

ENGINEERING TRIPOS PART 1A

2006

Paper 1 MECHANICAL ENGINEERING

SECTION A

①

1

(a) Bernoulli along surface streamline gives :

$$\cancel{p} + \frac{1}{2} \rho v_*^2 + \rho g(h-d) = \cancel{p} + \frac{1}{2} \rho v^2 + \rho g h$$

$$\Rightarrow \frac{1}{2} \rho v_*^2 = \rho g d + \frac{1}{2} \rho v^2$$

$$\Rightarrow \underline{\underline{v_*^2 = 2gd + v^2}}$$

(b) Continuity gives :

$$h v = (h - d) v_* = (h - 2d) v_*$$

$$\Rightarrow v_* = \frac{v}{1 - 2d/h}$$

$$\Rightarrow \frac{v^2}{(1 - 2d/h)^2} = v^2 + 2gd$$

$$\Rightarrow \underline{\underline{\frac{v^2}{2gd} = \left(1 + \frac{v^2}{2gd}\right) \left(1 - \frac{2d}{h}\right)^2}}$$

112 (a) Applying Bernoulli from nozzle exit to fluid leaving the bucket:

$$P + \frac{1}{2}\rho v^2 + \rho g y = \text{constant}$$

$$P = 0 \text{ and } y \approx \text{constant} \Rightarrow v = \text{constant}$$

(b) Applying the momentum equation to control volume shown below.

$$\sum_{\text{out}} \dot{m} \underline{u} - \sum_{\text{in}} \dot{m} \underline{u} = \sum \underline{F}$$

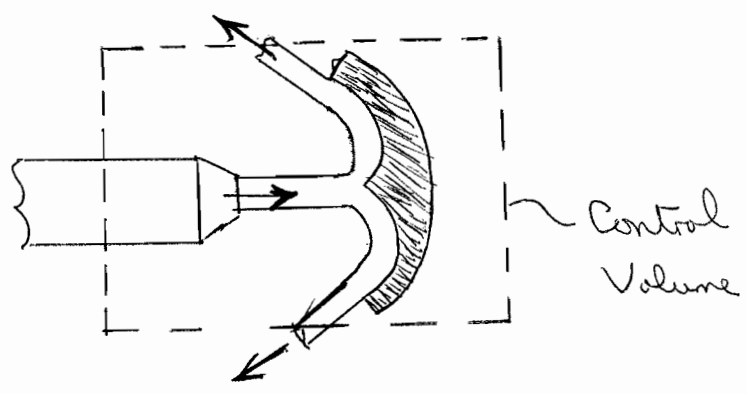
↙ Force on fluid

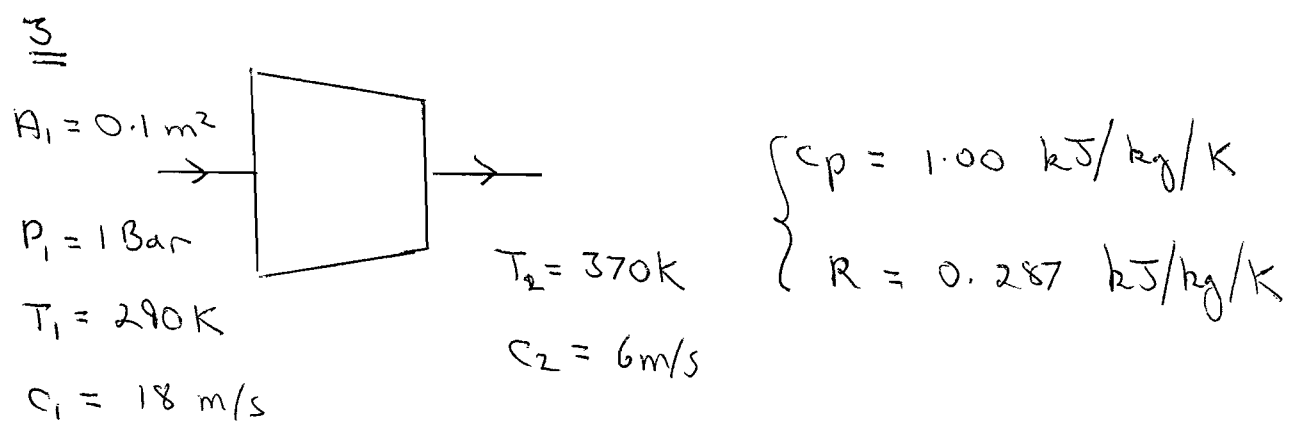
Apply in direction of flow leaving the Nozzle:

$$- \dot{m} v \cos\beta - \dot{m} v = -F$$

↖ force on bucket

$$\underline{F = \dot{m} v (1 + \cos\beta)}$$





(a) $P_1 = \rho_1 R T_1 \Rightarrow \rho_1 = \frac{P_1}{R T_1} = \frac{10^5 \text{ N/m}^2}{287 \text{ J/kg/K} \times 290 \text{ K}} = \underline{\underline{1.201 \text{ kg/m}^3}}$

$\dot{m} = \rho_1 A_1 c_1 = \underline{\underline{2.163 \text{ kg/s}}}$

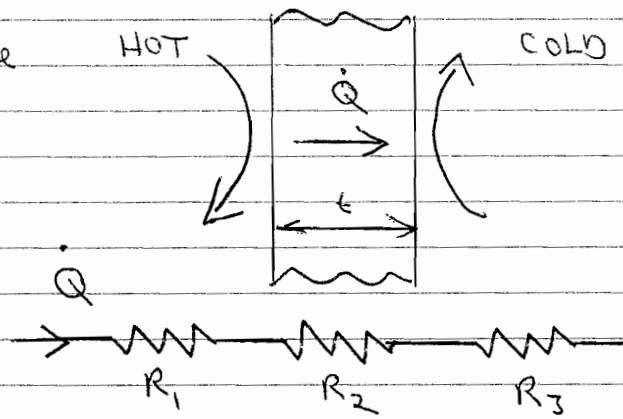
(b) $\dot{W} = -\dot{m} \left((h_2 - h_1) + \frac{1}{2}(c_2^2 - c_1^2) \right)$ (S.F.E.E.)

$= -\dot{m} \left[c_p (T_2 - T_1) + \frac{1}{2}(c_2^2 - c_1^2) \right]$
 $= -2.163 \left[10^3 \times 80 + \frac{1}{2}(18^2 - 6^2) \right]$
 $= -2163 \left[80 + 0.144 \right]$
 $= \underline{\underline{-172.7 \times 10^3 \text{ Watts}}}$

4

4 (a) Calculate thermal resistance

$$\begin{cases} \dot{Q} = hA \Delta T \\ \dot{Q} = -\lambda A \frac{\partial T}{\partial x} \end{cases}$$



$$\Rightarrow \begin{cases} R_1 = \frac{1}{hA} & R_2 = \frac{t}{\lambda A} \\ R_3 = \frac{1}{hA} \end{cases}$$

$$\text{Total resistance : } \Sigma R = \frac{1}{A} \left(\frac{2}{h} + \frac{t}{\lambda} \right)$$

$$\Rightarrow \dot{Q} = \frac{T_f - T_a}{\Sigma R} = \frac{T_f - T_a}{\frac{1}{A} \left(\frac{2}{h} + \frac{t}{\lambda} \right)}$$

$$\Rightarrow \underline{\underline{q = \frac{\dot{Q}}{A} = \frac{T_f - T_a}{\frac{2}{h} + \frac{t}{\lambda}}}}$$

15 (a)

$$W = \int F dx = \int PA dx = \int P dV$$

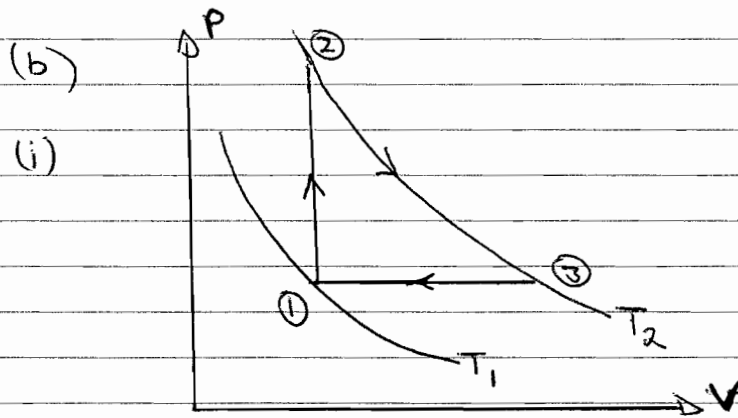
$$PV = nRT = \text{const} \quad W = \int_{V_a}^{V_b} \frac{nRT}{V} dV = nRT \ln \frac{V_b}{V_a}$$

$$= P_a V_a \ln \frac{V_b}{V_a}$$

Ideal gas $\Rightarrow U = U(T)$

T constant $\Rightarrow U = \text{constant}$

1st Law: $Q - W = \Delta U \Rightarrow Q = W = P_a V_a \ln \frac{V_b}{V_a}$
 (Heat into gas)



1 \rightarrow 2 : $PV = nRT, V = \text{const} \Rightarrow \frac{T_2}{T_1} = \frac{P_2}{P_1} = r$

3 \rightarrow 1 : $PV = nRT, P = \text{const} \Rightarrow \frac{V_3}{V_1} = \frac{T_2}{T_1} = r$

(ii) 1 \rightarrow 2 : $V = \text{constant} \Rightarrow W = 0 \Rightarrow Q = \Delta U.$

$$\Rightarrow Q = mc_v (T_2 - T_1)$$

$$\Rightarrow Q = mc_v T_1 (r - 1)$$

2 \rightarrow 3 : $T = \text{constant} \Rightarrow U = \text{constant} \Rightarrow Q = W$

$$\Rightarrow Q = nRT_2 \ln \frac{V_3}{V_2}$$

(from (a))

$$\Rightarrow Q = nRT_1 r \ln r$$

3 \rightarrow 1 : $Q = W + \Delta U = -P_1 (V_3 - V_1) - mc_v (T_2 - T_1)$

$$= -P_1 V_1 (r - 1) - mc_v T_1 (r - 1)$$

(6)

$$\Rightarrow Q_{31} = -mRT_1(r-1) - mc_vT_1(r-1)$$

$$= \underline{\underline{-m(R+c_v)T_1(r-1)}}$$

$$(iii) \quad \eta = \frac{\Sigma W}{Q_{in}} = \frac{\Sigma Q}{Q_{in}}$$

$$\Sigma Q = mT_1 [c_v(r-1) + Rr \ln r - (R+c_v)(r-1)]$$

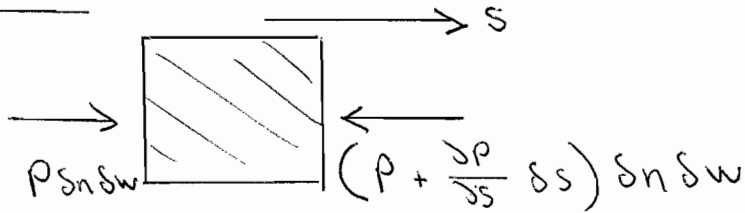
$$= mRT_1 [r \ln r - (r-1)]$$

$$Q_{in} = mT_1 [c_v(r-1) + Rr \ln r]$$

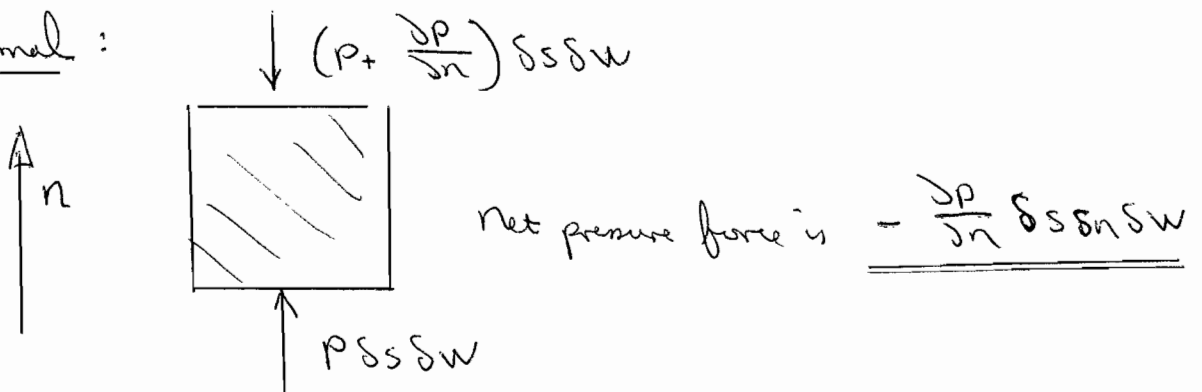
$$\Rightarrow \eta = \frac{R(r \ln r - (r-1))}{c_v(r-1) + Rr \ln r}$$

$$\Rightarrow \eta = \underline{\underline{\frac{r \ln r - (r-1)}{r \ln r + (r-1)c_v/R}}}$$

6 (a) (i)

Streamwise:

Net pressure force is $-\frac{\partial P}{\partial s} \delta s \delta n \delta w$

Normal:

Net pressure force is $-\frac{\partial P}{\partial n} \delta s \delta n \delta w$

(a) (ii) Newton II:

$$\parallel \text{ direction: } \rho (\delta n \delta s \delta w) v \frac{\partial v}{\partial s} = F_{\parallel} = -\frac{\partial P}{\partial s} \delta s \delta n \delta w$$

$$\Rightarrow \underline{\underline{\rho v \frac{\partial v}{\partial s} = -\frac{\partial P}{\partial s}}}$$

$$\perp^{\text{th}} \text{ direction: } \rho (\delta n \delta s \delta w) \left(-\frac{v^2}{R}\right) = -\frac{\partial P}{\partial n} \delta s \delta n \delta w$$

$$\Rightarrow \underline{\underline{\rho \frac{v^2}{R} = \frac{\partial P}{\partial n}}}$$

(a) (iii)

$$\frac{\partial P}{\partial s} + \rho v \frac{\partial v}{\partial s} = 0 \Rightarrow \frac{\partial}{\partial s} \left(P + \frac{1}{2} \rho v^2 \right) = 0$$

Integrate: $P + \frac{1}{2} \rho v^2 = \text{const. along } s\text{-line}$

(b) (i) { 4 variables $h-h_0, g, \omega, r$
2 dimensions, length, time

Π theorem tells us 2 dimensionless groups.

By inspection they are, $h-h_0/r$ and $\omega^2 r/g$

Thus $\frac{h-h_0}{r} = f\left(\frac{\omega^2 r}{g}\right)$

(ii) $\frac{\partial p}{\partial r} = \rho \frac{v^2}{R} \Rightarrow \frac{\partial p}{\partial r} = \rho \frac{v^2}{r} = \rho \omega^2 r$

Integrate $p = p_0 + \frac{1}{2} \rho \omega^2 r^2$

(iii) No vertical acceleration $\Rightarrow p(z)$ is hydrostatic.

This pressure on base is $p = \rho g h$.

$\Rightarrow \rho g h = \rho g h_0 + \frac{1}{2} \rho \omega^2 r^2$

$\Rightarrow \underline{\underline{h - h_0 = \frac{\omega^2 r^2}{2g}}}$

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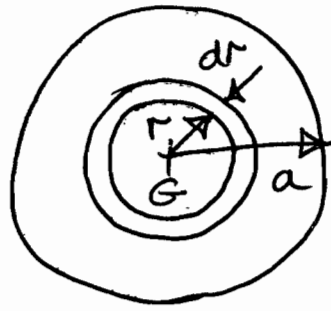
PAPER 1 MECHANICAL ENGINEERING

SECTION B MECHANICS

SOLUTIONS

PREPARED BY D J COLE 28-6-06

7 a)



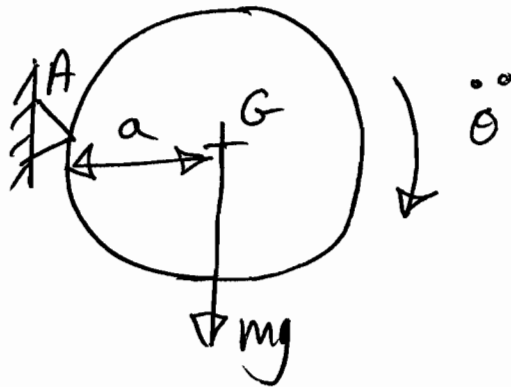
mass per unit area $\rho = \frac{m}{\pi a^2}$

$$I_G = \int_0^a 2\pi r \cdot r^2 \cdot \rho \cdot dr$$

$$= \frac{2\pi m}{\pi a^2} \left[\frac{r^4}{4} \right]_0^a$$

$$\underline{\underline{I_G = \frac{ma^2}{2}}}$$

b)



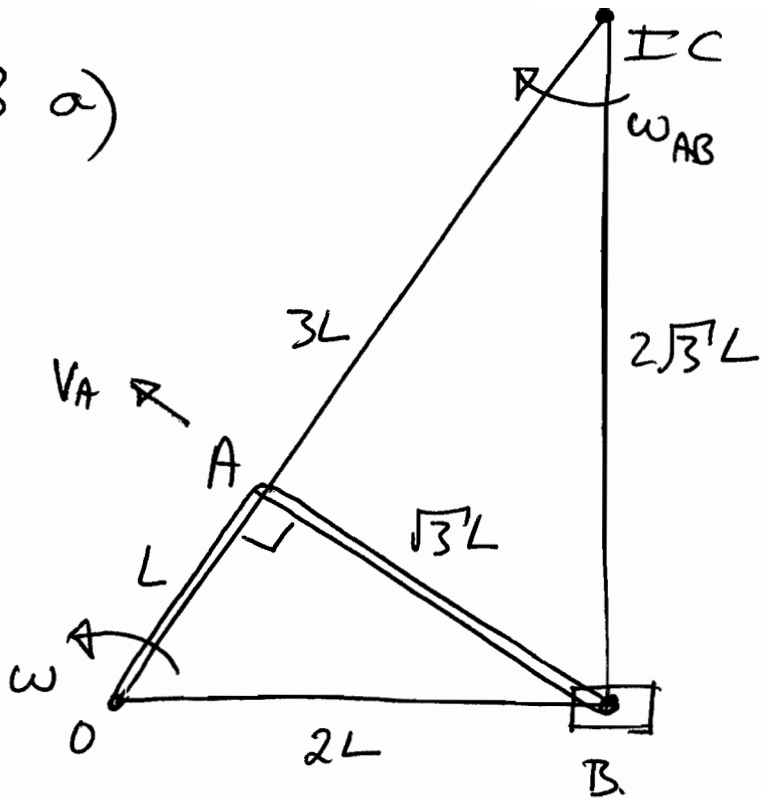
parallel axes $I_A = I_G + ma^2 = \frac{3}{2} ma^2$

moments about A $T = I_A \ddot{\theta}$

$$mga = \frac{3}{2} ma^2 \ddot{\theta}$$

$$\underline{\underline{\ddot{\theta} = \frac{2}{3} \frac{g}{a}}}$$

8 a)



By similar triangles $IC.A = 3L$

hence
$$\omega_{AB} = \frac{V_A}{IC.A} = \frac{\omega L}{3L} = \underline{\underline{\frac{\omega}{3}}}$$

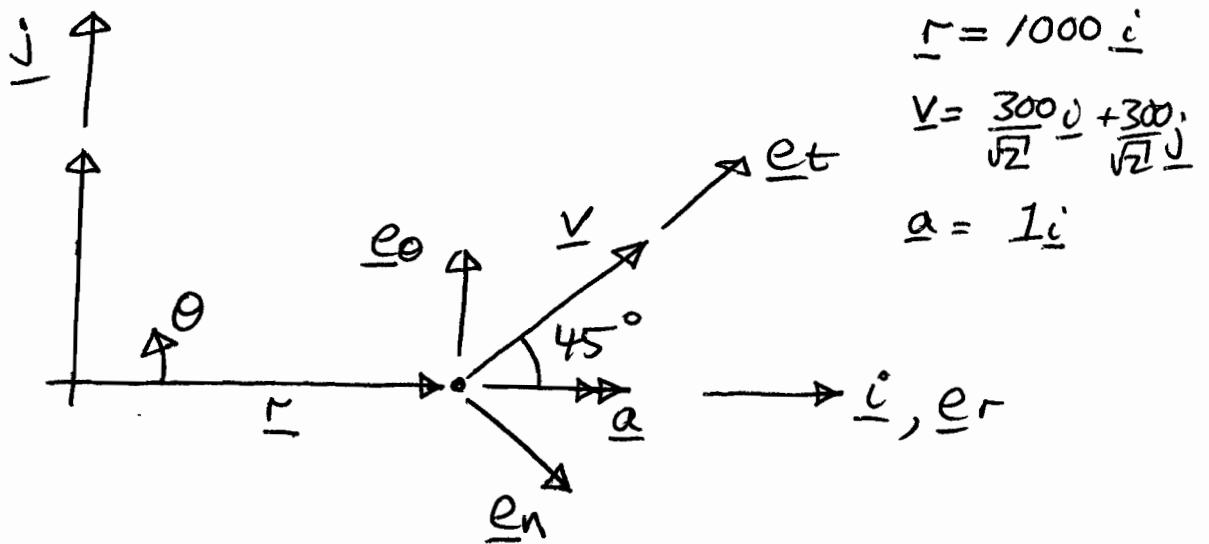
b)

$$T \cdot \omega = \left(\omega + \frac{\omega}{3} \right) Q$$

$$\underline{\underline{T = \frac{4}{3} Q}}$$

angular velocity between OA and AB

9



a)
$$\underline{v} = 300 \underline{e}_t \text{ m/s where } \underline{e}_t = \frac{\underline{i} + \underline{j}}{\sqrt{2}}$$

$$\underline{a} = \frac{1}{\sqrt{2}} \underline{e}_t + \frac{1}{\sqrt{2}} \underline{e}_n \text{ m/s}^2$$

b)
$$\underline{a} = \dot{s} \underline{e}_t + \frac{\dot{s}^2}{\rho} \underline{e}_n$$

$$\therefore \rho = \sqrt{2} \dot{s}^2 = \sqrt{2} 300^2 = \underline{\underline{90\sqrt{2} \text{ km}}}$$

c)
$$\underline{v} = \dot{r} \underline{e}_r + r \dot{\theta} \underline{e}_\theta$$

$$\underline{v} = \frac{300}{\sqrt{2}} \underline{e}_r + \frac{300}{\sqrt{2}} \underline{e}_\theta \text{ m/s}$$

$$\underline{a} = 1 \cdot \underline{e}_r + 0 \cdot \underline{e}_\theta \text{ m/s}^2$$

$$d) \quad \underline{a} = (\ddot{r} - r\dot{\theta}^2) \underline{e}_r + (2\dot{r}\dot{\theta} + r\ddot{\theta}) \underline{e}_\theta$$

In the \underline{e}_r direction

$$\ddot{r} - r\dot{\theta}^2 = 1$$

from (c) $r\dot{\theta} = \frac{300}{\sqrt{2}}$

$$\therefore \dot{\theta} = \frac{300}{\sqrt{2} \cdot 1000} = \frac{0.3}{\sqrt{2}}$$

$$\therefore \ddot{r} = 1000 \left(\frac{0.3}{\sqrt{2}} \right)^2 + 1 = 1 + \frac{90}{2} = \underline{\underline{46 \text{ m/s}^2}}$$

In the \underline{e}_θ direction

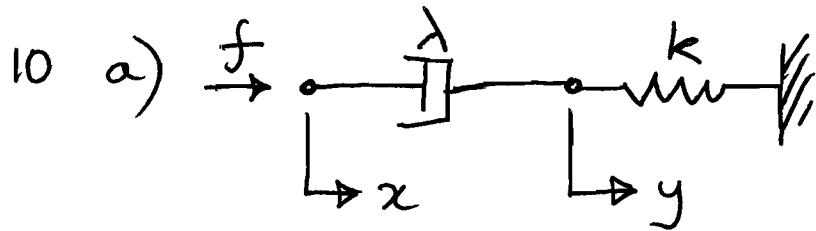
$$2\dot{r}\dot{\theta} + r\ddot{\theta} = 0$$

$$\ddot{\theta} = -\frac{2\dot{r}\dot{\theta}}{r}$$

$$= -2 \cdot \frac{300}{\sqrt{2}} \cdot \frac{0.3}{\sqrt{2}} \cdot \frac{1}{1000}$$

$$\ddot{\theta} = \underline{\underline{-0.09 \text{ rad/s}^2}}$$

i.e. 0.09 rad/s^2 in clockwise direction.



force in spring
= force in damper
= f

spring $f = ky$, $\dot{f} = k\dot{y}$, $\dot{y} = \frac{\dot{f}}{k}$

damper $f = (\dot{x} - \dot{y})\lambda$, eliminate \dot{y} : $f = \dot{x}\lambda - \dot{f}\frac{\lambda}{k}$

hence $\dot{x}k = \dot{f} + f\frac{k}{\lambda}$

b) unit step in $\dot{x} \rightarrow \dot{x} = 1 \quad t > 0$

$$\dot{f} + f\frac{k}{\lambda} = k$$

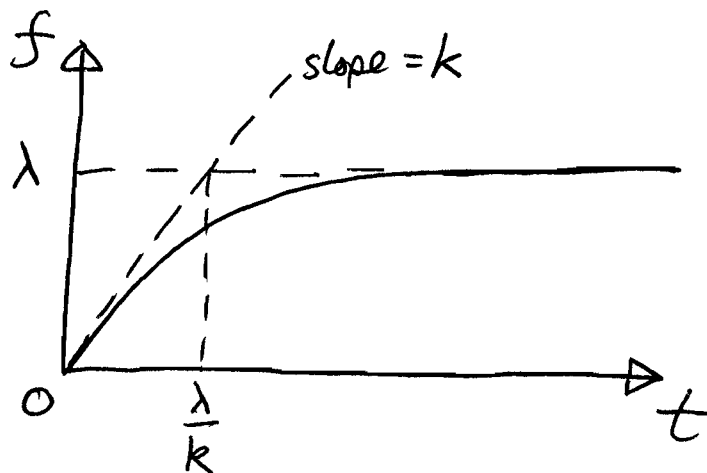
C.F. $f = Ae^{-\frac{k}{\lambda}t}$

P.I. $f = \lambda$

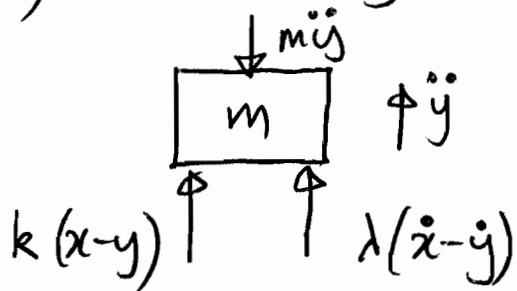
Gen. soln. $f = Ae^{-\frac{k}{\lambda}t} + \lambda$

but $f = 0$ at $t = 0 \therefore A = -\lambda$.

so $f = \lambda(1 - e^{-\frac{k}{\lambda}t})$



11 a) free body diagram

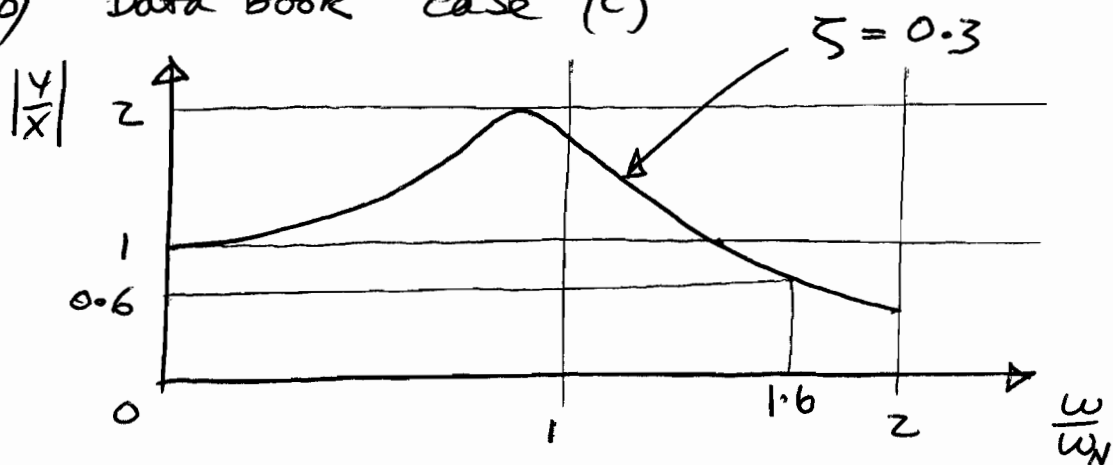


Newton's 2nd Law:

$$m\ddot{y} = k(x-y) + (\dot{x}-\dot{y})$$

$$\underline{\underline{m\ddot{y} + \lambda\dot{y} + ky = \lambda\dot{x} + kx}}$$

b) Data book case (c)

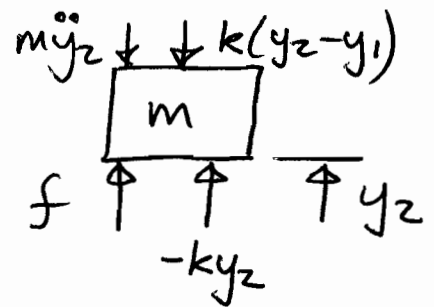
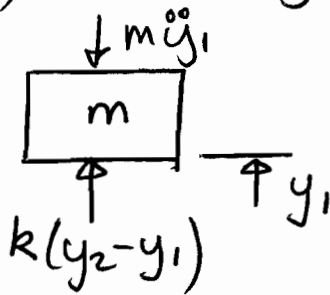


rearrange $\left| \frac{Y}{X} \right|_{\max} = 2$, so $\zeta = 0.3 = \frac{\lambda}{2\sqrt{km}}$

$$\therefore \lambda = \zeta 2\sqrt{km} = 0.3 \cdot 2\sqrt{12 \cdot 10^3 \cdot 10^1}$$

$$\underline{\underline{\lambda = 207.9 \text{ Ns/m}}}$$

12 a) Free body diagrams and Newton's 2nd Law:



$$m\ddot{y}_1 = k(y_2 - y_1)$$

$$m\ddot{y}_2 = f - ky_2 - k(y_2 - y_1)$$

In matrix form:

$$\underline{\begin{bmatrix} m & 0 \\ 0 & m \end{bmatrix} \begin{Bmatrix} \ddot{y}_1 \\ \ddot{y}_2 \end{Bmatrix} + \begin{bmatrix} k & -k \\ -k & 2k \end{bmatrix} \begin{Bmatrix} y_1 \\ y_2 \end{Bmatrix} = \begin{Bmatrix} 0 \\ f \end{Bmatrix}} \quad \text{--- (1)}$$

$$\begin{aligned} \text{b) } y_1 &= Y_1 e^{i\omega t} & \Rightarrow & \ddot{y}_1 = -\omega^2 Y_1 e^{i\omega t} \\ y_2 &= Y_2 e^{i\omega t} & \Rightarrow & \ddot{y}_2 = -\omega^2 Y_2 e^{i\omega t} \end{aligned}$$

hence

$$\left(-\omega^2 \begin{bmatrix} m & 0 \\ 0 & m \end{bmatrix} + \begin{bmatrix} k & -k \\ -k & 2k \end{bmatrix} \right) \begin{Bmatrix} Y_1 \\ Y_2 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$$

non-trivial solution when $\begin{vmatrix} k - m\omega^2 & -k \\ -k & 2k - m\omega^2 \end{vmatrix} = 0$

$$(k - m\omega^2)(2k - m\omega^2) - k^2 = 0$$

the solutions of which are the natural frequencies squared ω_1^2 and ω_2^2 .

$$\omega^4 m^2 - \omega^2 3km + k^2 = 0$$

$$\omega^2 = \frac{3km \pm \sqrt{9k^2 m^2 - 4m^2 k^2}}{2m^2}$$

$$\omega^2 = \frac{3 \pm \sqrt{5}}{2} \frac{k}{m}$$

$$\omega_1^2 = \frac{3 - \sqrt{5}}{2} \frac{k}{m}$$

$$\omega_2^2 = \frac{3 + \sqrt{5}}{2} \frac{k}{m}$$

$$c) \quad \begin{aligned} y_1 &= Y_1 e^{i\omega t} \Rightarrow \ddot{y}_1 = -\omega^2 Y_1 e^{i\omega t} \\ y_2 &= Y_2 e^{i\omega t} \Rightarrow \ddot{y}_2 = -\omega^2 Y_2 e^{i\omega t} \\ f &= F e^{i\omega t} \end{aligned}$$

putting these into (1) and rearranging gives

$$\left(-\omega^2 \begin{bmatrix} m & 0 \\ 0 & m \end{bmatrix} + \begin{bmatrix} k & -k \\ -k & 2k \end{bmatrix} \right) \begin{Bmatrix} Y_1 \\ Y_2 \end{Bmatrix} = \begin{Bmatrix} 0 \\ F \end{Bmatrix}$$

$$\begin{bmatrix} k - m\omega^2 & -k \\ -k & 2k - m\omega^2 \end{bmatrix} \begin{Bmatrix} Y_1 \\ Y_2 \end{Bmatrix} = \begin{Bmatrix} 0 \\ F \end{Bmatrix}$$

premultiply both sides by inverse of matrix:

$$\begin{Bmatrix} Y_1 \\ Y_2 \end{Bmatrix} = \frac{1}{(k - m\omega^2)(2k - m\omega^2) - k^2} \begin{bmatrix} 2k - m\omega^2 & k \\ k & k - m\omega^2 \end{bmatrix} \begin{Bmatrix} 0 \\ F \end{Bmatrix}$$

$$\text{hence } \frac{Y_2}{F} = \frac{k - m\omega^2}{(k - m\omega^2)(2k - m\omega^2) - k^2}$$

$$\text{and from (b)} \quad \frac{Y_2}{F} = \frac{k - m\omega^2}{m^2(\omega^2 - \omega_1^2)(\omega^2 - \omega_2^2)}$$

