

PART 1B

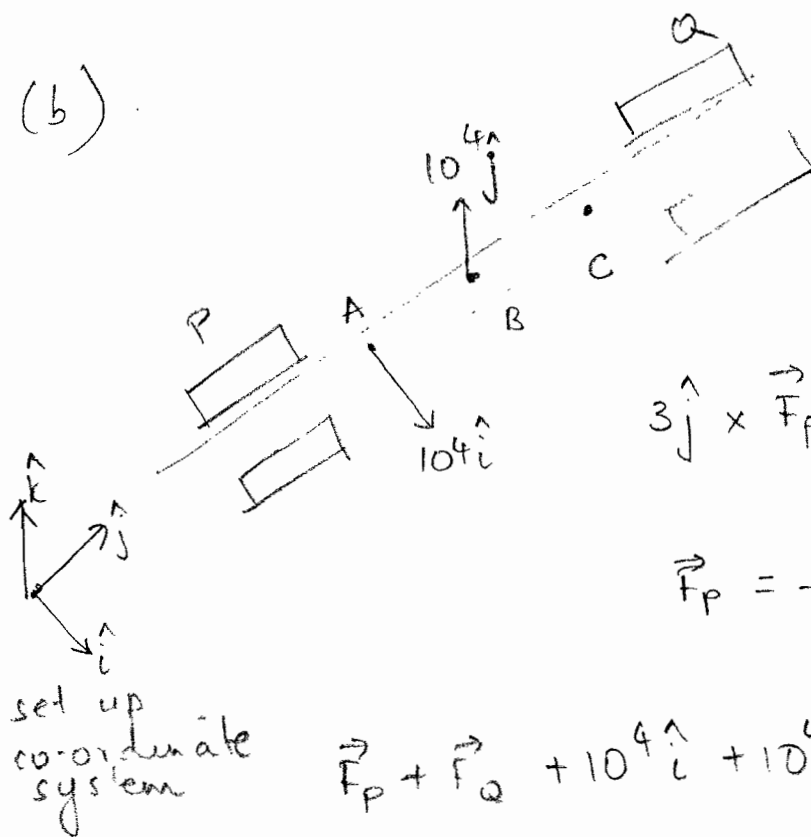
CRIB FOR PAPER 1

MECHANICS

June 2006 .

Q1 (a) A shaft is statically balanced if the overall center of gravity of the rotating masses lies on the shaft axis. In static balance the shaft bearing reactions are not necessarily zero for constant rotation. For dynamic balance for constant rotation the bearing forces are equal to zero eliminating undesired bearing reactions.

(b)



$$m.r\omega^2 = 0.01 \times 10^6 = 10^4 \text{ N}$$

Let bearing force at P and Q be \vec{F}_P and \vec{F}_Q

$$3\hat{j} \times \vec{F}_P = -2.5\hat{j} \times 10^4 \hat{i} - 1.5\hat{j} \times 10^4 \hat{k}$$

$$\vec{F}_P = \frac{-2.5 \times 10^4 \hat{i} - 0.5 \times 10^4 \hat{k}}{3}$$

set up co-ordinate system

$$\vec{F}_P + \vec{F}_Q + 10^4 \hat{i} + 10^4 \hat{k} = 0 \quad (\sum \vec{F} = 0)$$

$$\therefore \vec{F}_Q = \frac{-0.5 \times 10^4 \hat{i} - 0.5 \times 10^4 \hat{k}}{3}$$

(c) Let m_A and m_C be masses added to A and C for static and dynamic balance

$$\text{Static Balance } \sum_i m_i r_i = 0$$

$$\therefore m_S \vec{r}_S = \frac{-10^4 \hat{i} - 10^4 \hat{k}}{10^6}$$

$$\therefore m_A \vec{r}_A + m_C \vec{r}_C = m_S \vec{r}_S \quad (1)$$

Take moments about A (DYNAMIC BALANCE)

$$-\hat{j} \times 10^4 \hat{k} - 2\hat{j} \times m_C \vec{r}_C = 0$$

$$-2\hat{j} \times m_C \vec{r}_C = 10^4 \hat{i} / 10^6$$

$$m_C \vec{r}_C = \frac{5 \times 10^3}{10^6} (-\hat{k})$$

$$\therefore m_C = \frac{5 \times 10^3}{0.5 \times 10^6} = 10 \text{ g at } -\hat{k} \text{ on disc C}$$

From (1) and dynamic balance —

$$m_A \vec{r}_A = \frac{-10^4 \hat{i} - 10^4 \hat{k}}{10^6} + \frac{0.5 \times 10^4 \hat{k}}{10^6}$$

$$m_A \vec{r}_A = \frac{-10^4 \hat{i} - 0.5 \times 10^4 \hat{k}}{10^6}$$

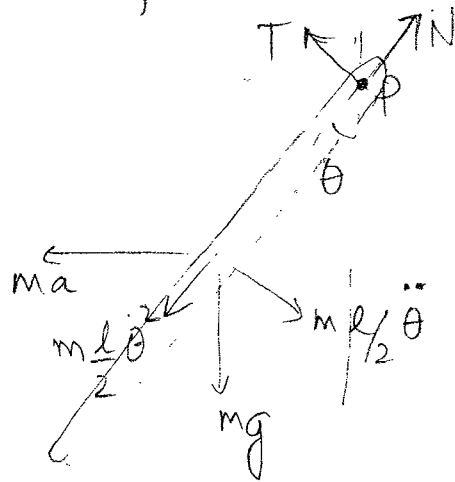
$$\therefore m_A \vec{r}_A = \left(\frac{10^4}{10^6} \right) \times 0.5 \times \sqrt{5} \frac{(-2\hat{i} - \hat{k})}{\sqrt{5}}$$

$$\vec{r}_A = \frac{0.5 (-2\hat{i} - \hat{k})}{\sqrt{5}}$$

$$m_A = \sqrt{5} \times 10^{-2} \text{ kg} = 22.4 \text{ g at } \vec{r}_A$$

Q2.

(a) Shown forces on rod



Taking moments about P —

$$I_0 \ddot{\theta} = ma \cos \theta - mg \sin \theta$$

$$\left(\frac{ml^2}{12} + \frac{ml^2}{4} \right) \ddot{\theta} = ma \cos \theta - mg \sin \theta$$

$$\ddot{\theta} = \frac{3}{2l} (a \cos \theta - g \sin \theta)$$

$$\int_0^{\theta} \dot{\theta} d\dot{\theta} = \int_0^{\theta} \ddot{\theta} d\theta$$

$$\frac{\dot{\theta}^2}{2} = \frac{3}{2l} \int_0^{\theta} (a \cos \theta - g \sin \theta) d\theta$$

$$= \frac{3}{2l} \left[g \cos \theta + a \sin \theta \right]_0^{\theta}$$

$$\therefore \dot{\theta}^2 = -\frac{3}{l} \left[g(1 - \cos \theta) - a \sin \theta \right]$$

(b) Normal reactions N and T as shown above

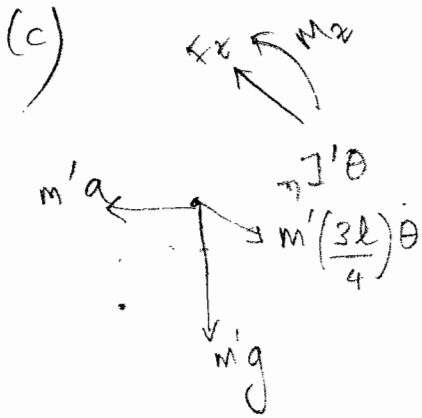
$$\sum F = 0 \quad N = mg \cos \theta + \frac{ml}{2} \dot{\theta}^2 + ma \sin \theta$$

$$N = mg \cos \theta + \frac{m l}{2} \cdot \frac{3}{l} \left[g (\cos \theta - 1) + a \sin \theta \right] + m a \sin \theta$$

$$N = \frac{5}{2} m (g \cos \theta + a \sin \theta) - \frac{3}{2} m g$$

$$\rightarrow \Sigma F = 0 \quad T = -m a \cos \theta + m g \sin \theta + \frac{m l}{2} \frac{l/2}{l^2/3} \left(a \cos \theta - g \sin \theta \right)$$

$$T = \frac{m}{4} (g \sin \theta - a \cos \theta)$$



M_2 (Bending Moment) at $l/2$ mid-point of rod

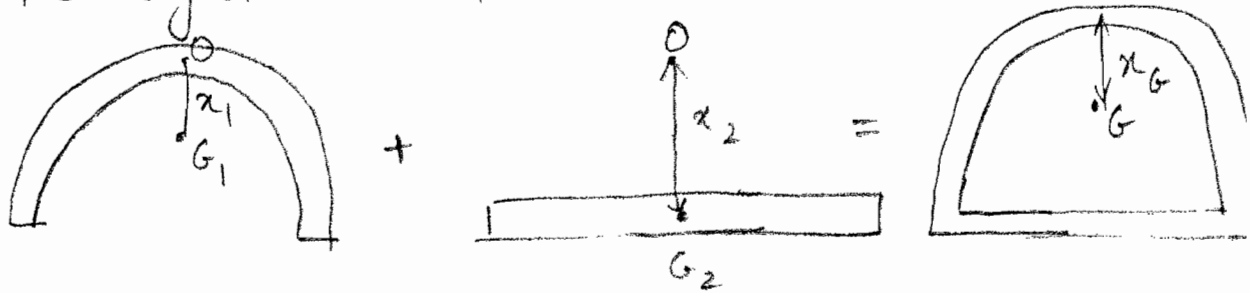
$$= -\frac{l}{4} \left(m' g \sin \theta - m' a \cos \theta + m' \left(\frac{3l}{4} \right) \ddot{\theta} \right) - I' \ddot{\theta}$$

$$= \frac{l}{4} \left(-m/2 g \sin \theta + \frac{m}{2} a \cos \theta - \frac{m}{2} \left(\frac{3l}{4} \right) \left(\frac{3}{2l} \right) \left(a \cos \theta - g \sin \theta \right) \right) - \frac{1}{2} \frac{m \left(\frac{l}{2} \right)^2}{12} \left(\frac{3}{2l} \right) \left(a \cos \theta - g \sin \theta \right)$$

$$= \frac{m l}{4} \left(-\frac{g}{2} \sin \theta + \frac{a}{2} \cos \theta + \frac{5}{8} \left(a \cos \theta - g \sin \theta \right) \right)$$

$$= + \frac{m l}{32} (g \sin \theta - a \cos \theta)$$

Q3 (a) Shape formed of a curved rod + straight rod



mass of curved rod - m_c

" " straight rod - m_s

$$m_c + m_s = m$$

$$m_c = \left(\frac{\pi}{\pi+2} \right) m \quad \text{and} \quad m_s = \frac{2m}{\pi+2}$$

$$x_1 \text{ (from mechanics databook)} = \frac{r - r \sin \pi/2}{\pi/2} = \left(\frac{\pi-2}{\pi} \right) r$$

$$x_2 = r$$

$$x_G = \left(\frac{\pi}{\pi+2} \right) \left(\frac{\pi-2}{\pi} \right) r + \left(\frac{2}{\pi+2} \right) r$$

$$x_G = \frac{\pi r}{\pi+2} \quad \text{location of center of mass below peg}$$

$$\begin{aligned} I_0 &= I_{G1} + I_{G2} + m_c r_{O-G1}^2 + m_s r_{O-G2}^2 \\ &= m_c \left[r^2 - \left(\frac{1}{\pi/2} \right)^2 r^2 \right] + \frac{m_s}{12} (2r)^2 + m_c x_1^2 + m_s x_2^2 \\ &= m_c \left[r^2 - \frac{4r^2}{\pi^2} + \frac{(\pi-2)^2 r^2}{\pi^2} \right] + \frac{m_s}{3} r^2 + m_s r^2 \\ &= \frac{2(\pi-2)}{\pi+2} m r^2 + \frac{4}{3} \left(\frac{2}{2+\pi} \right) m r^2 = \frac{(6\pi-4)}{3(\pi+2)} m r^2 \end{aligned}$$

$$(b) \quad T = \frac{1}{2} I_0 \dot{\theta}^2$$

$$= \frac{1}{2} \frac{(6\pi - 4)}{3(\pi + 2)} m r^2 \dot{\theta}^2$$

$$V = mg X_G \left[1 - \underset{\substack{\downarrow \\ \text{expand as } \left(1 - \frac{\theta^2}{2}\right) \text{ for} \\ \text{small } \theta}}{\cos \theta} \right]$$

$$V \approx mg \left(\frac{\pi r}{\pi + 2} \right) \frac{\theta^2}{2}$$

$$(c) \quad T + V = E \quad (\text{conservative system})$$

$$\frac{1}{2} \frac{(6\pi - 4)}{3(\pi + 2)} m r^2 \dot{\theta}^2 + \frac{\pi m g r}{\pi + 2} \frac{\theta^2}{2} = E$$

$$\frac{(6\pi - 4)}{3(\pi + 2)} m r^2 \ddot{\theta} + \frac{\pi m g r}{\pi + 2} \theta = 0 \quad (\text{Equation of Motion})$$

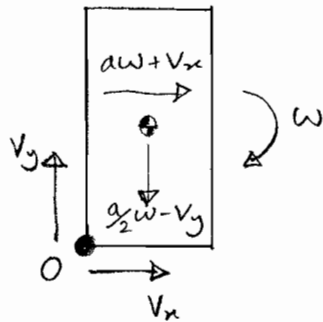
$$\omega^2 = \frac{\pi m g r}{\pi + 2} \frac{= 3\pi g}{(6\pi - 4)r} \frac{6\pi - 4}{3(\pi + 2)} m r^2$$

natural frequency of small oscillation

4) (a) Using the perpendicular axis theorem

$$I_{zz} = I_{xx} + I_{yy} \\ = \frac{1}{12} m b^2 + \frac{1}{12} m a^2 = \frac{1}{12} m (a^2 + b^2)$$

(b)



After impact O has velocity V_x, V_y

$$I_O = \frac{1}{12} m ((2a)^2 + a^2) = \frac{5}{12} m a^2$$

Conservation of linear momentum:

$$\rightarrow 5m(aw + V_x) + mV_x = 0 \quad \therefore 5aw + 6V_x = 0 \quad (1)$$

$$\downarrow 5m\left(\frac{a}{2}\omega - V_y\right) - mV_y = 5m \cdot u - m \cdot 5u = 0 \\ \therefore \frac{5}{2}a\omega - 6V_y = 0 \quad (2)$$

Conservation of moment of momentum:

About O: \curvearrowright

$$5m \cdot (aw + V_x) \cdot a + 5m \left(\frac{a}{2}\omega - V_y\right) \frac{a}{2} + \frac{5}{12} m a^2 \omega = 5m \cdot u \cdot \frac{a}{2}$$

$$\therefore \left(5 + \frac{5}{4} + \frac{5}{12}\right) a\omega + 5V_x - \frac{5}{2}V_y = \frac{5}{2}u \\ \frac{4}{3}a\omega + V_x - \frac{1}{2}V_y = \frac{1}{2}u \quad (3)$$

$$(1) \text{ \& } (2) \text{ -into } (3) \quad \frac{4}{3}a\omega - \frac{5}{6}a\omega - \frac{1}{2} \frac{5}{12}a\omega = \frac{1}{2}u$$

$$\left(\frac{8}{3} - \frac{5}{3} - \frac{5}{12}\right) a\omega = u \quad \therefore \omega = \frac{12u}{7a} \quad \text{clockwise}$$

$$\text{and} \quad V_x = \frac{-5a \cdot 12u}{6 \cdot 7a} = \frac{-10}{7}u$$

$$V_y = \frac{5}{7}u$$

4) (cont.) Velocity of C.O.G. of Q: $aw + V_x = \frac{12}{7}u - \frac{10}{7}u = \frac{2}{7}u$
 $\frac{a}{2}w - V_y = \frac{6}{7}u - \frac{5}{7}u = \frac{1}{7}u$

(c) Energy dissipated in impact = Initial K.E.
 - Final K.E.

$$\left\{ \frac{1}{2} \cdot 5m \cdot u^2 + \frac{1}{2} \cdot m \cdot (5u)^2 \right\} - \left\{ \frac{1}{2} \cdot 5m \left[\left(\frac{-10}{7}u \right)^2 + \left(\frac{5}{7}u \right)^2 \right] \right.$$

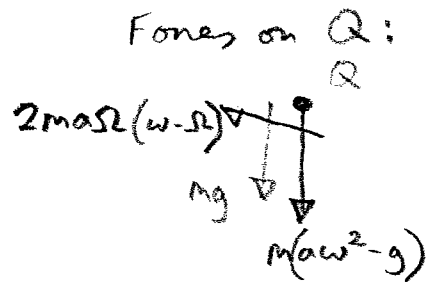
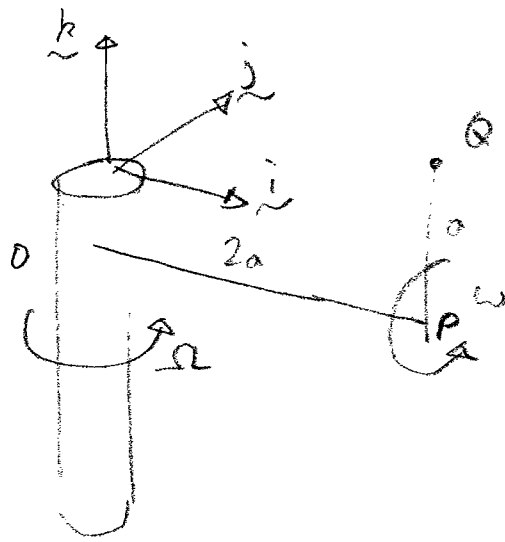
$$\left. + \frac{1}{2} \cdot m \left[\left(\frac{2}{7}u \right)^2 + \left(\frac{1}{7}u \right)^2 \right] + \frac{1}{2} \cdot \frac{5}{12} m a^2 \cdot \left(\frac{12u}{7a} \right)^2 \right\}$$

$$= \frac{mu^2}{2} \left(\left\{ 5 + 25 \right\} - \left\{ \frac{500}{49} + \frac{125}{49} + \frac{4}{49} + \frac{1}{49} + \frac{5 \cdot 12}{49} \right\} \right)$$

$$= \frac{mu^2}{2} \left(30 - \frac{690}{49} \right)$$

$$= \frac{390}{49} mu^2$$

5



$$\underline{r} = 2a \underline{i} + a \underline{k}$$

$$\left[\frac{d\underline{r}}{dt} \right]_R = -a\omega \underline{j} \quad \left[\frac{d^2 \underline{r}}{dt^2} \right]_R = -a\omega^2 \underline{k}$$

$$(a) \quad \underline{v}_Q = \left[\frac{d\underline{r}}{dt} \right]_R + \underline{\Omega} \times \underline{r} = -a\omega \underline{j} + \Omega \underline{k} \times (2a \underline{i} + a \underline{k})$$

$$= -a\omega \underline{j} + 2a\Omega \underline{j} = (2\Omega - \omega)a \underline{j}$$

$$(b) \quad \underline{a}_Q = \left[\frac{d^2 \underline{r}}{dt^2} \right]_R + \frac{d\underline{\Omega}}{dt} \times \underline{r} + 2\underline{\Omega} \times \left[\frac{d\underline{r}}{dt} \right]_R + \underline{\Omega} \times (\underline{\Omega} \times \underline{r})$$

$$= -a\omega^2 \underline{k} + 2\Omega \underline{k} \times -a\omega \underline{j} + \Omega \underline{k} \times 2a\Omega \underline{j}$$

$$= -a\omega^2 \underline{k} + 2\Omega \omega a \underline{i} + -2a\Omega^2 \underline{i}$$

$$= 2a\Omega(\omega - \Omega) \underline{i} - a\omega^2 \underline{k}$$

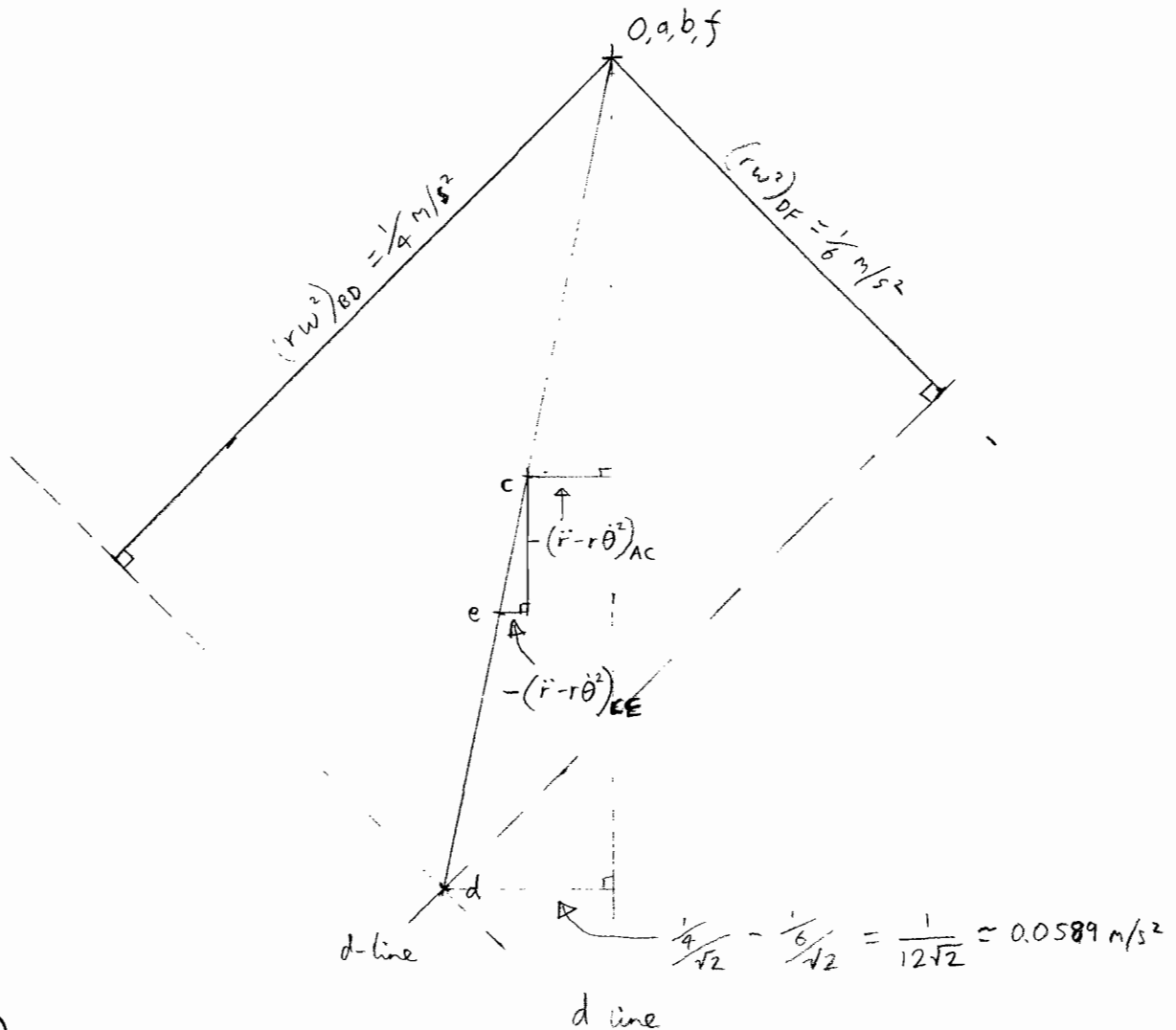
(c) Forces in bar PQ: Axial tension = $m(a\omega^2 - g)$

Shear force (in the \underline{j} direction) = $2ma\Omega(\omega - \Omega)$

b) (cont.)

Acceleration diagram

$(100 \text{ mm} = 0.25 \text{ m/s}^2)$



(b)

For AC $-(\ddot{r} - r\dot{\theta}^2)_{AC} = \frac{1}{2} \frac{1}{12\sqrt{2}}$

$$\begin{aligned} \ddot{r}_{AC} &= -\frac{1}{2} \frac{1}{12\sqrt{2}} + \sqrt{2} \times \left(\frac{1}{4\sqrt{2}}\right)^2 = \frac{-1}{24\sqrt{2}} + \frac{\sqrt{2}}{32} \\ &= \frac{1}{\sqrt{2}} \left(\frac{1}{16} - \frac{1}{24}\right) = \frac{1}{8\sqrt{2}} \left(\frac{1}{2} - \frac{1}{3}\right) \\ &= \frac{1}{48\sqrt{2}} \text{ m/s}^2 \end{aligned}$$

For CE $-(\ddot{r} - r\dot{\theta}^2)_{CE} = \frac{1}{3} \times \frac{1}{24\sqrt{2}}$

$$\begin{aligned} \ddot{r}_{CE} &= \frac{-1}{72\sqrt{2}} + \sqrt{2} \times \left(\frac{1}{6\sqrt{2}}\right)^2 = \frac{-1}{72\sqrt{2}} + \frac{1}{36\sqrt{2}} \\ &= \frac{1}{72\sqrt{2}} \text{ m/s}^2 \end{aligned}$$