

RANDOM AND NON-LINEAR VIBRATION CRTBS 2015

1) a) $m\ddot{x} + b\dot{x} + kx + \lambda v = ma$ — (1)

$C\dot{v} + v/R = \lambda \dot{x}$ — (2)

Put $x(t) = x(\omega) e^{i\omega t}$ and $v(t) = v(\omega) e^{i\omega t}$, $a(t) = a(\omega) e^{i\omega t}$

$$\Rightarrow \left. \begin{aligned} (-m\omega^2 + i\omega b + k)x + \lambda v &= ma \\ (C i\omega + 1/R)v &= \lambda i\omega x \end{aligned} \right\} \Rightarrow \underbrace{\left[\frac{\lambda^2 i\omega}{C i\omega + 1/R} \right]}_{H^{-1}(\omega)} x = a$$

So $x = H(\omega)a \Rightarrow \dot{x} = i\omega H(\omega)a \Rightarrow S_{\dot{x}\dot{x}} = |i\omega H|^2 S_{aa}(\omega)$

for white noise input $S_{\dot{x}\dot{x}}(\omega) = \omega^2 |H|^2 S_0$ where H is defined above. [30%]

b) For $C=0$ equation (2) yields $v = \lambda R \dot{x}$

Equation (1) then becomes $m\ddot{x} + (b + \lambda^2 R)\dot{x} + kx = ma$

Standard results for a system with white noise input $m\ddot{x} + c\dot{x} + kx = F$ $S_{FF}(\omega) = S_0$

$\Rightarrow \sigma_{\dot{x}}^2 = \pi S_0 / (ckm^2) \times m^2$

$\sigma_{\ddot{x}}^2 = \pi S_0 / (cm^3) \times m^2$

Here $c = b + \lambda^2 R$ and $F = ma \Rightarrow S_{FF} = m^2 S_0$. Thus:

$\sigma_{\dot{x}}^2 = \frac{\pi S_0 m^2}{(b + \lambda^2 R)k}$, $\sigma_{\ddot{x}}^2 = \frac{\pi S_0 m^2}{(b + \lambda^2 R)m}$ [30%]

Power dissipated by damper $P_1 = b\dot{x}^2 \Rightarrow E[P_1] = b\sigma_{\dot{x}}^2$
 by resistor $P_2 = \lambda^2 R \dot{x}^2 \Rightarrow E[P_2] = \lambda^2 R \sigma_{\dot{x}}^2$ } $E[P_1 + P_2] = \frac{\pi S_0}{m} \times m^2 = \pi S_0 m$

$$c) \quad \nu_b^+ = \frac{1}{2\pi} \left(\frac{\sigma_i}{\sigma_x} \right) e^{-\frac{1}{2}(b/\sigma_x)^2}$$

$$P_{fail} = 1 - e^{-\nu_b^+ T}$$

$$\text{Number of peaks in 1 hour} = \nu_b^+ T_1 = \frac{1}{2\pi} \left(\frac{\sigma_i}{\sigma_x} \right) T_1 \quad T_1 = 60 \times 60 \text{ s} = 1 \text{ hour}$$

$$= 1000$$

$$\Rightarrow \text{When } T = 3 \times T_1, \text{ then } \nu_b^+ T = 3000 \Rightarrow \nu_b^+ T = 3000 \times e^{-\frac{1}{2}(b/\sigma_x)^2}$$

$$\text{For } b = 5\sigma_x \text{ then } \nu_b^+ T = 3000 e^{-\frac{1}{2}5^2} = 0.0112$$

$$\Rightarrow P_{fail} = 1 - e^{-0.0112} = \underline{0.0111}$$

[30%]

d) Instead of $S_{aa} = S_0$ we have $S_{aa} = \omega^2 S_0$

For $S_{xx}(\omega)$ numerator $\rightarrow \omega^k$ For large ω
 denominator $\rightarrow \omega^k$

$$\Rightarrow \int_{-\infty}^{\infty} S_{xx}(\omega) d\omega \rightarrow \infty, \text{ non-physical}$$

[10%]

2) a) $p(x, \dot{x}) = C \exp\{-(\dot{x}/a)^2 - (x/d)^4\}$

$$v_b^+ = \int_0^\infty \dot{x} p(x, b) dx = C e^{-(b/d)^4} \int_0^\infty \dot{x} e^{-(\dot{x}/a)^2} d\dot{x} \quad \text{with } x=b$$

$$\int_0^\infty -\frac{1}{2} a^2 \frac{d}{d\dot{x}} [e^{-(\dot{x}/a)^2}] d\dot{x} = \frac{1}{2} a^2$$

$\Rightarrow v_b^+ = \frac{1}{2} C a^2 e^{-(b/d)^4}$ [25%]

b) Number of peaks above b in time T = $v_b^+ T$

Total number of peaks = $v_0^+ T$

Probability a peak is $> b = v_b^+ / v_0^+ = 1 - P(b)$; $P(b)$ = probability Function

$p(b) = \frac{d}{db} P(b) = -\frac{1}{v_0^+} \frac{d}{db} (v_b^+) = -\frac{d}{db} e^{-(b/d)^4}$

$p(b) = \frac{4b^3}{d^4} e^{-(b/d)^4}$ [25%]

c) Stros amplitude = $\beta \times$ peak height = βb

$\Rightarrow 1/N = \alpha^{-1} s^2 = (\beta^2/\alpha) b^2 \Rightarrow E[1/N] = (\beta^2/\alpha) E[b^2]$

$E[b^2] = \int_0^\infty b^2 p(b) db = \frac{4}{d^4} \int_0^\infty b^5 e^{-(b/d)^4} db$

Put $b^2 = y \Rightarrow db = dy/(2b) = \frac{1}{2} y^{-1/2} dy$
 $b^5 = y^{5/2}$

$E[b^2] = \frac{2}{d^4} \int_0^\infty y^2 e^{-(y/d^2)^2} dy$

Standard integral. Put $1/d^4 = 1/2\sigma^2$, result is $\frac{1}{2} \sqrt{2\pi} \sigma^3 = \frac{1}{2} \sqrt{2\pi} \frac{1}{2\sqrt{2}} d^6$

$E[b^2] = \frac{2}{d^4} \times \frac{\sqrt{\pi}}{4} d^6 = \frac{\sqrt{\pi}}{2} d^2$

$\Rightarrow E[1/N] = \left(\frac{\beta^2 \sqrt{\pi}}{2\alpha}\right) d^2$ [25%]

Note - only two students correctly changed the variables on this integral

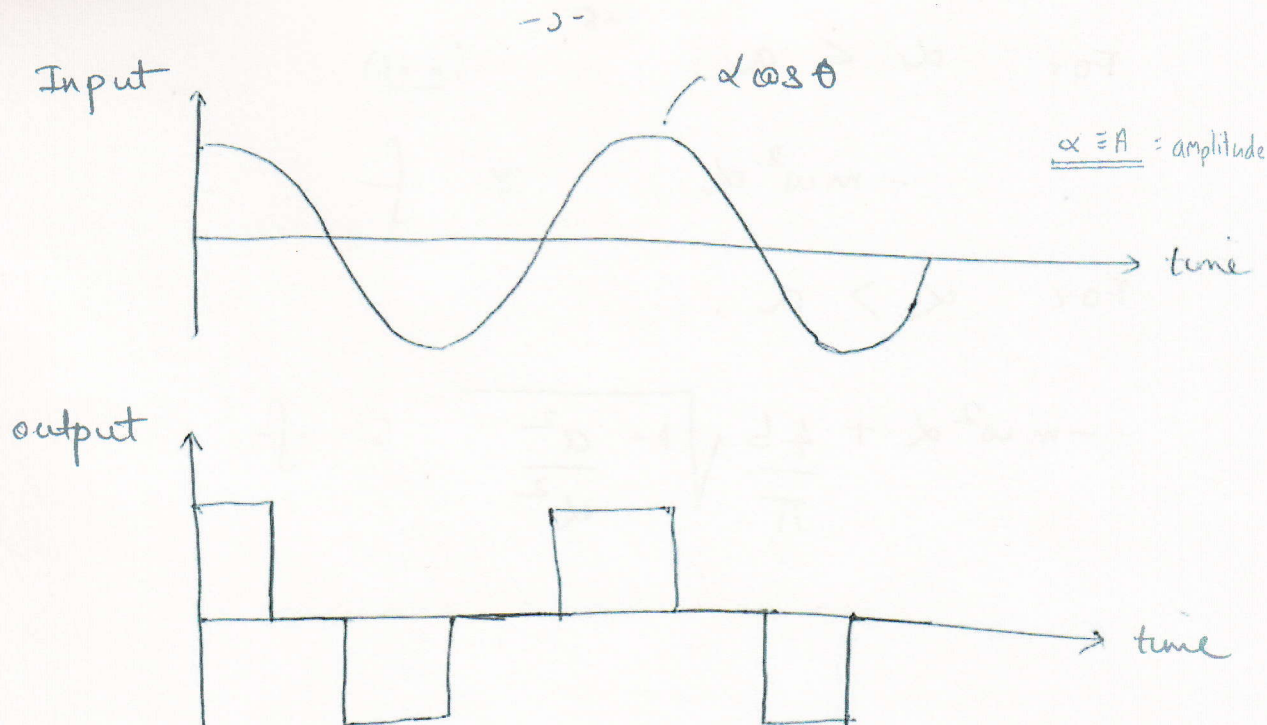
d) Number of peaks in time $T = \nu_0^+ T$

Fatigue damage in time $T = \nu_0^+ T \times E[1/N] = D$

For failure $D=1 \Rightarrow T = \{ \nu_0^+ E[1/N] \}^{-1}$

$$E[1/N] = \left(\frac{\beta^2 \sqrt{\pi}}{2\alpha} \right) d^2 ; \nu_0^+ = \frac{1}{2} C a^2 \Rightarrow T = \frac{6\alpha}{\sqrt{\pi} C \beta^2 d^2 a^2} \quad [25\%]$$

Q3 (a)



(b) Describing Function = 0 for $a < a$

For the case $a > a$

$$D.F. = \frac{1}{2\pi} \int_0^{2\pi} (\text{output}) \cos \theta \, d\theta$$

$$= \frac{4}{2\pi} \int_0^{\beta} b \cos \theta \, d\theta \quad ; \quad \beta = \cos^{-1}\left(\frac{a}{a}\right)$$

$$= \frac{4b}{2\pi} \sin \beta$$

$$= \frac{4b}{2\pi} \sqrt{1 - \frac{a^2}{a^2}}$$

(c) The equation of motion for the system in the Describing Function approximation is:

$$m\ddot{x} + (D.F.)x \approx f \cos \omega t$$

For $\alpha < a$ ($\alpha \approx a$)

$$-m\omega^2 \alpha \approx f$$

For $\alpha > a$

$$-m\omega^2 \alpha + \frac{4b}{\pi} \sqrt{1 - \frac{a^2}{\alpha^2}} \approx f$$

(b) Describing function = 0 for $\alpha < a$
 for the case $\alpha > a$

$$D.F. = \frac{1}{m} \int_0^{\pi} f(\alpha \cos \theta) \cos \theta d\theta$$

$$= \frac{1}{m} \int_0^{\pi} \left[-m\omega^2 \alpha \cos \theta + \frac{4b}{\pi} \sqrt{1 - \frac{a^2}{\alpha^2 \cos^2 \theta}} \cos \theta \right] \cos \theta d\theta$$

$$= \frac{4b}{\pi m} \int_0^{\pi} \sqrt{1 - \frac{a^2}{\alpha^2 \cos^2 \theta}} \cos^2 \theta d\theta$$

(c) The equivalent of motion for the system in the describing function approximation is $m\ddot{x} + (D.F.)\dot{x} \approx f \cos \omega t$

(a) Singular points given by:

$$\dot{x} = 0 \quad \text{and} \quad \dot{y} = 0$$

$$y - y^3 = 0 \Rightarrow y = 0, y = \pm 1$$

$$\text{and } -\alpha x - y^2 = 0 \Rightarrow \text{for } y = 0, x = 0$$

$$\text{for } y = \pm 1, -\alpha x - 1 = 0$$

$$\therefore \text{for } y = \pm 1, x = -\frac{1}{\alpha}$$

singular points are $(0, 0)$, $(-\frac{1}{\alpha}, 1)$, $(-\frac{1}{\alpha}, -1)$

(b) linearising about $(0, 0)$

$$A = \begin{bmatrix} 0 & 1 \\ -\alpha & 0 \end{bmatrix}$$

eigenvalues given by:

$$\begin{vmatrix} -\lambda & 1 \\ -\alpha & -\lambda \end{vmatrix} = 0 \Rightarrow \lambda^2 + \alpha = 0$$

$$\lambda = \pm \sqrt{-\alpha}$$

centre if $\alpha > 0$ and saddle point if $\alpha < 0$

linearising about $(-\frac{1}{\alpha}, 1)$

$$A = \begin{bmatrix} 0 & -2 \\ -\alpha & -2 \end{bmatrix}$$

eigenvalues given by:

$$\begin{vmatrix} -\lambda & -2 \\ -\alpha & -2-\lambda \end{vmatrix} = 0 \Rightarrow \lambda^2 + 2\lambda - 2\alpha = 0$$

$$\Rightarrow \lambda = -1 \pm \sqrt{1 + 2\alpha}$$

\therefore saddle point if $\alpha > 0$, stable node for $\alpha < 0$
and stable focus for $\alpha < -0.5$

Note - the phase plane is (x, y) .
Some students considered (y, \dot{y}) ,
which is not intended

linearising about $(-1/\alpha, -1)$

$$A = \begin{bmatrix} 0 & -2 \\ -\alpha & 2 \end{bmatrix}$$

eigenvalues of A given by:

$$\begin{vmatrix} -\lambda & -2 \\ -\alpha & 2-\lambda \end{vmatrix} = 0 \Rightarrow \lambda^2 - 2\lambda - 2\alpha = 0$$

$$\lambda = 1 \pm \sqrt{1+2\alpha}$$

$\alpha > 0 \Rightarrow$ saddle point, if $-0.5 < \alpha < 0 \Rightarrow$ unstable node
and if $\alpha < -0.5 \Rightarrow$ unstable focus.

(c) origin is a centre and the other two equilibrium points are saddle points

