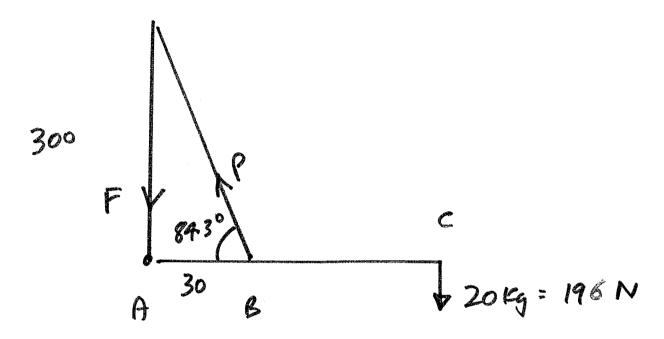
1.(a)



Take moments about A for ulna.

P. sin 84.3.30 = 196.300

Resolve volitally

F + 196.2 = P. sin 84.3

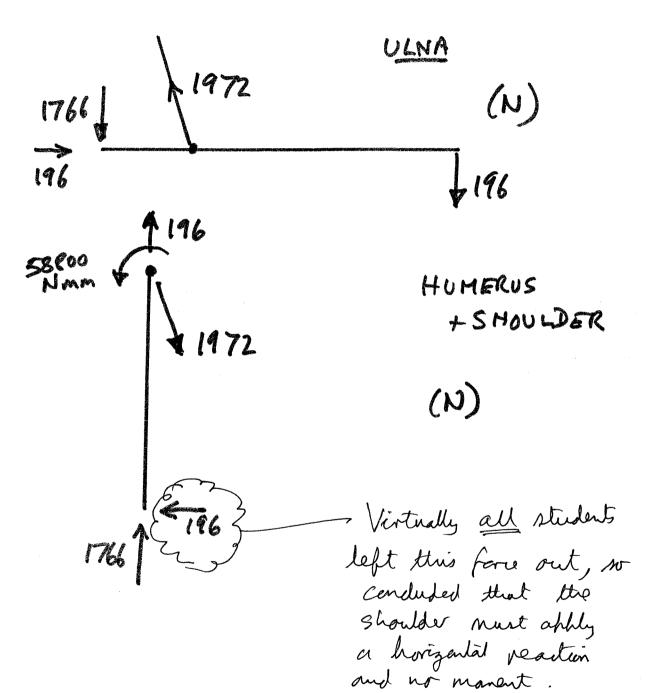
[5 marks]

⇒ F: 1766 N

Humerus is in compression.

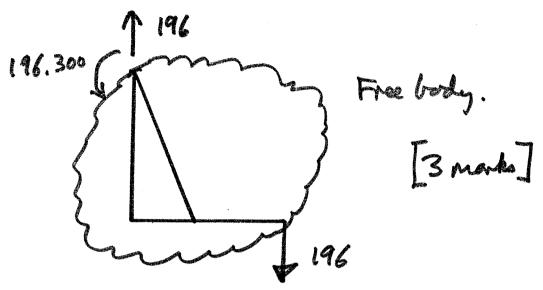
Birefo must enert a horizontal force at B of PGD 84.3 = 196 N

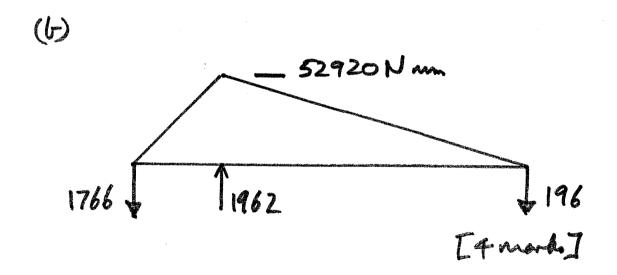
This must be balamed by a force at the elbow



V3(3)

Shoulde reactions can also be found from global equilibrium







(G) Need to shlit the loading into combonants. Several valid ways of doing this

Method I. Assume clamb at albow and then apply rigid body rotation later

$$S_{B1} : 196(30)^{3} + 196.270.30^{2} = 196.(300)^{3}$$

$$3 E I$$

$$= 1.76 \cdot 10^{6} + 23.8.10^{6} = 1.76 \cdot 10^{9}$$

$$E I$$

$$E I$$

Plus
$$\begin{cases}
1962 \uparrow \\
4 & \end{cases}
\end{cases} = -270.1962.(30)^{2}$$

$$2. ET$$

$$\begin{cases}
61 = 1962 (30)^{3} \\
3. ET
\end{cases} = -238 10^{6}$$

$$ET$$

$$17.7.10^{6}$$

Total downward deflection at C is

(1760 - 238) 106 = 1522.106

ET

Correct this with rigid body rotation

$$\frac{1522 \cdot 10^6}{E1}$$

. . Upword movement at B

Mother 2

Assume support at A & B

$$S = 196. \frac{270.30}{3EI} \cdot 270 + 196. \frac{(270)^3}{3EI}$$

$$= \frac{1430.10^6}{E7}$$

Rotate anticlocheric about A to climinate S, as a rigid body

Rotation = 1800.106 / 300

... Upwards movement of $B = 1430.10^6$. $\frac{36}{E2}$

= 143.10⁶ . (N, mm)

which is the some so method I (to rouding ever) as enfected.

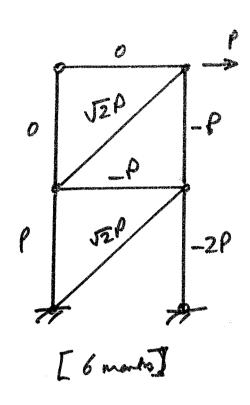
Most students tried a version of Method I but as earn be seen here it is much more long-winder, and most attempts made some simplifying assumptions, or simply didn't enhance the logic brokerly.

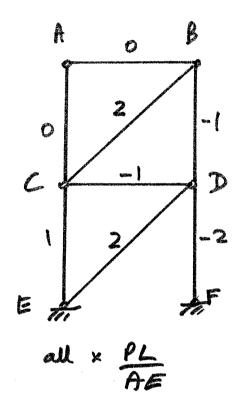
Since EI has dimensions, which are not sheified, it is important to note what wints are being used in the calculation. Many condidates lost marks for lack of care with units.

2 (4)

FORCES

EXTENSIONS



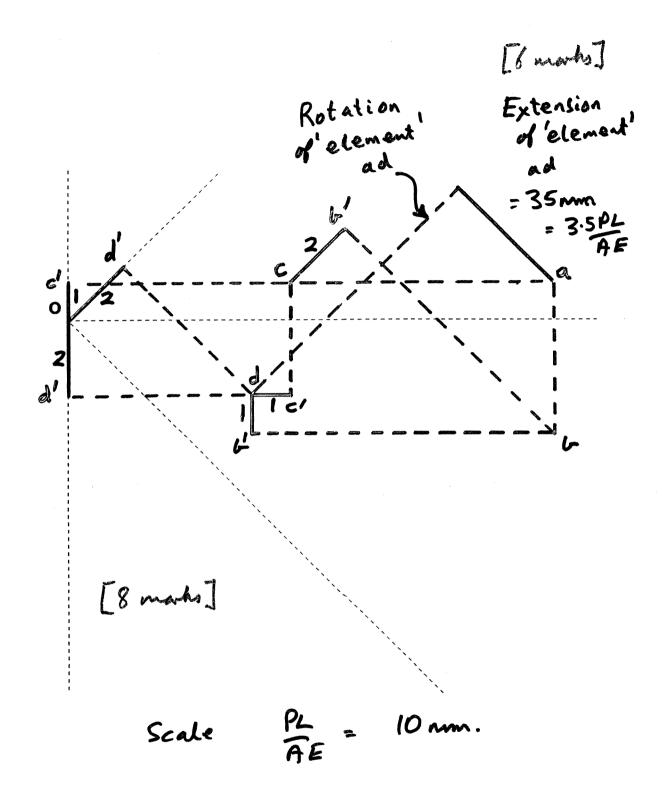


Desplacement biogram on rent sheet

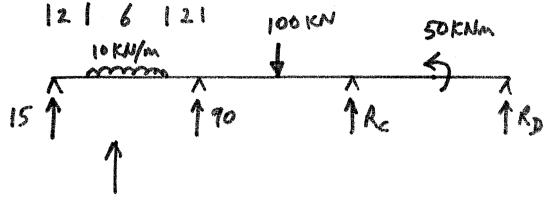
Common arror. Forces wrong. Must start analysis with point where only two unthrown forces, since only 2 equil. equations. So order should be A, B, C, D. Many students forgot that length of CB & ED is 12L.

To find charge in length A > D, sinagine there is a prember AD. Then blot an diagram the entension and rotation of this cinaginal clement. The entension is the part that is wanted, not the told mavement ad.

Many candidates got the direction of the entensions arrang on the diplacement diagram, enherially C as bound from d.



3 (a)



Total load = 10 kN/m x 6 m = 60 KN

More than half of the candidates made this 80 KN!

A beam on 4 supports would normally be statically inheterminate, but two of the support reactions have been given.

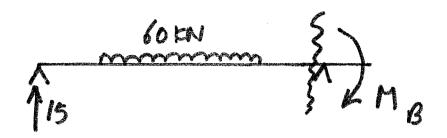
. Re + Ro can be bound by sunfle equilibrium

Resolve votially

Take moments about D (to eliminate one of the unknowns)

5 marks

(b) Take a bree body out at B



MB = 60 x 5 - 15.10 = 150 KNM

Take a bree body out at C

Me = 25.10 - 50 = 200 KNM

[5 marks]

To draw B.M & S.F diagrams, lake free body cuts at appropriate places.

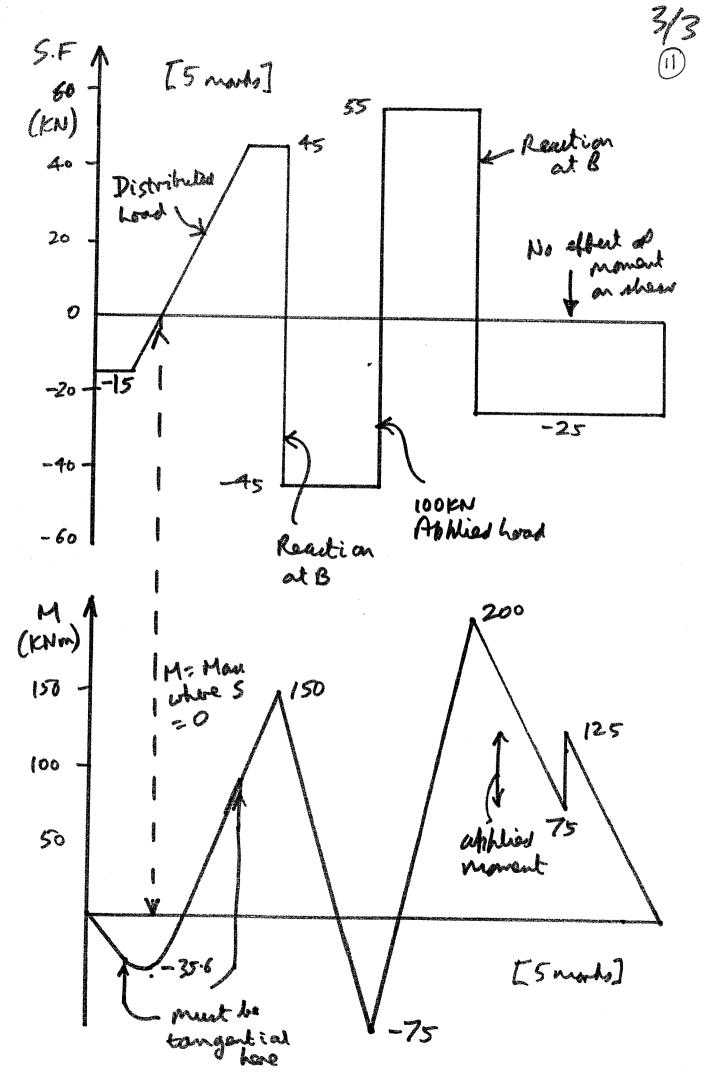
Comman errors. Making it four too complicated.

Not taking bree body cuts carefully when constructing

M + S diagrams. Question is not difficult but

many students tried to do it "by inshedien" which

does not work!



4/1

A(a) $I_{timber} = \frac{100.200^3}{12} = 0.666.10^8 \text{ nm}^4$

[2 mah]

Area of CFRP = 100 nm

Tuibe removed and replaced by CFRP

:. Effective area of CFRP = (108 -1).100

so timber = 1100 mm²

Find height above roffet of new antorid = 5

 $\bar{y} = 100.200.100 + 1100.12.5 = 95.4 \text{ mm}$ 100.200 + 1100

New $I = 0.666.10^8$ (old value) + 100.200 (100 - 95.4)² (about new axis) + $\frac{110.5^2}{12}$. (CPRP about own) axis - regligible) + $1100 (95.4 - 12.5)^2$ (CPRP about \bar{y})

= 0.746.108 mmt (timber units)

[6 marks]

This hart done well by more students.

(4)

5 1 4m 15

[Zmarks]

Mat centre = 10,2.1 - 5.2 = -5 KNm

More than 50% of candidates got the moment wrong!

Manimum bending steep in triber without repair (not asked for but a useful comparisin)

 $= \frac{M_{y}}{I} = \frac{5.10^{6}.100}{0.666.10^{8}} = 7.5 \text{ N/nm}^{2}$

Marinim bending stress in timber after repair (y = 104.6 mm)

= 5.106.104.6 = 7.01 N/mm² 0.746.108 [2marks]

Menine bending stress in CFRP (y = 95.4 - 10 = 85.4 nm)

= 5.10⁶.85.4.10⁸ = 68.6 N/m² 0.746.10⁸ 9 [2 marks]

Many students left this term out.

(6)

This was not recognised by most students. They took a shear permeter across whole width of beam

> This is the permete where show failing could one if the CFRP would break away

at ends = 5 KW

Many students got this army!

S (A5) T.t = 50, 108 (95.4-12.5) (i.e. in timber units) 25 mm

(timber units) (2×10+5)

Important that there are both $T = \frac{5.10^{3}}{2.5}.50.108 \left(\frac{15.4 - 12.5}{9}\right)$ in the same material units

[8 marks] 0.133 N/nm2

Area being considered is 50.108 = 600 mm²

because it is the actual CFRI that would break away, not leaving behind a preio of trinker.

5(a) Because the misalignment cause on increase in moment due to Pe, which then causes an additional deflection Development in turn cause an increased moment. This is the basic cause of bruskling.

When dealing with flexural hours, the leves arm is not affected by small deflected by small deflected of the beam, so there is no vicious curile with moments being made worse.

[4 marks]

$$M = -EI \frac{d^2v}{dn^2} = P(e+v)$$

(c) Solution is $U = A \sin \alpha x + B \cos \alpha x - e$ where $\alpha^2 = PEI$

Ally boundary conditions

So solution is

Many students made no attempt to apply boundary conditions, or invented totally false ones, like du=0 at x=0!

(d) 1/2 of Ender load :. P =
$$\pi^2 E I$$
 $\frac{1}{2L^2}$

$$CDRL = -0.609$$
 $CDRL/2 = 0.445$

$$-\frac{1}{100}\left(\frac{5}{6}\right)^{-1} = \frac{1+0.604}{0.797} \cdot 0.896 + 0.445 - 1$$

= 1.248

Il e= 100 additional deflection = 0.01248L.

Many students did not try to apply routh of (c) to this host and got ridiculous answers.

C J Burgoyne



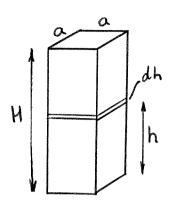
ENGINEERING TRIPOS PART IA SECTION B: MATERIALS

JUNE 2003

6. (a) $m = \rho V = \rho a^2 (H - h)$ above a typical section

$$\sigma(h) = \frac{mg}{a^2} = \rho g(H - h)$$
 (compression)

Local
$$\varepsilon(h) = \frac{\sigma(h)}{E} = \frac{\rho g}{E} (H - h)$$
 (compressive)



Length change of a typical element of length dh is εdh .

Total length change
$$\Delta H = \int_0^H \varepsilon \ dh = \frac{\rho g}{E} \int_0^H (H - h) \ dh = \frac{\rho g H^2}{2E}$$

Fractional change in length $=\frac{\Delta H}{H} = \frac{\rho g H}{2 E}$

(strictly
$$\frac{\Delta H}{H - \Delta H}$$
 , negligible difference for small $\frac{\Delta H}{H}$)

For
$$\frac{\Delta H}{H} = 0.001\%$$
, $\rho = 2750 \text{ kg/m}^3$, $E = 123 \times 10^9 \text{ N/m}^2$, $g = 9.81 \text{ m}^2/\text{s}$

$$\Rightarrow H = 92.7 \text{ m}$$

$$\sigma_{base} = \rho g H = 1000 \, \text{MPa} \implies H \approx 37 \, \text{km}$$
, i.e. stone is very strong.

(Note: the strength value in the question is on the high side, and is strictly for small samples of high quality stone; values for bulk masonry could be around 50 times lower, but the conclusion is essentially the same – tall stone structures are not close to their compressive strength, but are limited by bending).

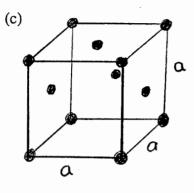
(b)
$$f = f(EI, l, M_o)$$
, i.e. assume $f \propto (EI)^{\alpha} l^{\beta} M_o^{\gamma}$

Dimensions M, L, T:
$$T^{-1} \propto (ML^3 T^{-2})^{\alpha} (L)^{\beta} (M)^{\gamma}$$

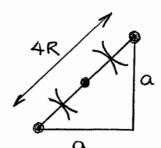
Considering only T:
$$-1 = -2\alpha$$
, $\alpha = \frac{1}{2}$ so $f \propto \sqrt{E}$, $E \propto f^2$

(Not needed, but
$$\alpha = -\gamma$$
, $\gamma = -\frac{1}{2}$ and $3\alpha = -\beta$, $\beta = -\frac{3}{2}$; so $(EI) \propto M_o l^3 f^2$





Atoms touch on diagonals of the faces.



$$2a^2 = (4R)^2$$

$$a = 2\sqrt{2} R$$

Cube volume =
$$a^3 = (2\sqrt{2} R)^3$$

Number of atoms/cube =
$$8 \times \frac{1}{8} + 6 \times \frac{1}{2} = 4$$

Volume of atoms/cube = $4 \times \frac{4}{3} \pi R^3$

Hence packing factor
$$= \frac{\binom{16\pi/3}{R^3}}{(2\sqrt{2})R^3} = 0.74$$

Mass of Al atom =
$$\frac{\text{atomic mass}}{\text{Avogadro's constant}} = \frac{26.9815}{6.022 \times 10^{26}} = 4.48 \times 10^{-26} \text{ kg}$$

Hence
$$\rho = \frac{4 \times 4.48 \times 10^{-26}}{(2\sqrt{2} \times 1.432 \times 10^{-10})^3} = 2700 \text{ kg/m}^3$$
; same as databook value.

Examiner's comments

Popular question, done by most candidates, with above average marks.

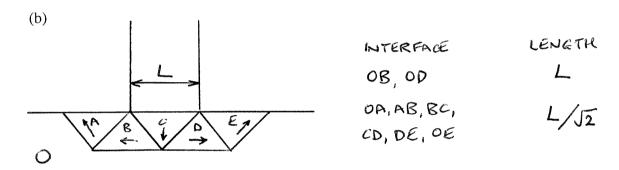
Part (a) was very close to an Examples problem, but many still failed to appreciate that stress and strain varied with depth. The purpose of the question is to recognise that the change in length required integration, but many simply used the stress at the base to find a strain and apply this to the whole length. Significant numbers omitted "g" from their expression for weight.

Part (b) was a simple dimensional analysis problem, perhaps not expected by many on the Materials paper. Many tried to relate E to (f, EI, l and M_o) rather than f to (EI, l and M_o). More worrying though were: an inability to find the dimensions of E or EI; treating force "F" as a dimension (expressing mass as FT^2/L); and turning "m" (metres) directly into dimension "M" (mass).

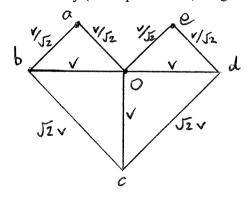
19

7. (a) Yield stress is the load per unit area when the limit of elasticity is reached, usually measured under uniaxial loading in a tensile test. Hardness is the load (either in kg or N) applied to an indenter pressed into a flat surface, divided by the projected area of the indentation made. Ductility is the total plastic strain to failure in a tensile test after fracture.

Yield stress and hardness do not depend on specimen dimensions. Ductility includes both the uniform straining prior to necking in a tensile test, and the localised extension in the necked region – hence its value depends on the length and cross-section area of the test piece (i.e. not a material property).



Velocity (or displacement) diagram:



NTERFACE	Length	RELATIVE	Livi
	Li	VELOCITY	
0A	L/J2	V: V/52	LV/2
AB	4/52	V/52	Lv/2
BC	L/52	J2 V	LV
CD	L/52	JE V	LV
DE	4/52	V/52	LV/2
0E	L/52	V/52	LV/2
•	L	V	LV
OB	L	V	LV
00	-		
		$\leq L_i$	$v_i = 6Lv$

External work rate = F vInternal work rate = 6 k L vHence $F = 6 k L = 3 \sigma_y L$

Hardness = F/L (as unit depth) = $3\sigma_y$

- (c) For all hardening mechanisms, the contribution to strengthening is of the order Gb/l, where G is the shear modulus, b is the Burgers vector, and l is the obstacle spacing. The microstructural parameters controlling obstacle spacing are:
- work hardening: dislocation density
- solid solution hardening: concentration of solute
- precipitation hardening: volume fraction and size of precipitates

Examiner's comments

Very unpopular question (attempted by 40% of candidates), below average marks Descriptive parts mostly done well, but the upper bound problem proved too difficult – though some students got full marks. In retrospect it would have been better to have provided the hodograph in outline, and asked for this to be annotated and analysed.

8 (a) Tensile failure: worst defect (in terms of size and orientation to tensile stress) governs failure (when $K = K_{IC}$).

Compressive failure: many cracks propagate stably, growing parallel to the applied stress; final failure by crushing and an unstable shear band forming.

Typically compressive strength is 10-15 times greater than tensile strength.

(b) (i)
$$P_s(V) = exp\left\{-\left(\frac{\sigma}{\sigma_o}\right)^m \left(\frac{V}{V_o}\right)\right\}$$
 as stress uniform; σ_o , V_o , m: constants

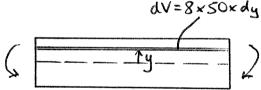
For same probability of failure: $\sigma_1^m \ V_1 = \sigma_2^m \ V_2$

$$\left(\frac{\sigma_t}{500}\right)^m = \left(\frac{V_{cyl}}{V_{sq}}\right) = \frac{30 \times \pi \times 3^2}{50 \times 8 \times 8}$$
 and as m = 8, $\sigma_t = 423$ MPa

(Check: larger volume, thus lower failure stress).

(Note: no need to find σ_o , but if V_o is taken to be the volume of the square section specimen, can solve for σ_o by substituting $P_s = 0.5$ into the Weibull equation, with $V = V_o$. This gives $\sigma_o = 523$ MPa, which is then substituted into the equation with the new volume).

(ii) By inspection:
$$\sigma(y) = \sigma_{max} \frac{y}{4}$$



For same failure probability: $\sigma_t^m V = \int_V [\sigma(y)]^m dV$

$$\sigma_t^m (8 \times 8 \times 50) = \int_0^4 \left[\sigma_{max} \frac{y}{4} \right]^m 8 \times 50 \ dy$$
 (top half only: tensile region)

$$\sigma_t^m \times 8 = \sigma_{max}^m \left[\frac{y^{m+1}}{4^m (m+1)} \right]_0^4 = \sigma_{max}^m \frac{4}{(m+1)}$$

$$\frac{\sigma_{max}}{\sigma_t} = (2(m+1))^{1/m} = 1.435 \quad \text{hence} \quad \sigma_{max} = 607 \text{ MPa}$$

(iii) Tension locates the worst flaw in the whole volume; bending loads only half in tension, with the stress varying from zero to σ_{max} , giving a lower probability of large flaws seeing a high tensile stress (or alternatively, requiring a higher σ_{max} to give the same probability).

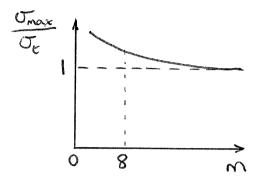


$$\frac{\sigma_{max}}{\sigma_t} = (2(m+1))^{1/m}$$

Hence as m \rightarrow large value, $\frac{\sigma_{max}}{\sigma_t} \rightarrow 1$ (i.e. failure stress is deterministic, like a yield stress).

As m \rightarrow smaller value (e.g. m = 3), $\frac{\sigma_{max}}{\sigma_t} > 1$, i.e. a greater spread in tensile failure stress

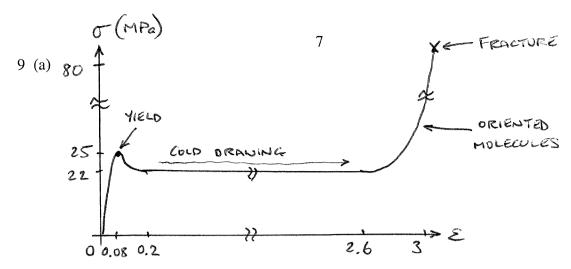
(low m) means that the difference between bending and tensile strength increases.



Examiner's comments

Popular question, below average marks.

This was the first time Weibull analysis had appeared in the IA exam, having moved from IB the previous year. A large proportion did not understand the meaning of the reference stress σ_o , taking this to be the value given (for probability ½, rather than 1/e). Very few recognised they didn't need it anyway, and could use simple scaling of stress and volume. The integration in (b,ii) was done badly – many struggled to relate $\sigma(y)$ to σ_{max} , thinking they needed to know the moment, and there were few complete correct integrals. This probably reflected removal of the (harder) 3-point bending problem from the Examples, replacing it with a rather obscure 1D problem.



- (b) Add fibres (e.g. glass) or particles (glass, silica, rubber) which either promote multiple cracking, or which bridge cracks, both leading to greater energy dissipation as the material fractures.
- (c) (i) Nominal area: projected area of component over which contact is made

 True area: sum of area of microscopic contacts at tips of surface asperities



True contact area: ∝ load, and ∝ 1/Hardness.

At each contact, assume load/area $\approx \sigma_y$, $a_{true} \approx \frac{W}{\sigma_y} \approx \frac{3W}{H}$

(Alternatively, treat each contact like a hardness indentation, so $a_{true} \approx \frac{W}{H}$)

True contact area independent of nominal contact area (for small fractions, typical of metals).

For elastomers, the low modulus allows the surfaces to conform elastically, so true area approaches nominal area and contacts do not yield (so doesn't depend on hardness).

Normal stress = $\frac{W}{a} \approx \sigma_y$; shear stress = $\frac{F}{a} \approx k$ (for dry sticking contact)

As
$$k = \sigma_y / 2$$
, $\frac{F}{W} = \mu \approx \frac{\sigma_y / 2}{\sigma_y} \approx 0.5$

(Alternatively, if normal stress = $\frac{W}{a} \approx$ hardness, $3\sigma_y$, then $\mu \approx 1/6$).

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(d) Aqueous corrosion examples:

(only 2 required)

Prevention:

Rusting of iron due to exposure to water +

oxygen in the atmosphere (e.g. bicycles)

Paint (or other coatings)

Rusting of steel sheet (corrugated roof, car body)

Galvanise with Zn, which corrodes preferentially

Corrosion of steel ships, pipes

Galvanic protection – attach sacrificial anode which is more electronegative (e.g. Mg)

Rusting in central heating system

Use closed system, so oxygen is used up; repair leaks to prevent fresh oxygen supply.

Examiner's comments

Popular question, with above average marks.

Answers to (a,d) on polymers and corrosion were excellent, and the discussion of friction was OK apart from the estimate of μ , which was full of attempts to equate forces and stresses. Part (b) on polymers produced greatest confusion – lots of detailed explanations of how to toughen a polymer, using the techniques applied to strengthen metals (such as work hardening to raise the dislocation density). Many thought it a good idea to raise the temperature – not the most practical solution in a design context.



10. (a) Mass,
$$m \propto L^a (\delta/F)^b \rho^c E^d$$
 with $a = 5/2$

Dimensions M, L, T: $M^1 \propto L^{5/2} (M^{-1}T^2)^b (ML^{-3})^c (ML^{-1}T^{-2})^d$

M:
$$1 = -b + c + d$$
 (1)

L:
$$0 = 5/2 - 3c - d$$
 (2)

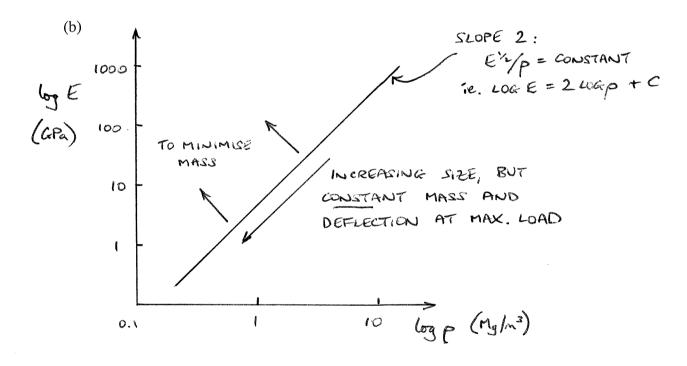
T:
$$0 = 2b - 2d$$
 (3)

Hence: b = d (from 3); c = 1 (from 1); d = -1/2 (from 2); and b = -1/2

Hence: $m \propto L^{5/2} (\delta/F)^{-1/2} \rho E^{-1/2}$

For fixed L, (δ /F): minimum mass \Rightarrow maximise $E^{1/2} / \rho$

Section size is not an independent variable – given (δ/F) and L, the modulus E will fix the section size (via EI). Conversely, size is the free variable which enable the stiffness constraint to be met as the material varies.



(c) To avoid failure while minimising mass, derive a second performance index – either by dimensional analysis (for which the information given in insufficient) or from objective and constraint:

Objective: $m = \rho A L$

Constraint: $\sigma_{max} = \sigma_f$ (failure stress of material), with σ_{max} depending on section size (through I/y_{max}).

Eliminate free variable (size) to find merit index for minimum mass which doesn't fail.

To find whether stiffness or strength is limiting for each material:

- find actual mass required to meet each constraint
- take the heavier of the two for each material, i.e. to just meet the more stringent of the two
- optimum material has the lowest of these heavier masses.

This requires that the design parameters are defined numerically (not just specified as constant), i.e. length, load and allowable deflection. Also need the bending mode to give the numerical constants in the bending formulae for deflection and stress (e.g. cantilever, 3-point bending etc).

(Notes: it is meaningless to directly compare the values of the 2 merit indices for a given material, since though each is proportional to mass, it is a different mass in each case – one which provides adequate stiffness, the other which is strong enough.

Another misconception is that the materials can be ranked on the first constraint, and then the maximum stress calculated from the top down until a material is found which is below its failure stress. This procedure does *not* find the lightest – for example, if *all* the materials are strength-limited, the first to come through on the basis of low mass-for-stiffness need not be the lightest in relation to strength.)

Examiner's comments

Moderately popular question (attempted by 70% of candidates), below average marks. Part (a) threw up similar trouble with dimensional analysis as Q.6, though this problem was similar to an Examples question. Simple errors in algebra led many astray, e.g. when gathering terms on dimensions, $(1/T^{-2})^b$ came through as -2b.

In part (b), many candidates had clearly not appreciated that a given merit index line of constant value corresponded to equal mass and equal stiffness, with size varying – which is the whole point of the analysis. Some interesting merit indices such as E^{90}/ρ^{19} emerged, and the student ploughed on doggedly to plot this on a selection chart. Descriptions of how to extend the analysis to include a second constraint were poor – clearly people prefer to just do the sums, rather than to outline the steps involved. Many thought the second constraint set a limit on a new property, rather than the property for each material setting a new requirement on section size (to avoid failure). One character suggested using the selection software, so you could "hand all the decisions over to a computer". It is to be hoped they find another career rather than Engineering.

H.R. Shercliff June 2003