLY

INDG PNDGNI POINTS ON THE PLANE.

USING GRAHAM-SCHMIDT:

$$\vec{q}_1 = \frac{u}{\|u\|} = \frac{1}{\sqrt{13}} \begin{bmatrix} 3 \\ 2 \\ 0 \end{bmatrix}$$

$$\begin{aligned} \vec{v} &= v - (q_1 \cdot v)q_1 = \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix} - \frac{1}{\sqrt{13}} \left( \begin{bmatrix} 3 \\ 2 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix} \right) \cdot \frac{1}{\sqrt{13}} \begin{bmatrix} 3 \\ 2 \\ 0 \end{bmatrix} = \\ &= \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix} - \frac{2}{13} \begin{bmatrix} 3 \\ 2 \\ 0 \end{bmatrix} = \frac{1}{13} \begin{bmatrix} -6 \\ 9 \\ 39 \end{bmatrix} = \frac{3}{13} \begin{bmatrix} -2 \\ 3 \\ 13 \end{bmatrix} \end{aligned}$$

$$\vec{q}_2 = \frac{1}{\sqrt{182}} \begin{bmatrix} -2 \\ 3 \\ 13 \end{bmatrix}$$

SO THE BASIS IS  $\left\{ \frac{1}{\sqrt{13}} \begin{bmatrix} 3 \\ 2 \\ 0 \end{bmatrix}, \frac{1}{\sqrt{182}} \begin{bmatrix} -2 \\ 3 \\ 13 \end{bmatrix} \right\}$

$$q_1 \cdot q_2 \propto \begin{bmatrix} 3 \\ 2 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} -2 \\ 3 \\ 13 \end{bmatrix} = -6 + 6 = 0$$

$$\vec{q}_1 \cdot \vec{v} \propto \begin{bmatrix} 3 \\ 2 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix} = 0$$

$$q_2 \cdot \vec{v} \propto \begin{bmatrix} -2 \\ 3 \\ 13 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix} = -4 - 9 + 13 = 0$$

(d) (i)

6/7

$$A^T A = \begin{bmatrix} 0 & 1 & 0 \\ a & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & a & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & a^2 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

EIGEN VALUES ARE 1,  $a^2$  AND 0 (DIAGONAL).

$$q_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad q_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \quad q_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$Q = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

SINGULAR VALUES: 1,  $|a|$ , 0

$$\hat{q}_1 = \frac{A q_1}{1} = \frac{\begin{bmatrix} 0 & a & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}}{1} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$$\hat{q}_2 = \frac{A q_2}{|a|} = \frac{\begin{bmatrix} 0 & a & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}}{|a|} = \frac{1}{|a|} \begin{bmatrix} a \\ 0 \\ 1 \end{bmatrix}$$

$$A A^T = \begin{bmatrix} 0 & a & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ a & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} a^2 & 0 & a \\ 0 & 1 & 0 \\ a & 0 & 1 \end{bmatrix}$$

EIGEN VECTOR FOR GIVEN VALUE 0 IS  $\begin{bmatrix} 1 \\ 0 \\ -a \end{bmatrix} \cdot \frac{1}{\sqrt{1+a^2}}$

(d-i - CONTINUOUS)

7/7

IF  $0 < |a| < 1$  THEN

$$A = \hat{Q}\hat{\Sigma}\hat{Q}^T = \begin{bmatrix} 0 & \frac{a}{|a|} & \frac{1}{\sqrt{1+a^2}} \\ 1 & 0 & 0 \\ 0 & \frac{1}{|a|} & -a \cdot \frac{1}{\sqrt{1+a^2}} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & |a| & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} =$$

$$= \begin{bmatrix} 0 & a & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

IF  $|a| > 1$

$$A = \hat{Q}\hat{\Sigma}\hat{Q}^T = \begin{bmatrix} \frac{a}{|a|} & 0 & \frac{1}{\sqrt{1+a^2}} \\ 0 & 1 & 0 \\ \frac{1}{|a|} & 0 & -a \cdot \frac{1}{\sqrt{1+a^2}} \end{bmatrix} \begin{bmatrix} |a| & 0 & 0 \\ 0 & 1 & 0 \\ a & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} =$$

$$= \begin{bmatrix} a & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & a & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

IF  $a=0$  THEN  $\hat{q}_1 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$   $\hat{q}_2 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$  AND EIGENVECTOR FOR  $\lambda=0$  OF  $AA^T$  IS  $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ .

HENCE  $A = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$

(ii) COLUMN SPACE  $\left\{ \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} a \\ 0 \\ 1 \end{bmatrix} \right\}$  ROW SPACE  $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\}$

LEFT NULL SPACE  $\left\{ \begin{bmatrix} 1 \\ 0 \\ a \end{bmatrix} \right\}$  NULL SPACE  $\left\{ \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$

Q6.

(a)(i)

FOR BOTH TEAMS TO PLAY ALL 7 ROUNDS,  
BOTH OF THEM NEED TO WIN 3 TIMES.

$$P(A \text{ WINS 3 OF 6}) = \binom{6}{3} p^3 (1-p)^3 = \frac{6!}{3!3!} p^3 (1-p)^3 = 20 p^3 (1-p)^3$$

NOTE, WHEN A WINS 3 THEN B WINS 3 AS WELL.

(a)(ii)

LET  $k$  BE NUMBER OF HOME WINS FOR A.

THEN

$$P(A \text{ WINS 3 OF 6}) = \sum_{k=0}^3 \binom{3}{k} p^k (1-p)^{3-k} \cdot \binom{3}{k} q^{3-k} (1-q)^k$$

(b)

LET  $X^0$  AND  $X^1$  BE RANDOM VARIABLES COUNTING THE  
NUMBER OF TIMES 0s AND 1s TRANSMITTED RESPECTIVELY.

$Y = X^0 + X^1$  - TOTAL NUMBER OF SYMBOLS TRANSMITTED.

WE HAVE:

$$P(X^0 = n, X^1 = m) = P(X^0 = n, X^1 = m | Y = n+m) P(Y = n+m) =$$

$$= \binom{n+m}{n} p^n (1-p)^m \frac{\lambda^{n+m} e^{-\lambda}}{(n+m)!} = \frac{(p\lambda)^n e^{-\lambda p}}{n!} \cdot \frac{e^{-\lambda(1-p)} (\lambda(1-p))^m}{m!}$$

$$\text{HENCE } P(X^0 = n) = \sum_{m=0}^{\infty} P(X^0 = n, X^1 = m) =$$

(c - CONTINUED)

$$= \frac{e^{-\lambda p} (\lambda p)^n}{n!} e^{-\lambda(1-p)} \sum_{m=0}^{\infty} \frac{\lambda(1-p)^m}{m!} = \quad (1)$$

$$= \frac{e^{-\lambda p} (\lambda p)^n}{n!} e^{-\lambda(1-p)} e^{\lambda(1-p)} = \frac{e^{-\lambda p} (\lambda p)^n}{n!}$$

(1) - POISSON PMF WITH PARAMETER  $\lambda(1-p)$  SUMS TO 1.

HENCE  $X^0$  IS POISSON WITH PARAMETER  $\lambda p$ .

(c) (i)

$$F_Z(z) = P(Z \leq z) = p P(X \leq z) + (1-p) P(Y \leq z) = p F_X(z) + (1-p) F_Y(z)$$

DIFFERENTIATING WITH RESPECT TO  $z$ , WE GET:

$$f_Z(z) = p f_X(z) + (1-p) f_Y(z)$$

(ii) LET  $X$  BE RV WITH PDF:

$$f_X(x) = \begin{cases} \lambda e^{-\lambda x}, & \text{IF } x < 0, \\ 0, & \text{OTHERWISE} \end{cases}$$

AND  $Y$  s.t

$$f_Y(y) = \begin{cases} 0 & \text{IF } y < 0 \\ \lambda e^{-\lambda y} & \text{OTHERWISE} \end{cases}$$



CDF'S OF  $X$  AND  $Y$  ARE

$$F_X(x) = \begin{cases} e^{\lambda x}, & \text{IF } x < 0 \\ 1 & \text{OTHERWISE} \end{cases}$$

AND

$$F_Y(y) = \begin{cases} 0, & \text{IF } y < 0 \\ 1 - e^{-\lambda y}, & \text{OTHERWISE} \end{cases}$$

FROM PART (c-i) WE HAVE

$$F_Z(z) = p F_X(z) + (1-p) F_Y(z) =$$

$$= \begin{cases} p e^{\lambda z}, & z < 0 \\ p + (1-p)(1 - e^{-\lambda z}) = 1 - (1-p)e^{-\lambda z}, & \text{OTHERWISE} \end{cases}$$

(c-ii)

$$E(Z) = \int_{-\infty}^{\infty} z f_Z(z) dz = \int_{-\infty}^0 z p \lambda e^{\lambda z} dz + \int_0^{\infty} z (1-p) \lambda e^{-\lambda z} dz$$

$$= -p \int_0^{\infty} z \lambda e^{-\lambda z} dz + (1-p) \int_0^{\infty} z \lambda e^{-\lambda z} dz = \frac{p}{\lambda} + \frac{(1-p)}{\lambda} = \frac{1-2p}{\lambda}$$

$$E(Z^2) = \int_{-\infty}^{\infty} z^2 f_Z(z) dz = \int_{-\infty}^0 z^2 p \lambda e^{\lambda z} dz + \int_0^{\infty} z^2 (1-p) \lambda e^{-\lambda z} dz =$$

$$= \frac{2p}{\lambda^2} + \frac{2(1-p)}{\lambda^2} = \frac{2}{\lambda^2} \quad \text{HENCE } \text{VAR}(Z) = \frac{2}{\lambda^2} - \frac{(1-2p)^2}{\lambda^2}$$

(d)

4/4

$$P(S < s) = P(\max(x_1, x_2, \dots, x_n)) =$$

$$= P(x_1 < s \cap x_2 < s \cap \dots \cap x_n < s) \stackrel{(1)}{=} P(x < s)^n \stackrel{(2)}{=} (1 - e^{-\lambda s})^n$$

(1) INDEPENDENCE OF  $x_1, x_2$

(2) CDF OF EXP( $\lambda$ )

(3) DERIVATIVE OF CDF W.R.T.  $s$ .

$$\text{HENCE PDF } f_S(s) = n \lambda e^{-\lambda s} (1 - e^{-\lambda s})^{n-1} \quad (3)$$