

ENGINEERING TRIPOS PART IB 1997

PAPER 7 MATHEMATICAL METHODS

ANSWERS AND HINTS

1. $a = 3, \quad b = 3/2, \quad$ or *vice versa*, $\quad \phi = \sin(x + 3y).$
2. Identities required are $\nabla \times (\mathbf{u}_1 \times \mathbf{u}_2), \quad \nabla \times (\phi \mathbf{u}).$
 Also note $\nabla r^n = nr^{n-1} \nabla r = nr^{n-2} \mathbf{r}$
 $\nabla(fg) = f \nabla g + g \nabla f$ is useful for last part.
3. (ii) Note that, if $\mathbf{a} \cdot \mathbf{b} = \mathbf{a} \cdot \mathbf{c}, \quad \mathbf{b} \neq \mathbf{c}$ in general.
 (iii) Define $\bar{\mathbf{r}}$ rigorously in terms of \mathbf{r} first.
4. $\phi = 8 \ln x + 2$
 Using central differencing for interior points and backward differencing for $d\phi/dx$ at $x = 4$, the numerical solution is $\phi_1 = 2.00, \quad \phi_2 = 7.55, \quad \phi_3 = 10.79, \quad \phi_4 = 13.09$
5. a) $\alpha \Delta t / \Delta x^2 = 1/6$ (Note that $\partial^2 u / \partial t^2 = \alpha \partial^4 u / \partial x^4$).
 b) $A \Delta t / \Delta x < 1$ (Note that disturbance propagates downwind only).
6. For the discrete representation:
 $|F(0)| = 1.0, \quad |F(\pi)| = 0.6533, \quad |F(2\pi)| = 0, \quad |F(3\pi)| = 0.2706, \quad |F(4\pi)| = 0,$
 (Other values are symmetrical).
 (Do not forget to multiply the F_k by the sampling time).
7. For the second part, direct integration is most straightforward, noting that $F(2\pi k/T)$ is not a function of t . For the last part, note that the equation is valid for all ω . Hence, if $F(\omega)$ is sampled at intervals of $\Delta\omega = 2\pi/T$, $F(2\pi k/T)$ can be calculated for all k and $F(\omega)$ reconstructed in its entirety
8. Construct a tree diagram to find the probability that the game ends with n bags and hence that

$$m(t) = \sum_{n=2}^{\infty} \frac{(n-1)}{n!} t^n$$

Then show that this is the same as the given expression.

Finally, mean $(N) = e$, $\quad \text{var}(N) = 3e - e^2.$

PART I B PAPER 7 1997

MATHEMATICAL METHODS

SOLUTIONS BY J.B. Young

1. First application of the chain rule gives:

$$\frac{\partial \phi}{\partial x} = \frac{\partial \phi}{\partial u} \frac{\partial u}{\partial x} + \frac{\partial \phi}{\partial v} \frac{\partial v}{\partial x} = \frac{\partial \phi}{\partial u} + \frac{\partial \phi}{\partial v}$$

$$\frac{\partial \phi}{\partial y} = \frac{\partial \phi}{\partial u} \frac{\partial u}{\partial y} + \frac{\partial \phi}{\partial v} \frac{\partial v}{\partial y} = a \frac{\partial \phi}{\partial u} + b \frac{\partial \phi}{\partial v}$$

Second application gives:

$$\frac{\partial^2 \phi}{\partial x^2} = \left(\frac{\partial}{\partial u} + \frac{\partial}{\partial v} \right) \left(\frac{\partial \phi}{\partial u} + \frac{\partial \phi}{\partial v} \right) = \frac{\partial^2 \phi}{\partial u^2} + 2 \frac{\partial^2 \phi}{\partial u \partial v} + \frac{\partial^2 \phi}{\partial v^2}$$

$$\frac{\partial^2 \phi}{\partial x \partial y} = \left(\frac{\partial}{\partial u} + \frac{\partial}{\partial v} \right) \left(a \frac{\partial \phi}{\partial u} + b \frac{\partial \phi}{\partial v} \right) = a \frac{\partial^2 \phi}{\partial u^2} + (a+b) \frac{\partial^2 \phi}{\partial u \partial v} + b \frac{\partial^2 \phi}{\partial v^2}$$

$$\frac{\partial^2 \phi}{\partial y^2} = \left(a \frac{\partial}{\partial u} + b \frac{\partial}{\partial v} \right) \left(a \frac{\partial \phi}{\partial u} + b \frac{\partial \phi}{\partial v} \right) = a^2 \frac{\partial^2 \phi}{\partial u^2} + 2ab \frac{\partial^2 \phi}{\partial u \partial v} + b^2 \frac{\partial^2 \phi}{\partial v^2}$$

Hence $9 \frac{\partial^2 \phi}{\partial x^2} - 9 \frac{\partial^2 \phi}{\partial x \partial y} + 2 \frac{\partial^2 \phi}{\partial y^2} = 0$ becomes,

$$[9 - 9a + 2a^2] \frac{\partial^2 \phi}{\partial u^2} + [18 - 9(a+b) + 4ab] \frac{\partial^2 \phi}{\partial u \partial v} + [9 - 9b + 2b^2] \frac{\partial^2 \phi}{\partial v^2} = 0$$

This reduces to $\frac{\partial^2 \phi}{\partial u \partial v} = 0$ when:

$$(9 - 9a + 2a^2) = (3-a)(3-2a) = 0 \rightarrow a = 3 \text{ or } \frac{3}{2}$$

$$(9 - 9b + 2b^2) = (3-b)(3-2b) = 0 \rightarrow b = 3 \text{ or } \frac{3}{2}$$

$$[18 - 9(a+b) + 4ab] \neq 0$$

Hence $a=3$, $b=\frac{3}{2}$ or vice versa.

[10]

By inspection, $\phi = f(u)$ and $\phi = g(v)$ both satisfy $\frac{\partial^2 \phi}{\partial u \partial v} = 0$. As the equation is linear, the general solution is

$$\phi = f(u) + g(v) = f(x+3y) + g(x+\frac{3}{2}y)$$

where f and g are arbitrary functions. [3]

To find the particular solution, note that,

$$\phi(x, 0) = f(x) + g(x) = \sin x \quad \dots \dots (i)$$

$$\frac{\partial \phi(x, 0)}{\partial y} = 3f'(x) + \frac{3}{2}g'(x) = 3\cos x \quad \dots \dots (ii)$$

Differentiating (i) gives

$$f'(x) + g'(x) = \cos x$$

Combining with (ii) gives $g'(x) = 0$, $f'(x) = \cos x$.

Hence $f(x) = \sin x$, $g(x) = \text{constant}$.

But $g(x) = 0$ to satisfy (i). Hence the solution is

$$\phi(x, y) = f(x+3y) = \sin(x+3y)$$

[7]

2. Using the vector identity for $\nabla \times (\underline{u}_1 \times \underline{u}_2)$,

$$\begin{aligned}\nabla \times (\underline{a} \times \underline{r}) &= \underline{a} (\nabla \cdot \underline{r}) - \underline{r} (\nabla \cdot \underline{a}) + (\underline{r} \cdot \nabla) \underline{a} - (\underline{a} \cdot \nabla) \underline{r} \\ &= \underline{a} (\nabla \cdot \underline{r}) - (\underline{a} \cdot \nabla) \underline{r} \quad [\underline{a} = \text{constant}]\end{aligned}$$

Now :

$$\nabla \cdot \underline{r} = \frac{\partial}{\partial x}(x) + \frac{\partial}{\partial y}(y) + \frac{\partial}{\partial z}(z) = 3$$

$$\begin{aligned}(\underline{a} \cdot \nabla) \underline{r} &= (a_x \frac{\partial}{\partial x} + a_y \frac{\partial}{\partial y} + a_z \frac{\partial}{\partial z})(x \underline{i} + y \underline{j} + z \underline{k}) \\ &= a_x \underline{i} + a_y \underline{j} + a_z \underline{k} \\ &= \underline{a}\end{aligned}$$

Hence,

$$\nabla \times (\underline{a} \times \underline{r}) = 3\underline{a} - \underline{a} = 2\underline{a} \quad [6]$$

Using the vector identity for $\nabla \times (\phi \underline{u})$,

$$\begin{aligned}\nabla \times [r^n (\underline{a} \times \underline{r})] &= r^n \nabla \times (\underline{a} \times \underline{r}) + \nabla r^n \times (\underline{a} \times \underline{r}) \\ &= 2r^n \underline{a} + \nabla r^n \times (\underline{a} \times \underline{r})\end{aligned}$$

Now :

$$\begin{aligned}\nabla r^n &= \left(\underline{i} \frac{\partial}{\partial x} + \underline{j} \frac{\partial}{\partial y} + \underline{k} \frac{\partial}{\partial z} \right) r^n \quad [r = (x^2 + y^2 + z^2)^{1/2}] \\ &= nr^{n-1} \left(\underline{i} \frac{x}{r} + \underline{j} \frac{y}{r} + \underline{k} \frac{z}{r} \right) \\ &= nr^{n-2} \underline{r}\end{aligned}$$

$$\therefore \nabla \times \underline{F} = 2r^n \underline{a} + nr^{n-2} \underline{r} \times (\underline{a} \times \underline{r})$$

Using the triple vector product formula,

$$\underline{r} \times (\underline{a} \times \underline{r}) = (\underline{r} \cdot \underline{r}) \underline{a} - (\underline{r} \cdot \underline{a}) \underline{r}$$

$$\therefore \nabla_x F = 2r^n \underline{a} + nr^{n-2} [r^2 \underline{a} - (\underline{r} \cdot \underline{a}) \underline{r}]$$

$$\underline{\nabla}_x F = (2+n)r^n \underline{a} - nr^{n-2} (\underline{r} \cdot \underline{a}) \underline{r} \quad [9]$$

Setting $n=-3$, we have

$$- \nabla_x \left(\frac{\underline{a} \times \underline{r}}{r^3} \right) = r^{-3} \underline{a} - 3r^{-5} (\underline{r} \cdot \underline{a}) \underline{r}$$

Now:

$$\nabla \left(\frac{\underline{a} \cdot \underline{r}}{r^3} \right) = \frac{1}{r^3} \nabla(\underline{a} \cdot \underline{r}) + (\underline{a} \cdot \underline{r}) \nabla r^{-3}$$

$$\nabla(\underline{a} \cdot \underline{r}) = \left(\underline{i} \frac{\partial}{\partial x} + \underline{j} \frac{\partial}{\partial y} + \underline{k} \frac{\partial}{\partial z} \right) (xa_x + ya_y + za_z) = \underline{a}$$

$$\nabla r^{-3} = -3r^{-5} \underline{r}$$

$$\therefore \nabla \left(\frac{\underline{a} \cdot \underline{r}}{r^3} \right) = r^{-3} \underline{a} - 3r^{-5} (\underline{r} \cdot \underline{a}) \underline{r}$$

Hence,
$$\nabla \left(\frac{\underline{a} \cdot \underline{r}}{r^3} \right) = - \nabla_x \left(\frac{\underline{a} \times \underline{r}}{r^3} \right)$$

[5]

3. (i) \underline{r} has a scalar potential if $\nabla \times \underline{r} = 0$

$$\nabla \times \underline{r} = \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x & y & z \end{vmatrix} = 0$$

$$\underline{r} = \nabla \phi ; \quad \frac{\partial \phi}{\partial x} = x, \quad \frac{\partial \phi}{\partial y} = y, \quad \frac{\partial \phi}{\partial z} = z$$

$$\rightarrow \phi = \frac{x^2}{2} + \frac{y^2}{2} + \frac{z^2}{2} \rightarrow \phi = \frac{r^2}{2} \quad [5]$$

(ii) Apply Gauss's theorem to the vector field $\phi \underline{e}$:

$$\oiint_S \phi \underline{e} \cdot d\underline{A} = \iiint_V \nabla \cdot (\phi \underline{e}) dV$$

$$\nabla \cdot (\phi \underline{e}) = \phi (\nabla \cdot \underline{e}) + \underline{e} \cdot \nabla \phi = \underline{e} \cdot \nabla \phi \quad (\nabla \cdot \underline{e} = 0)$$

Hence :

$$\oiint_S \underline{e} \cdot (\phi d\underline{A}) = \iiint_V \underline{e} \cdot \nabla \phi dV$$

But \underline{e} is a constant vector so,

$$\underline{e} \cdot \oiint_S \phi d\underline{A} = \underline{e} \cdot \iiint_V \nabla \phi dV$$

But \underline{e} is any unit vector so,

$$\oiint_S \phi d\underline{A} = \iiint_V \nabla \phi dV \quad (\text{Gradient theorem}) \quad [8]$$

(iii) Position vector of centre of mass is defined by

$$\underline{\bar{r}} \iiint_V \rho dV = \iiint_V \underline{r} \rho dV$$

Setting $\underline{r} = \nabla \phi$ with $\phi = \frac{r^2}{2}$ and uniform ρ gives

$$\underline{\bar{r}} \iiint_V dV = \iiint_V \nabla \left(\frac{r^2}{2} \right) dV$$

$$\therefore \underline{\bar{r}} = \frac{1}{V} \oiint_S \frac{r^2}{2} d\underline{A} \quad (\text{from gradient theorem}) \quad [7]$$

$$4. \quad x \frac{d^2 \phi}{dx^2} + \frac{d\phi}{dx} = \frac{d}{dx} \left(x \frac{d\phi}{dx} \right) = 0$$

$$\therefore x \frac{d\phi}{dx} = C_1 \quad ; \quad \phi = C_1 \ln x + C_2$$

Applying the boundary conditions:

$$\left. \begin{aligned} 2 &= C_1 \ln 1 + C_2 \\ 2 &= C_1/4 \end{aligned} \right\} \begin{aligned} C_1 &= 8 \\ C_2 &= 2 \end{aligned} \quad [4]$$

A 2nd order accurate discretization for interior points is,

$$x_i \frac{(\phi_{i+1} - 2\phi_i + \phi_{i-1}))}{\Delta x^2} + \frac{(\phi_{i+1} - \phi_{i-1}))}{2\Delta x} = 0$$

with $\Delta x = 1$,

$$\phi_{i-1}(x_i - 0.5) + \phi_i(-2x_i) + \phi_{i+1}(x_i + 0.5) = 0$$

$$\text{At } x=1, \quad \phi(1) = 2 \quad \rightarrow \quad \phi_1 = 2$$

$$\text{At } x=4, \quad \frac{d\phi(4)}{dx} = 2 \quad \rightarrow \quad \frac{\phi_4 - \phi_3}{\Delta x} = 2$$

Second bc is only 1st order accurate. (This could be improved by fitting a quadratic through points (2,3,4) and calculating the slope at point 4.) [5]

In matrix form the difference equations are:

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 1.5 & -4 & 2.5 & 0 \\ 0 & 2.5 & -6 & 3.5 \\ 0 & 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} \phi_1 \\ \phi_2 \\ \phi_3 \\ \phi_4 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \\ 0 \\ 2 \end{bmatrix}$$

$$\begin{array}{cccc|c}
 1 & 0 & 0 & 0 & 2 \\
 0 & -4 & 2.5 & 0 & -3 \\
 0 & 2.5 & -6 & 3.5 & 0 \\
 0 & 0 & -1 & 1 & 2
 \end{array}
 \Rightarrow
 \begin{array}{cccc|c}
 1 & 0 & 0 & 0 & 2 \\
 0 & -4 & 2.5 & 0 & -3 \\
 0 & 0 & -4.4375 & 3.5 & -1.875 \\
 0 & 0 & -1 & 1 & 2
 \end{array}$$

$$\Rightarrow
 \begin{array}{cccc|c}
 1 & 0 & 0 & 0 & 2 \\
 0 & -4 & 2.5 & 0 & -3 \\
 0 & 0 & -4.4375 & 3.5 & -1.875 \\
 0 & 0 & 0 & 0.21127 & 2.42254
 \end{array}$$

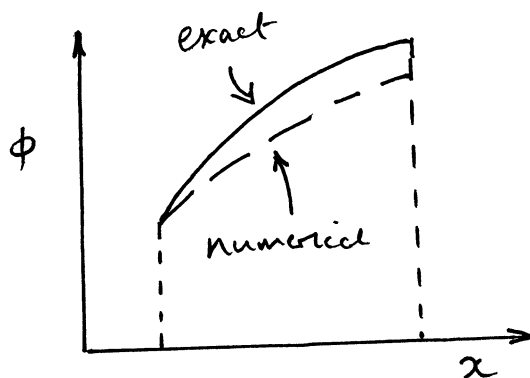
Back substitution gives :

$$\begin{aligned}
 \phi_4 &= 11.467 & -4.4375 \phi_3 + 3.5 \phi_4 &= -1.875 \\
 \phi_3 &= 9.467 & -4 \phi_2 + 2.5 \phi_3 &= -3 \\
 \phi_2 &= 6.667 \\
 \phi_1 &= 2.0
 \end{aligned}$$

[8]

Exact values from solution of differential equation :

$$\begin{aligned}
 \phi_4 &= 13.090 \\
 \phi_3 &= 10.789 \\
 \phi_2 &= 7.545 \\
 \phi_1 &= 2.0
 \end{aligned}$$



1st order discretization of BC at $x=4$ affects solution badly. More points would improve matters.

[3]

$$\begin{aligned}
 5. (a) \quad u_i^{n+1} &= u_i^n + \frac{\partial u}{\partial t} \Delta t + \frac{\partial^2 u}{\partial t^2} \frac{\Delta t^2}{2} + \frac{\partial^3 u}{\partial t^3} \frac{\Delta t^3}{6} + \dots \\
 u_{i+1}^n &= u_i^n + \frac{\partial u}{\partial x} \Delta x + \frac{\partial^2 u}{\partial x^2} \frac{\Delta x^2}{2} + \frac{\partial^3 u}{\partial x^3} \frac{\Delta x^3}{6} + \\
 &\quad \frac{\partial^4 u}{\partial x^4} \frac{\Delta x^4}{24} + \frac{\partial^5 u}{\partial x^5} \frac{\Delta x^5}{120} + \frac{\partial^6 u}{\partial x^6} \frac{\Delta x^6}{720} + \dots \\
 u_{i-1}^n &= u_i^n - \frac{\partial u}{\partial x} \Delta x + \frac{\partial^2 u}{\partial x^2} \frac{\Delta x^2}{2} - \frac{\partial^3 u}{\partial x^3} \frac{\Delta x^3}{6} + \\
 &\quad \frac{\partial^4 u}{\partial x^4} \frac{\Delta x^4}{24} - \frac{\partial^5 u}{\partial x^5} \frac{\Delta x^5}{120} + \frac{\partial^6 u}{\partial x^6} \frac{\Delta x^6}{720} + \dots
 \end{aligned}$$

Substituting into the finite difference approximation:

$$\begin{aligned}
 \frac{\partial u}{\partial t} + \frac{\partial^2 u}{\partial t^2} \frac{\Delta t}{2} + \frac{\partial^3 u}{\partial t^3} \frac{\Delta t^2}{6} + \dots &= \\
 \propto \left[\frac{\partial^2 u}{\partial x^2} + \frac{\partial^4 u}{\partial x^4} \frac{\Delta x^2}{12} + \frac{\partial^6 u}{\partial x^6} \frac{\Delta x^4}{360} + \dots \right]
 \end{aligned}$$

From the differential equation:

$$\frac{\partial^2 u}{\partial t^2} = \alpha^2 \frac{\partial^4 u}{\partial x^4} \quad ; \quad \frac{\partial^3 u}{\partial t^3} = \alpha^3 \frac{\partial^6 u}{\partial x^6}$$

Hence:

$$\begin{aligned}
 \frac{\partial u}{\partial t} &= \alpha \frac{\partial^2 u}{\partial x^2} + \frac{\alpha}{12} \frac{\partial^4 u}{\partial x^4} \left[1 - \frac{6\alpha\Delta t}{\Delta x^2} \right] \Delta x^2 \\
 &\quad + \frac{\alpha}{360} \frac{\partial^6 u}{\partial x^6} \left[1 - \frac{60\alpha^2\Delta t^2}{\Delta x^4} \right] \Delta x^4 + \dots
 \end{aligned}$$

\therefore The truncation error is of order Δx^2 unless Δt is chosen such that $\frac{\alpha\Delta t}{\Delta x^2} = \frac{1}{6}$, when the error is of order Δx^4 .

[10]

(b) The finite difference approximation is rearranged to give,

$$u_i^{n+1} = u_i^n - c(u_i^n - u_{i-1}^n) \quad c = A \frac{\Delta t}{\Delta x}$$

i.e., $u_i^{n+1} = c u_{i-1}^n + (1-c) u_i^n$

	n	$n+1$	$n+2$	$n+3$	$n+4$
$i-1$	0	0	0	0	0
i	ϵ	$(1-c)\epsilon$	$(1-c)^2\epsilon$	$(1-c)^3\epsilon$	$(1-c)^4\epsilon$
$i+1$	0	$c\epsilon$	$2c(1-c)\epsilon$	$3c(1-c)^2\epsilon$	$4c(1-c)^3\epsilon$
$i+2$	0	0	$c^2\epsilon$	$3c^2(1-c)\epsilon$	$6c^2(1-c)^2\epsilon$
$i+3$	0	0	0	$c^3\epsilon$	$4c^3(1-c)\epsilon$
$i+4$	0	0	0	0	$c^4\epsilon$
$i+5$	0	0	0	0	0

Errors will only decay if $c < 1$ and so the stability limit is $c = \frac{A\Delta t}{\Delta x} = 1$.

{ For $c < 1$, accuracy is lost because numerical diffusion causes the solution to "spread" in space. } [10]

$$\begin{aligned}
 6. \quad F(\omega) &= \int_{-\infty}^{\infty} f(t) e^{-j\omega t} dt = \int_0^1 e^{-j\omega t} dt \\
 &= \left. \frac{e^{-j\omega t}}{-j\omega} \right|_0^1 = \frac{e^{-j\omega} - 1}{-j\omega} \\
 &= e^{-j\omega/2} \left(\frac{e^{j\omega/2} - e^{-j\omega/2}}{j\omega} \right) = e^{-j\omega/2} \frac{\text{sinc}(\omega/2)}{(\omega/2)} \\
 &= e^{-j\omega/2} \text{sinc}\left(\frac{\omega}{2}\right) \quad [5]
 \end{aligned}$$

Sampling generates the series :

$$\{f_n\}_{n=0}^7 = \{1, 1, 1, 1, 0, 0, 0, 0\}$$

The DFT is,

$$\begin{aligned}
 F_k &= \sum_{n=0}^7 f_n e^{-jkn2\pi/N} \quad \text{with } N=8 \\
 &= \sum_{n=0}^3 f_n e^{-jkn(\pi/4)} \quad \text{as } f_4 = f_5 = f_6 = f_7 = 0
 \end{aligned}$$

The estimate of the FT is then the sequence

$$\{TF_k\}_{k=0}^7 = \{0.25 F_k\}_{k=0}^7$$

i.e., 8 values representing the FT at $\omega = k\Delta\omega = k\pi$, $k=0 \rightarrow 7$.

$$0.25 F_0 = 0.25 [1 + 1 + 1 + 1] = 1$$

$$0.25 F_1 = 0.25 [1 + e^{-j\pi/4} + e^{-j\pi/2} + e^{-j3\pi/4}] = 0.25 - j0.6036$$

$$0.25 F_2 = 0.25 [1 + e^{-j\pi/2} + e^{-j\pi} + e^{-j3\pi/2}] = 0$$

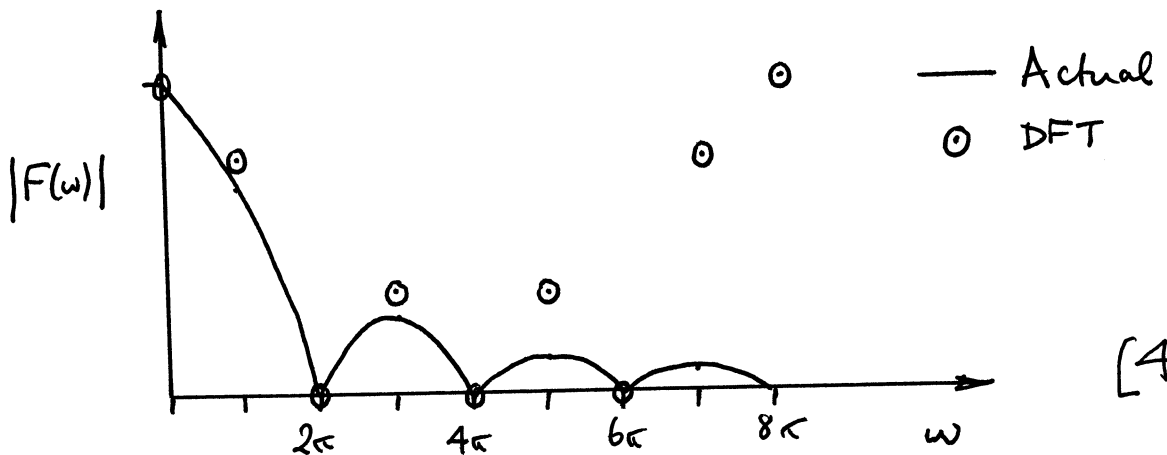
$$0.25 F_3 = 0.25 [1 + e^{-j3\pi/4} + e^{-j3\pi/2} + e^{-j9\pi/4}] = 0.25 - j0.6036$$

$$0.25 F_4 = 0.25 [1 + e^{-j\pi} + e^{-j2\pi} + e^{-j3\pi}] = 0$$

[11]

ω	Actual $ F(\omega) $	Discrete $ F(\omega) $
0	1.0	1.0
π	0.6366	0.6533
2π	0	0
3π	0.2122	0.2706
4π	0	0
5π	0.1273	0.2706
6π	0	0
7π	0.0909	0.6533
8π	0	1.0

} Symmetrical



[4]

7. The Fourier transform of $f(t)$ is

$$F(\omega) = \int_{-T/2}^{T/2} f(t) e^{-j\omega t} dt$$

If $f(t)$ can be represented as a Fourier series, then

$$f(t) = \sum_{k=-\infty}^{\infty} C_k e^{j\frac{2\pi k}{T}t}$$

where the complex coefficients are given by

$$C_k = \frac{1}{T} \int_{-T/2}^{T/2} f(t) e^{-j\frac{2\pi k}{T}t} dt$$

Thus,

$$C_k = \frac{1}{T} F\left(\frac{2\pi k}{T}\right)$$

[5]

Now,

$$f(t) = \sum_{k=-\infty}^{\infty} C_k e^{j\frac{2\pi k}{T}t} = \sum_{k=-\infty}^{\infty} \frac{1}{T} F\left(\frac{2\pi k}{T}\right) e^{j\frac{2\pi k}{T}t}$$

The Fourier transform is thus,

$$F(\omega) = \int_{-T/2}^{T/2} \left\{ \sum_{k=-\infty}^{\infty} \frac{1}{T} F\left(\frac{2\pi k}{T}\right) e^{j\frac{2\pi k}{T}t} \right\} e^{-j\omega t} dt$$

As $F\left(\frac{2\pi k}{T}\right)$ is not a function of t , this may be written

$$F(\omega) = \sum_{k=-\infty}^{\infty} \frac{1}{T} F\left(\frac{2\pi k}{T}\right) \int_{-T/2}^{T/2} e^{-j(\omega - \frac{2\pi k}{T})t} dt$$

$$= \sum_{k=-\infty}^{\infty} \frac{1}{T} F\left(\frac{2\pi k}{T}\right) \frac{e^{-j(\omega - \frac{2\pi k}{T})t}}{-j(\omega - \frac{2\pi k}{T})} \Bigg|_{-T/2}^{T/2}$$

$$F(\omega) = \sum_{k=-\infty}^{\infty} \frac{1}{T} F\left(\frac{2\pi k}{T}\right) \left\{ \frac{e^{j(\omega - \frac{2\pi k}{T})\frac{T}{2}} - e^{-j(\omega - \frac{2\pi k}{T})\frac{T}{2}}}{j(\omega - \frac{2\pi k}{T})} \right\}$$

$$F(\omega) = \sum_{k=-\infty}^{\infty} F\left(\frac{2\pi k}{T}\right) \text{sinc}\left[(\omega - \frac{2\pi k}{T})\left(\frac{T}{2}\right)\right] \quad [12]$$

This equation is valid for all ω . Hence, if $F(\omega)$ is sampled at discrete intervals $\Delta\omega = 2\pi/T$, $F(2\pi k/T)$ can be calculated for all k and so $F(\omega)$ can be reconstructed in its entirety, not just at values of $\omega = 2\pi k/T$. [3]

8. If a discrete random variable N takes integer values n , then $m(t)$ is a moment generating function for N if

$$m(t) = \sum_{\text{relevant } n} p_n t^n$$

where $p_n = \text{probability } (N=n)$. It is useful for generating means, variances and other moments:

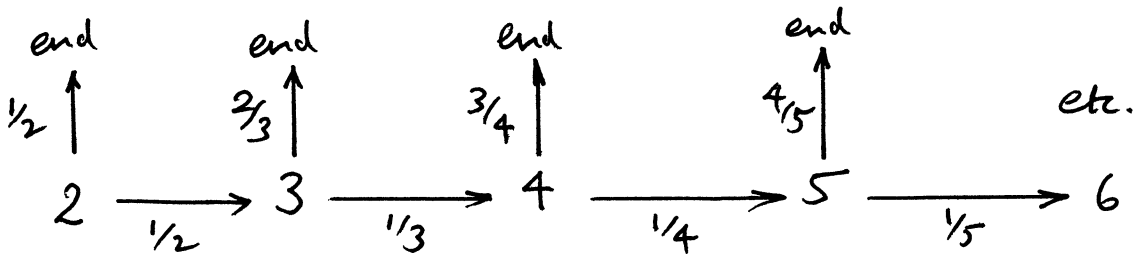
$$m(t) = \sum p_n t^n \rightarrow m(1) = \sum p_n = 1$$

$$m'(t) = \sum n p_n t^{n-1} \rightarrow m'(1) = \sum n p_n = \text{Mean}(N)$$

$$m''(t) = \sum n(n-1) p_n t^{n-2} \rightarrow m''(1) = \sum n^2 p_n - \sum n p_n$$

$$\text{Var}(N) = \sum n^2 p_n - (\sum n p_n)^2 = m''(1) + m'(1) - [m'(1)]^2 \quad [4]$$

etc.



$$P(\text{reaches } 5) = \frac{1}{4} P(\text{reaches } 4) = \frac{1}{4} \cdot \frac{1}{3} \cdot \frac{1}{2}$$

$$P(\text{reaches } n) = \frac{1}{(n-1)!}$$

$$P(\text{ends at } 5) = \frac{4}{5} P(\text{reaches } 5)$$

$$P(\text{ends at } n) = \left(\frac{n-1}{n}\right) \frac{1}{(n-1)!} = \frac{(n-1)}{n!}$$

Moment generating function is

$$m(t) = \sum_{n=2}^{\infty} \frac{(n-1)}{n!} t^n$$

$$\begin{aligned}
\text{Now } \sum_{n=2}^{\infty} \frac{(n-1)}{n!} t^n &= \sum_2^{\infty} \frac{nt^n}{n!} - \sum_2^{\infty} \frac{t^n}{n!} \\
&= t \sum_2^{\infty} \frac{t^{n-1}}{(n-1)!} - \sum_2^{\infty} \frac{t^n}{n!} \\
&= t \sum_1^{\infty} \frac{t^m}{m!} - \sum_2^{\infty} \frac{t^n}{n!} \\
&= t(e^t - 1) - (e^t - 1 - t) \\
&= te^t - e^t + 1
\end{aligned}$$

Alternatively, work backwards:

$$\begin{aligned}
te^t - e^t + 1 &= t(1 + t + \frac{t^2}{2!} + \dots) - (1 + t + \frac{t^2}{2!} + \dots) + 1 \\
&= t^2 \left[1 - \frac{1}{2!}\right] + t^3 \left[\frac{1}{2!} - \frac{1}{3!}\right] + \dots + \\
&\quad t^n \left[\frac{1}{(n-1)!} - \frac{1}{n!}\right] + \dots
\end{aligned}$$

$$\text{But } \left[\frac{1}{(n-1)!} - \frac{1}{n!}\right] = \frac{n-1}{n!} \quad [12]$$

$$\begin{aligned}
m(t) &= te^t - e^t + 1 && \rightarrow m(1) = 1 \\
m'(t) &= e^t + te^t - e^t = te^t && \rightarrow m'(1) = e \\
m''(t) &= e^t + te^t && \rightarrow m''(1) = 2e
\end{aligned}$$

$$\therefore \text{Mean}(N) = e ;$$

$$\text{Var}(N) = 2e + e - e^2 = 3e - e^2 \quad [4]$$