Thursday 6 June $2013 \quad 2$ to 4

Paper 6

## INFORMATION ENGINEERING

Answer not more than four questions.
Answer not more than two questions from each section.
All questions carry the same number of marks.
The approximate number of marks allocated to each part of a question is indicated in the right margin.

Answers to questions in each section should be tied together and handed in separately.

Attachments: Additional copy of Fig. 1

STATIONERY REQUIREMENTS
Single-sided script paper

SPECIAL REQUIREMENTS
Engineering Data Book
CUED approved calculator allowed

## SECTION A

Answer not more than two questions from this section.

1 (a) Briefly describe a procedure to measure experimentally the Bode diagram of a physical system. What conditions should the system satisfy if this procedure is to be carried out?
(b) Figure 1 shows the Bode diagram of a stable linear system with transfer function of the form

$$
G(s)=\frac{a s(1+b s)}{(1+c s)\left(1+0.4\left(s / \omega_{n}\right)+\left(s / \omega_{n}\right)^{2}\right)} .
$$

(i) Estimate the values of $a, b, c$ and $\omega_{n}$.
(ii) The system is to be controlled in a unity gain negative feedback system with pre-compensator

$$
K(s)=k \frac{s+1}{0.1 s+1} .
$$

For $k=1$ sketch the Bode diagram of the compensated system $G(j \omega) K(j \omega)$ on the attached figure.
(iii) Use your sketch to estimate the value of $k$ for which the compensated system in part (b)(ii) has a phase margin of $45^{\circ}$.


Fig. 1

Note: an additional copy of Fig. 1 is attached at the end of this paper. This should be annotated with your constructions and handed in with your answer to this question.
(b) (i) Show that the Laplace transfer function relating $v_{o}$ to $v_{i}$ for the operational amplifier circuit shown in Fig. 2 is given by

$$
\frac{-K}{T s+1}
$$

where $K=R_{1} / R_{2}$ and $T=R_{1} C_{1}$. It may be assumed that all circuit elements behave in an ideal manner.
(ii) Four identical circuits of the form shown in Fig. 2 are connected in series. It may be assumed that this cascade connection continues to behave in an ideal manner with transfer function equal to

$$
\frac{K^{4}}{(T s+1)^{4}} .
$$

Sketch the Nyquist diagram of this transfer function. Calculate the intersection points of the Nyquist diagram with the real axis.
(iii) The cascade circuit of part (b)(ii) is connected in a unity gain negative feedback loop. Show that the loop is stable providing

$$
0<K<\sqrt{2}
$$

Find the corresponding condition for a unity gain positive feedback loop.


Fig. 2

3 A stirred tank with heater has inflow and outflow pipes with equal flow rates. The temperature of the liquid in the tank and outflow pipe is $T$ and the temperature in the inflow pipe is $T_{i}$. The rate of supply of heat from the heater is denoted by $Q_{\mathrm{in}}$. An energy balance per unit time for the system results in the equation

$$
V \frac{d T}{d t}=F\left(T_{i}-T\right)+\frac{1}{\rho c_{p}} Q_{\text {in }}
$$

where $V=5 \mathrm{~m}^{3}$ is the volume of liquid in the tank, $F=0.1 \mathrm{~m}^{3} \mathrm{~s}^{-1}$ is the flow rate, $c_{p}$ is the specific heat capacity of the liquid and $\rho$ is its density. A sensor measures the temperature at a point in the outflow pipe to provide the signal $y(t)=T(t-\tau)$ where $\tau=2 \mathrm{~s}$ is the "transport" delay. The heat supply is set by the feedback law

$$
\frac{1}{\rho c_{p}} Q_{\mathrm{in}}(t)=k_{p}\left(T_{0}(t)-y(t)\right)
$$

where $T_{0}$ is the desired temperature and $k_{p}$ is a proportional gain parameter.
(a) Sketch a block diagram of the system.
(b) Calculate the closed-loop transfer-functions $H_{1}(s)$ and $H_{2}(s)$ for which

$$
\bar{T}(s)=H_{1}(s) \bar{T}_{0}(s)+H_{2}(s) \bar{T}_{i}(s) .
$$

(c) Calculate and sketch the response of $T(t)$ to a step change of 1 K in $T_{i}$, assuming that $k_{p}=0$, i.e. the heater is switched off.
(d) It is necessary to select $k_{p}$ so that the closed-loop system is stable. It may be assumed that $k_{p}=0.05$ is such a choice. If $T_{i}$ is a sine wave of amplitude 1 K at a frequency of $1 \mathrm{rad} \mathrm{s}^{-1}$, what is the steady-state amplitude of oscillation in $T$ ?

## SECTION B

Answer not more than two questions from this section.

4
(a) The Fourier transforms of $f(t)$ and $g(t)$ are $F(\omega)$ and $G(\omega)$ respectively.
(i) If $h(t)$ is the convolution of $f(t)$ and $g(t)$, i.e. $h(t)=f(t) * g(t)$, prove that the Fourier transform of $h(t)$, which we write as $H(\omega)$, is given by

$$
H(\omega)=F(\omega) G(\omega)
$$

(ii) If the cross-correlation, $R_{f g}(t)$, of two real functions $f(t)$ and $g(t)$ is defined by

$$
R_{f g}(t)=\int_{-\infty}^{\infty} f(\tau) g(\tau+t) d \tau
$$

give an expression for the Fourier transform of $R_{f g}(t)$ in terms of $F(\omega)$ and $G(\omega)$.
(iii) Describe how $f * g$ is related to $g * f$, and how $R_{f g}$ is related to $R_{g f}$.
(b) The function $p(t)$ has Fourier transform $q(\omega)$.
(i) Show that $q(t)$ has a Fourier transform given by $2 \pi p(-\omega)$. This is the duality property.
(ii) Using duality or otherwise, find the Fourier transform of $\operatorname{sinc}(t)$.
(iii) Using Parseval's Theorem and the result in part (b)(ii), show that

$$
\int_{-\infty}^{\infty} \operatorname{sinc}^{2} t d t=\pi
$$

5 (a) If a continuous time signal $y(t)$ is sampled at a frequency $f_{s}$, which is greater than twice the maximum frequency component, $f_{\max }$, in $y(t)$, describe how we can recover the original signal from the sampled signal, $y_{s}(t)$, via a reconstruction filter with impulse response, $h_{r}(t)$. The explicit form of $h_{r}(t)$ should be given.
(b) The signal

$$
y(t)= \begin{cases}1 & 0 \leq t<1 \\ 0 & \text { otherwise }\end{cases}
$$

is sampled at 0.25 s intervals starting at $t=0$. If we take 8 samples, $y_{n}$, for $n=0, . ., 7$, we can form 8 discrete Fourier transform (DFT) coefficients, $Y_{k}$, for $k=0, . ., 7$. Find the first 3 DFT coefficients, verifying that $Y_{2}=0$. By considering the continuous Fourier transform of $y(t)$, comment on whether you expect $Y_{2}$ to be zero.
(c) A digitiser has two analogue input channels each able to receive input signals of bandwidth up to 20 kHz . After sampling and quantising the input signals, the digitiser combines them into a joint data stream which is transmitted at a rate of $1.5 \mathrm{Mbits}^{-1}$. Estimate how many bits per sample are available if the input signals are sampled so as to avoid aliasing. If the input signals can be approximated by sinusoidal components, determine the maximum signal to quantisation noise power ratio that can be achieved on each channel, stating any assumptions that are made.

6 (a) Modulation techniques which can accommodate multiple users in a communications channel are termed Multiple Access methods. Describe and compare the three main multiple access techniques.
(b) A channel with additive, white Gaussian noise (with a power spectral density given by $N_{0}$ ) is to have total bandwidth $B$ and a capacity of $C$. What is the total transmitted power $P$ ?
(c) Assuming no overlap nor guard bands, give expressions for the channel capacity per user for the FDMA and TDMA multiple access techniques in terms of total bandwidth, noise characteristics, total power transmitted and number of users.
(d) A wireless channel extends from 50 MHz to 250 MHz and we wish to use FDMA to transmit binary data from $M$ users at a rate of $50 \mathrm{kbit} \mathrm{s}^{-1}$ per user.
(i) If the data from each user is to be modulated using BPSK with user $i$ having a carrier frequency of $f_{c}^{i}$, determine and sketch the BPSK power spectrum.
(ii) Using the result in part (d)(i), find the maximum value of $M$ assuming that any overlaps between the spectra of adjacent users are to occur beyond the first sidelobe. State clearly any assumptions made.

## END OF PAPER

## Candidate Number:

## ENGINEERING TRIPOS PART IB

Thursday 6 June 2013, Paper 6, Question 1.



Copy of Fig. 1. This should be annotated with your constructions and handed in with your answer to question 1.

