

1)

$$(a) \quad \sigma_{rr} = A - \frac{B}{r^2} - \frac{E\alpha}{r^2} \int_0^r r T_0 \left(1 - \frac{r^2}{b^2}\right) dr \quad \text{- for plane stress}$$

$$\sigma_{\theta\theta} = A + \frac{B}{r^2} + \frac{E\alpha}{r^2} \int_0^r r T_0 \left(1 - \frac{r^2}{b^2}\right) dr - E\alpha T_0 \left(1 - \frac{r^2}{b^2}\right)$$

$$\int_0^r r T_0 \left(1 - \frac{r^2}{b^2}\right) dr = \frac{1}{2} T_0 r^2 \left(1 - \frac{1}{2} \frac{r^2}{b^2}\right)$$

B.C.       $\sigma_{rr}$  finite at  $r=0 \Rightarrow B=0$

$$\sigma_{rr} = 0 \text{ @ } r=b \Rightarrow A = \frac{E\alpha T_0}{4}$$

$$\Rightarrow \sigma_{rr} = -\frac{E\alpha T_0}{4} \left(1 - \frac{r^2}{b^2}\right)$$

$$\sigma_{\theta\theta} = \frac{E\alpha T_0}{4} + \frac{E\alpha T_0}{2} \left(1 - \frac{1}{2} \frac{r^2}{b^2}\right) - E\alpha T_0 \left(1 - \frac{r^2}{b^2}\right)$$

$$= -\frac{E\alpha T_0}{4} \left(1 - \frac{3r^2}{b^2}\right)$$

Now convert to plane strain

$$\sigma_{rr} = -\frac{E\alpha T_0}{4(1-\nu)} \left(1 - \frac{r^2}{b^2}\right); \quad \sigma_{\theta\theta} = -\frac{E\alpha T_0}{4(1-\nu)} \left(1 - \frac{3r^2}{b^2}\right)$$

$$\epsilon_{zz} = 0 \Rightarrow \sigma_{zz} = \nu(\sigma_{\theta\theta} + \sigma_{rr}) = -\frac{\nu E\alpha T_0}{2(1-\nu)} \left(1 - \frac{2r^2}{b^2}\right)$$

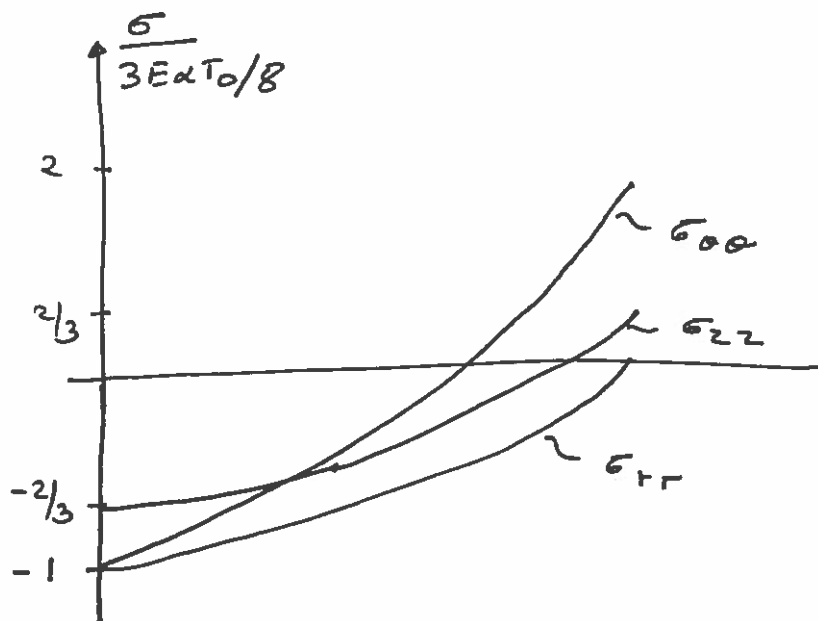
$$\sigma_{r\theta} = 0$$

$$(b) \quad \nu = \frac{1}{3}$$

$$\sigma_{rr} = - \frac{3E\alpha T_0}{8} \left(1 - \frac{r^2}{b^2}\right)$$

$$\sigma_{\theta\theta} = - \frac{3\alpha E T_0}{8} \left(1 - 3\frac{r^2}{b^2}\right)$$

$$\sigma_{zz} = - \frac{E\alpha T_0}{4} \left(1 - 2\frac{r^2}{b^2}\right)$$



$$(c) \quad \frac{u}{r} = \epsilon_{\theta\theta} = \frac{1}{E} (\sigma_{\theta\theta} - \nu\sigma_{rr} - \nu\sigma_{zz})$$

$$u = \frac{r}{E} \left( \frac{-E\alpha T_0}{4(1-\nu)} \right) \left[ 1 - \frac{3r^2}{b^2} - \nu \left(1 - \frac{r^2}{b^2}\right) - 2\nu^2 \left(1 - \frac{2r^2}{b^2}\right) \right]$$

$$\text{@ } r=b \quad u = \frac{-\alpha b T_0}{4(1-\nu)} (-2 + 2\nu^2) = \frac{\alpha b T_0}{2} (1 + \nu)$$

(d)

$$\tau_{\max} = \max \left[ \frac{|\sigma_{rr} - \sigma_{\theta\theta}|}{2}, \frac{|\sigma_{\theta\theta} - \sigma_{zz}|}{2}, \frac{|\sigma_{zz} - \sigma_{rr}|}{2} \right]$$

Inspection shows (see b)  $\tau_{\max}$  occurs at  $r_2 = b$  with

$$\tau_{\max} = \frac{\gamma}{2} = \frac{|\sigma_{rr} - \sigma_{\theta\theta}|}{2} = \frac{E\alpha T_0}{4(1-\nu)}$$

If no yielding may allowable  $T_0$  is

$$T_0 = \frac{2(1-\nu)\gamma}{E\alpha}$$

(2)

$$(a) \quad ① \quad \frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \sigma_{xy}}{\partial y} + F_x = 0 \quad \&$$

$$② \quad \frac{\partial \sigma_{xy}}{\partial x} + \frac{\partial \sigma_{yy}}{\partial y} + F_y = 0 \quad \text{where } F_x = 0; F_y = -\rho g$$

① is automatically satisfied ;

$$③ \quad \rho g - \rho y = 0 \quad \checkmark \quad \text{at } y = 0 \quad -\sigma_{yy} A = \rho g h A \\ \Rightarrow C = -\rho g h$$

$$\sigma_{yy} = \rho g (y - h)$$

$$(b) \quad \epsilon_{xx} = -\frac{\nu \sigma_{yy}}{E} = \frac{\partial u}{\partial x} = -\frac{\nu \rho g}{E} (y - h)$$

$$u = \frac{\nu \rho g}{E} (h - y)x + f(y)$$

$$\epsilon_{yy} = \frac{\sigma_{yy}}{E} = \frac{\partial v}{\partial y} = \frac{\rho g}{E} (y - h)$$

$$\Rightarrow v = \frac{\rho g}{E} \left( \frac{y^2}{2} - hy \right) + g(x)$$

$$\gamma_{xy} = 0 = -\frac{\nu \rho g x}{E} + f'(y) + g'(x) = 0$$

$$f'(y) = 0 \quad ; \quad f(y) = C_1$$

$$g(x) = \frac{\nu \rho g x^2}{2E} + C_2$$

$$u = \frac{\nu \rho g}{E} (h-y)x \quad \text{as } u=0 \text{ @ } x=0$$

$$v = \frac{\rho g}{E} \left( \frac{y^2}{2} - hy \right) + \frac{\nu \rho g x^2}{2E} \quad \left[ C_2 = 0 \text{ as } v=0 \text{ @ } x=0 \text{ \& } y=0 \right]$$

$$(c) \quad U = \int_0^h \frac{1}{2} \sigma_{yy} \epsilon_{yy} dy A$$

$$= \frac{A}{2E} \int_0^h \rho^2 g^2 (y-h)^2 dy = \frac{A \rho^2 g^2 h^3}{6E}$$

(d)

$$\epsilon_{xx} = ~~\frac{\sigma_{xx}}{E}~~ - \frac{\nu \sigma_{yy}}{E} + \alpha \Delta T$$

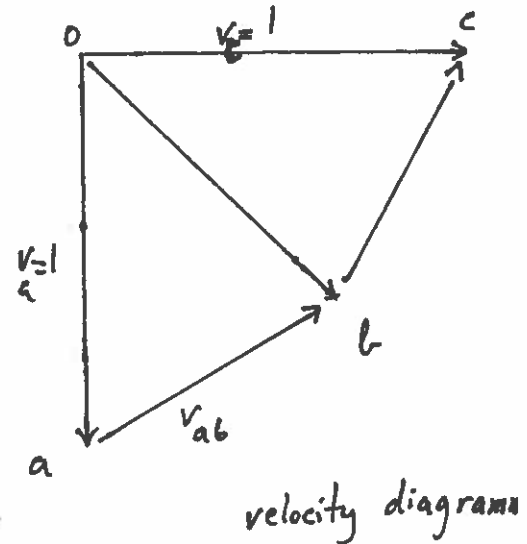
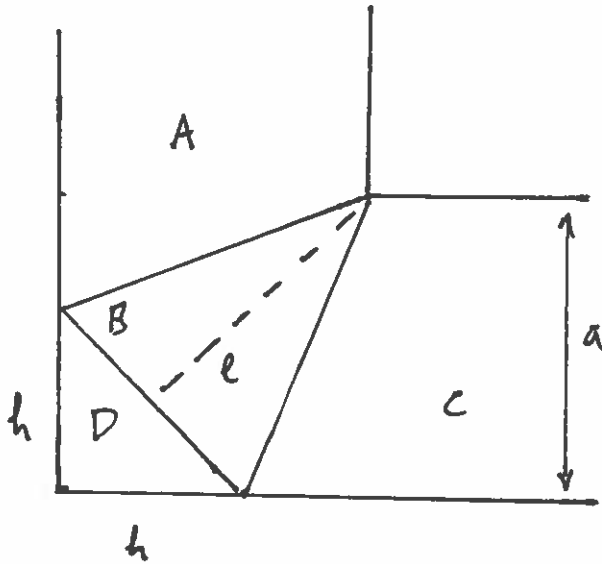
$$\epsilon_{yy} = \frac{\sigma_{yy}}{E} + \alpha \Delta T$$

$$\Rightarrow u = \frac{\nu \rho g}{E} (h-y)x + \alpha \Delta T x$$

$$v = \frac{\rho g}{E} \left( \frac{y^2}{2} - hy \right) + \frac{\nu \rho g x^2}{2E} + \alpha \Delta T y$$

3 a) After postulating a collapse mechanism the maximum forming load can be computed. This gives a conservative estimate for the design of the forming equipment.

b)



$$l^2 = \sqrt{2} a - \frac{h}{\sqrt{2}}$$

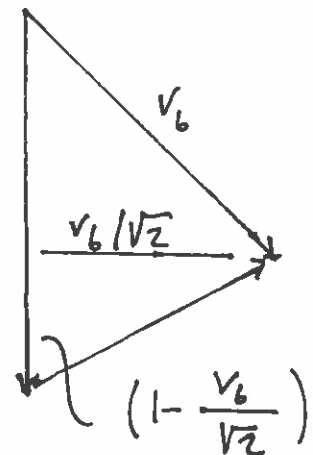
- Volume conservation (set  $v_a = 1$  too shorten the equations)

$$v_a = v_c = 1$$

$$1 \cdot a = v_b \cdot l \Rightarrow v_b = \frac{a}{\sqrt{2} a - \frac{h}{\sqrt{2}}} = \frac{1}{\sqrt{2} - \frac{x}{\sqrt{2}}} = \frac{\sqrt{2}}{2-x}$$

- determine  $v_{ab}$  from velocity diagram

$$\begin{aligned} v_{ab}^2 &= \frac{v_b^2}{2} + \left(1 - \frac{v_b}{\sqrt{2}}\right)^2 \\ &= \frac{v_b^2}{2} + 1 - \frac{2}{\sqrt{2}} v_b + \frac{v_b^2}{2} \\ &= 1 - \frac{\sqrt{2}}{2} v_b + v_b^2 \\ &= 1 - \frac{2}{2-x} + \frac{2}{(2-x)^2} = \frac{x^2 - 2x + 2}{(2-x)^2} \end{aligned}$$



- length of interface between blocks A and B

2

$$l_{ab}^2 = a^2 + (a-h)^2 = 2a^2 - 2ah + h^2$$

- length of interface between blocks B and D

$$l_{bd} = \sqrt{2} h$$

Upper bound theorem

$$p \cdot a \cdot l = k (l_{ab} v_{aL} + l_{bd} v_{bd} + l_{bc} v_{bc})$$

note that  $l_{ab} = l_{bc}$

$$v_{aL} = v_{bc}$$

$$v_{bd} = v_c$$

$\Rightarrow$

$$\frac{p a}{k} = 2 \sqrt{2a^2 - 2ah + h^2} \cdot \frac{\sqrt{x^2 - 2x + 2}}{2-x} + \sqrt{2} h \frac{\sqrt{2}}{2-x}$$

$$\frac{p}{2k} = \sqrt{2 - 2x + x^2} \frac{\sqrt{x^2 - 2x + 2}}{2-x} + \frac{x}{2-x}$$

$$= \frac{x^2 - x + 2}{2-x} = \underline{\underline{1 + \frac{x^2}{2-x}}}$$

ii)  $\frac{d(p/2k)}{dx} = \frac{2x}{2-x} + \frac{x^2}{(2-x)^2} = 0$

$$2x(2-x) + x^2 = 0$$

$$4x - x^2 = 0 \Rightarrow x=0; r_{min} = 2k$$

iii)

Length of "outer lining":  $2(a + a - h) = 4a - 2h$

Length of "inner lining" =  $2a$

Upper bound theorem

$$p \cdot a = 2ka \left( 1 + \frac{x^2}{2-x} \right) + k \ell (4a - 2h + 2a)$$

$$\frac{p}{2k} = 1 + \frac{x^2}{2-x} + \ell (3-x)$$



(4)

$$\phi = \frac{Cr^2}{\tan \alpha - \alpha} \left[ \alpha - \theta + \frac{\sin 2\theta}{2} - \tan \alpha \cos^2 \theta \right]$$

$$\frac{\partial \phi}{\partial r} = \frac{2Cr}{\tan \alpha - \alpha} \left[ \alpha - \theta + \frac{\sin 2\theta}{2} - \tan \alpha \cos^2 \theta \right]$$

$$\frac{\partial^2 \phi}{\partial r^2} = \frac{2C}{\tan \alpha - \alpha} \left[ \alpha - \theta + \frac{\sin 2\theta}{2} - \tan \alpha \cos^2 \theta \right]$$

$$\frac{\partial \phi}{\partial \theta} = \frac{Cr^2}{\tan \alpha - \alpha} \left[ -1 + \cos 2\theta + 2 \tan \alpha \sin \theta \cos \theta \right]$$

$$\frac{\partial^2 \phi}{\partial \theta^2} = \frac{Cr^2}{\tan \alpha - \alpha} \left[ -2 \sin 2\theta + 2 \tan \alpha (\cos^2 \theta - \sin^2 \theta) \right]$$

$$\frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial \phi}{\partial \theta} \right) = \frac{C}{\tan \alpha - \alpha} \left[ -1 + \cos 2\theta + 2 \tan \alpha \sin \theta \cos \theta \right]$$

$$\sigma_{rr} = \frac{1}{r} \frac{\partial \phi}{\partial r} + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2}$$

$$= \frac{C}{\tan \alpha - \alpha} \left[ 2\alpha - 2\theta - \sin 2\theta - 2 \tan \alpha \sin^2 \theta \right]$$

$$\sigma_{\theta\theta} = \frac{\partial^2 \phi}{\partial r^2} = \frac{C}{\tan \alpha - \alpha} \left[ 2\alpha - 2\theta + \sin 2\theta - 2 \tan \alpha \cos^2 \theta \right]$$

$$\sigma_{r\theta} = -\frac{\partial}{\partial r} \left[ \frac{1}{r} \frac{\partial \phi}{\partial \theta} \right] = \frac{C}{\tan \alpha - \alpha} \left[ 1 - \cos 2\theta - 2 \tan \alpha \sin \theta \cos \theta \right]$$

h) along OB :  $\sigma_{ra} = \sigma_{\theta\theta} = 0$

along OA :  $\sigma_{ra} = 0 ; \sigma_{\theta\theta} = -p$

$$\sigma_{\theta\theta}|_{\theta=\alpha} = \frac{C}{\tan \alpha - \alpha} [2\alpha - 2\alpha - \sin 2\alpha - 2\sin \alpha \cos \alpha] = 0$$

$$\sigma_{ra}|_{\theta=\alpha} = \frac{C}{\tan \alpha - \alpha} [1 - \cos 2\alpha - 2\sin^2 \alpha] = 0$$

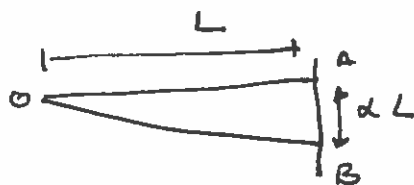
$\Rightarrow$  B. C. along OB satisfied

$$\sigma_{\theta\theta}|_{\theta=0} = \frac{C}{\tan \alpha - \alpha} [2\alpha - 2\tan \alpha] = -2C = -p$$

$$C = p/2$$

$$\sigma_{ra}|_{\theta=0} = \frac{C}{\tan \alpha - \alpha} [1 - 1 - 0] = 0$$

(c) (i)



consider cantilever of unit depth

$$M = pL \frac{L}{2} = \frac{pL^2}{2}$$

$$I @ AB = \frac{b d^3}{12} = \frac{1(\alpha L)^3}{12}$$

$$\sigma \text{ at A} = \frac{My}{I} = \frac{pL^2}{2} \frac{\alpha L}{2} \frac{12}{\alpha^3 L^3} = \frac{3p}{\alpha^2}$$

$$(ii) \quad G_{rr} |_{\theta=0} = \frac{p}{2(\tan \alpha - \alpha)} \quad (2\alpha)$$

$$\tan \alpha \sim \alpha + \frac{\alpha^3}{3}$$

$$= \frac{p}{\frac{2\alpha^3}{3}} \quad 2\alpha = \frac{3p}{\alpha^2}$$