# ENGINEERING TRIPOS PART IB

Friday 7 June 1996

9 to 11

Paper 7

# MATHEMATICAL METHODS

Answer not more than four questions.

Answer at least one question from each section.

Answers to questions in each section should be tied together and handed in separately.

## SECTION A

Answer at least one question from this section.

A machined metal part has a base which is bounded by the positive x-axis, the circle  $(x-a)^2 + y^2 = a^2$  and the line y = x as shown in Fig. 1. The height, z, is given by xy.

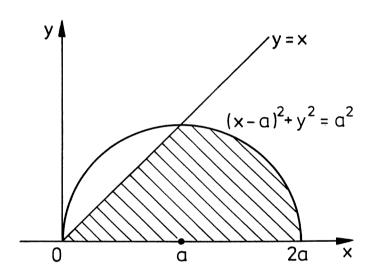


Fig.1

(i) Show, by using the 2D cartesian to polar transformation, that the volume, V, can be evaluated as a double integral of the form

$$V = \iint_R f(r,\theta) dr d\theta$$

(ii) Find the region of integration and evaluate the integral.

- 2 (a) What are meant by solenoidal, irrotational and conservative vector fields?
  - (b) A vector field is defined by

$$v = u + \omega \times r$$

where  $\mathbf{u}$  and  $\boldsymbol{\omega}$  are constant vectors and  $\mathbf{r}$  is the position vector  $x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$ . Show that  $\nabla \times \mathbf{v} = 2\boldsymbol{\omega}$  and  $\nabla \cdot \mathbf{v} = 0$ .

- (c) A vector force field **p** has spherical symmetry and a scalar potential  $\phi(x,y,z) = \frac{k}{r}$ , where  $r = |\mathbf{r}| = \sqrt{x^2 + y^2 + z^2}$ .
  - (i) Find the force **p** at position **r**.
  - (ii) Find the curl and divergence of the vector force field and show that the scalar potential satisfies  $\nabla^2 \phi = 0$  for r > 0.
  - (iii) What work is done on a particle in moving it from position (5,0,0) to (0,0,6) in a straight line?

3 (a) A curve C is the boundary of a flat, closed region S in the xy-plane. Using Stokes' Theorem or otherwise, show that if P and Q are functions of x and y only, then

$$\iint_{S} \left[ \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right] dx dy = \oint_{C} P dx + Q dy$$

(b) Use the result derived in part (a) to show that the area of S is given by

$$\frac{1}{2} \oint_C x dy - y dx = \oint_C x dy = -\oint_C y dx$$

and hence find the area of the ellipse parameterised by  $x = a \cos \theta$ ,  $y = b \sin \theta$ .

### SECTION B

Answer at least one question from this section.

4 (a) The partial differential equation  $\frac{\partial u}{\partial t} + \frac{\partial u}{\partial x} = 0$  can be integrated numerically by the Lax-Wendroff finite-difference scheme:

$$\frac{u_i^{n+1} - u_i^n}{\Delta t} + \frac{u_{i+1}^n - u_{i-1}^n}{2\Delta x} = \frac{\Delta t}{2} \left[ \frac{u_{i+1}^n - 2u_i^n + u_{i-1}^n}{(\Delta x)^2} \right]$$

where the discrete value of the solution u(x,t) at time  $t = n\Delta t$  and position  $x = i\Delta x$  is represented by  $u_i^n = u(i\Delta x, n\Delta t)$ .

Show that the terms on the left hand-side are finite difference approximations for  $\frac{\partial u}{\partial t}$  and  $\frac{\partial u}{\partial x}$  which are first order accurate in time increment  $\Delta t$  and second order accurate in space increment  $\Delta x$  respectively.

(b) Show that the finite difference expression

$$\frac{u_{i+1}^n - 2u_i^n + u_{i-1}^n}{(\Delta x)^2}$$

is an approximation to the spatial derivative  $\frac{\partial^2 u}{\partial x^2}$  and find the order of its accuracy.

By showing that the general solution u(x,t) to  $\frac{\partial u}{\partial t} + \frac{\partial u}{\partial x} = 0$  also satisfies

$$\frac{\partial^2 u}{\partial t^2} = \frac{\partial^2 u}{\partial x^2}$$

show how the Lax-Wendroff scheme achieves second order accuracy in both space and time.

5 (a) The straight line y = a + bx is to be fitted through a discrete set of data points  $(x_1, y_1) \dots (x_n, y_n)$  where n > 2. Show that the values of a and b which minimize the sum of the squares of the distances (measured in the y-direction) of the data points to the straight line satisfy the following equations:

$$an + b \sum_{i=1}^{n} x_i = \sum_{i=1}^{n} y_i$$

$$a \sum_{i=1}^{n} x_i + b \sum_{i=1}^{n} x_i^2 = \sum_{i=1}^{n} x_i y_i$$

When might it be appropriate to minimize the errors measured in the x-direction instead?

(b) An experiment is carried out to determine the relationship between current I and corresponding voltage V for a semiconductor diode. The relationship between I and V is expected to be of the form  $I = I_0 \exp(V/V_S)$ .

The table below gives the values of  $\ln I$  measured for different voltages V.

- (i) Show that a linear relationship is expected between  $\ln I$  and V.
- (ii) One of the measurements was incorrectly recorded. Plot the data to find the incorrect measurement. Assuming that any measurement error occurs in the measurement of  $\ln I$  estimate the parameters  $I_0$  and  $V_S$  by the method of least squares using the 4 valid measurements.
- (iii) The measurement error in the V = 0.9 reading is known to have an error distribution with variance  $\sigma^2$ . The other measurements have error distributions with variance  $2\sigma^2$ . How would you modify the method of least squares to exploit this information?

## SECTION C

Answer at least one question from this section.

- 6 (a) A signal x(t) has Fourier transform  $X(\omega)$ . Show that the Fourier transform of the signal  $x(t)e^{j\omega_0t}$  is  $X(\omega-\omega_0)$ .
  - (b) A band limited signal x(t) has spectrum  $X(\omega)$ , where

$$X(\omega) = k$$
  $-B \le \omega \le B$   
 $X(\omega) = 0$  otherwise.

The signal, x(t), is modulated by being multiplied by a periodic waveform s(t) with period  $T = 2\pi/\omega_0$ , so that

$$y(t) = x(t)s(t).$$

Find and sketch the spectrum of y(t) for the following periodic signals s(t):

- (i)  $s(t) = \cos \omega_0 t$ ;
- (ii)  $s(t) = \frac{1}{T} \sum_{n=-\infty}^{\infty} \operatorname{sinc}\left(\frac{n\omega_0 \tau}{2}\right) e^{jn\omega_0 t}$  where  $\operatorname{sinc}(x)$  is defined as  $\frac{\sin x}{x}$ .

What happens to the spectrum of y(t) in the limit when  $\tau \to 0$ ? What happens when  $\tau \to T$ ?

- 7 (a) An analogue signal is to be spectrum analysed. It is fed through an antialiasing filter, then sampled at 20kHz and the DFT of 1024 samples computed. What should be the highest frequency present after the anti-aliasing filter? Determine the frequency spacing of the spectral samples.
- (b) A sampled signal  $x_s(t) = \sum_{-\infty}^{\infty} x(t)\delta(t nT)$  is passed through a filter with impulse response h(t) shown in Fig. 2.

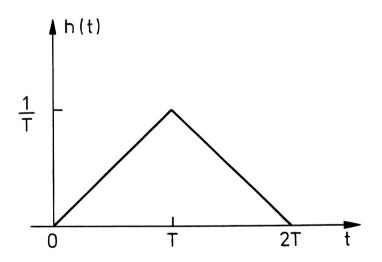


Fig.2

- (i) Sketch the output signal y(t) and give a practical use for this filter.
- (ii) Find the frequency response  $|H(\omega)|$  of the filter. Compare this response to the frequency response of the ideal filter required to recover the original signal x(t) from its samples.

- 8 (a) What is meant by the moment generating function of a random variable? How is it used in the theory of probability?
  - (b) If X and Y are independent random variables with Normal distributions

$$X \sim N(\mu_1, \sigma_1)$$
$$Y \sim N(\mu_2, \sigma_2)$$

show that the random variable Z=X-Y has a probability density function which is also Normal with distribution  $N\left(\mu_1-\mu_2,\sqrt{\sigma_1^2+\sigma_2^2}\right)$ .

(c) A manufactured product is sold in cans. The cans have a weight which is normally distributed with mean 200g and standard deviation 9g. The filling machine is set to give a total weight (can and contents) with mean W and standard deviation 12g.

What should be the least value of W to ensure that less than 0.25% of the filled cans have contents weighing less than 1000g?

