

1/ (a) For full bridge  $\Delta V = \frac{I}{2fC}$

Assuming: Instantaneous charging of the capacitor\*  
No voltage drop over the diodes.

2

\* ie.  $\frac{1}{2}$  cycle discharge (alt. answer)

$$\Delta V = 0.05 \cdot \sqrt{2} \cdot 230$$

$$C = \frac{10}{0.05 \cdot \sqrt{2} \cdot 230 \cdot 100} = 6.1 \text{ mF}$$

4

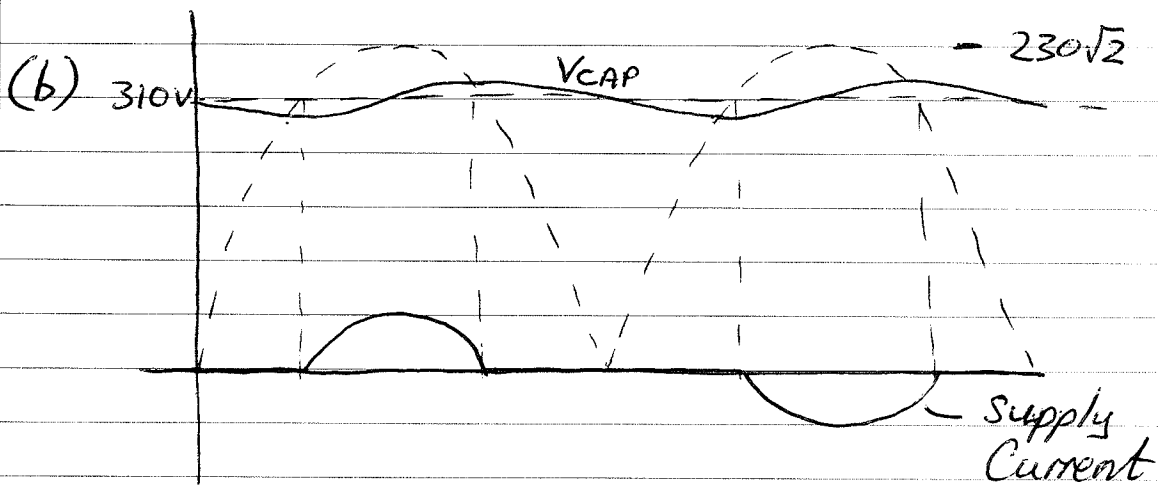
C discharged.  $I = C \frac{dV}{dt}$ , max  $\frac{dV}{dt}$  at  $\hat{V} \sin 0$

$$\hat{I} = C \omega \hat{V} = 6.1 \text{ m} \cdot 2\pi \cdot 50 \cdot \sqrt{2} \cdot 230$$

$$= 628 \text{ A}$$

2

In reality the line inductance will greatly reduce this extreme value.



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1 (b) cont. Peak magnitude from sketch

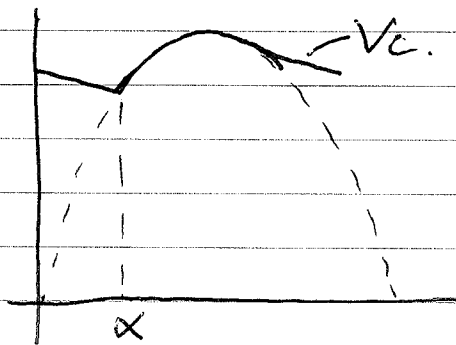
$$\text{at } I = \frac{\sqrt{2} \cdot 230 - 310}{0.5 \Omega} = 30 \text{ A}$$

3

Assuming the capacitor voltage is half charged at  $\pi$  of the sine wave (or 310V is nearly constant).

1

Close the switch (between charges say).



$$\alpha = \sin^{-1} \frac{310}{325} \\ = 72.5^\circ$$

$$I = \frac{C dV}{dt} = 6.1 \text{ m} \cdot 325 \cdot 2\pi \cdot 50 \cos 72.5^\circ \\ = 187 \text{ A}$$

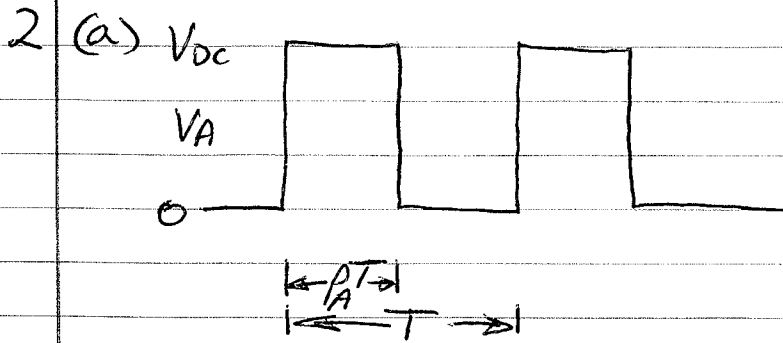
2

Still pretty horrible  $\Rightarrow$

Use a MOSFET as a controlled resistor

or add small inductor

2



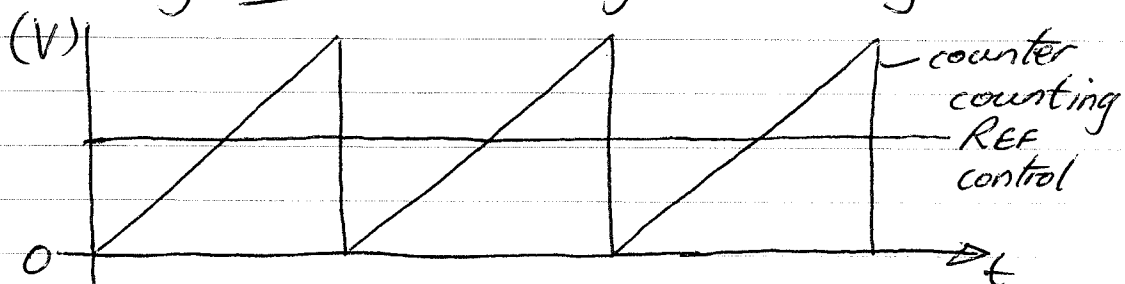
The average value of  $V_A$  is  $P V_{dc}$ .

If the load is inductive the high frequency components are filtered out, and only the dc component comes through. This may vary, however, as long as it's not too fast, for the filter effect ~~to~~ <sup>may</sup> cut it down.

Only the  $M_1$  switching matters as  $M_4 = \overline{M_1}$ , to avoid the voltage depending on the current sense.

Bipolar mode  $M_2 = M_1$ ,  $M_3 = M_4 = \overline{M_1} = \overline{M_2}$

so only one control signal necessary.



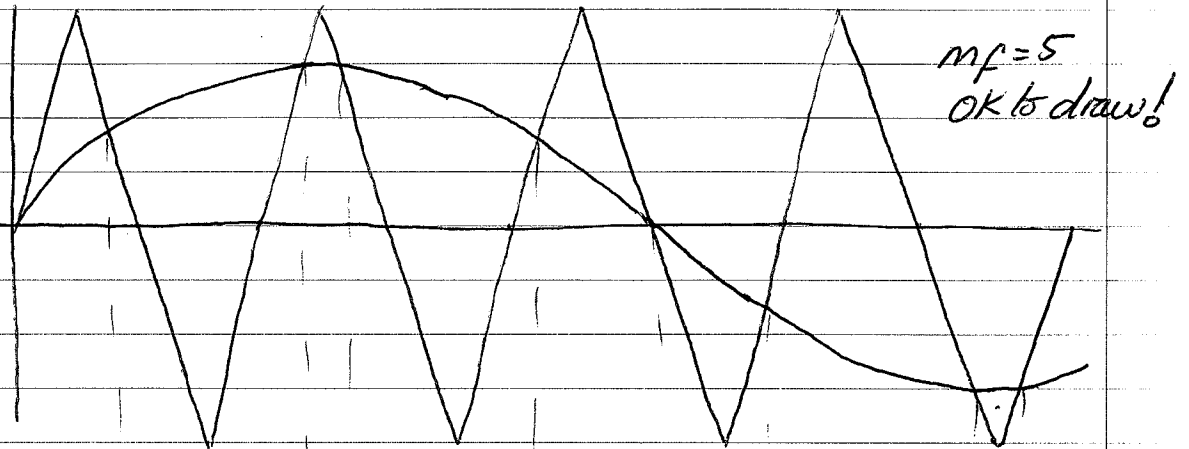
If count > REF  $M_1$  ON ;  $V_A = V_{DC}$ .

If count < REF  $M_1$  OFF ;  $V_A = 0$

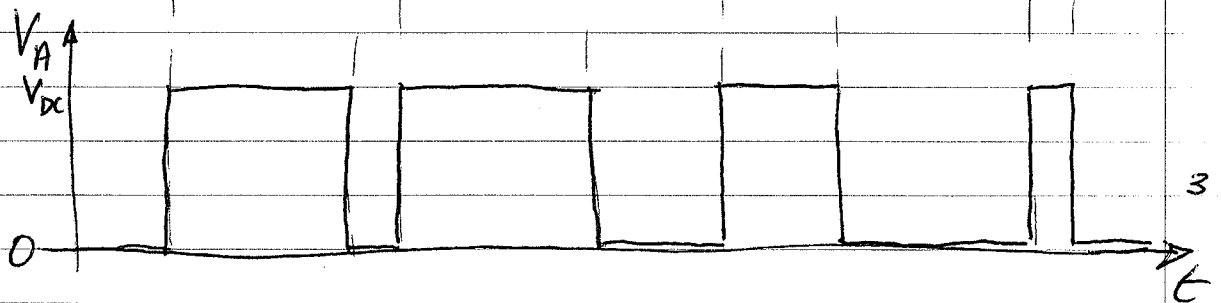
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(b) To avoid subharmonics use integer  $m_f$ .

(Odd integer  $\times 3$  is best!)



$m_f = 5$ ; (9 is hard to draw!)



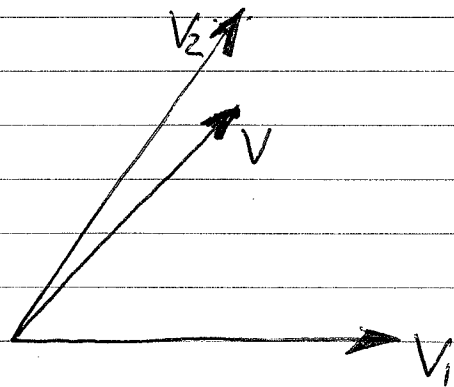
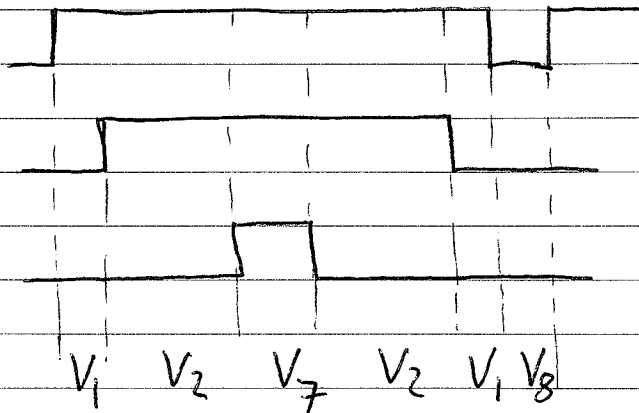
3 SVM sequences:

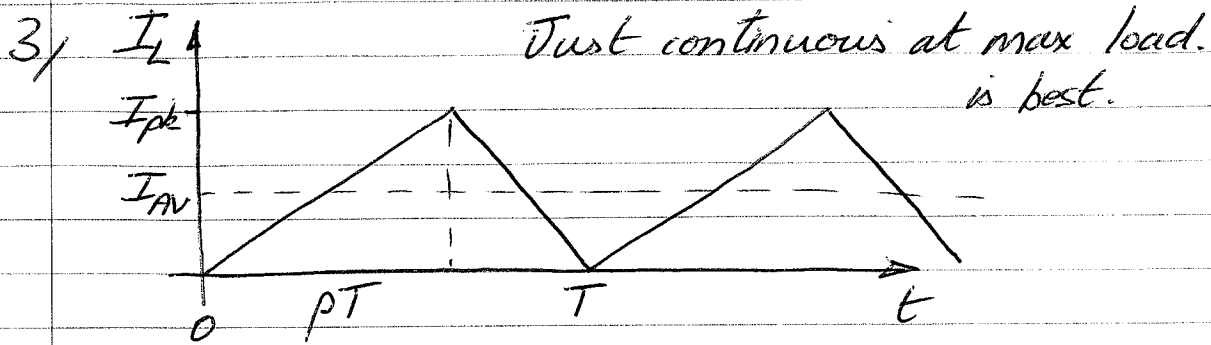
eg.  $V_1 V_2 V_7 V_1 V_2 V_7 \dots$   
 $V_1 V_2 V_8 V_1 V_2 V_8 \dots$   
 $V_1 V_2 V_7 V_2 V_1 V_8 V_1 \dots$   $\leftarrow$  minimal switching.

|       |       |       |       |
|-------|-------|-------|-------|
| $V_1$ | $1^*$ | $0$   | $0$   |
| $V_2$ | $1$   | $1^*$ | $0$   |
| $V_7$ | $1$   | $1$   | $1^*$ |
| $V_2$ | $1$   | $1$   | $0^*$ |
| $V_1$ | $1$   | $0^*$ | $0$   |
| $V_8$ | $0^*$ | $0$   | $0$   |

Only 1 commutation\*  
per change of state.

eg.





Current drawn from 12V all the time.

$$\Rightarrow 500W = 12 \times I_{AV} \quad I_{pk} = 2I_{AV}$$

$$\therefore I_{pk} = 83.3A \quad I_{AV} = 41.6A$$

So MOSFET withstands 42V, 83.3A: MOSFETS below 60V are very good and 83.3A is quite possible, maybe with two in parallel.

If the load is disconnected the voltage would be uncontrolled and too high if there is no feedback controller, (and the load will vary here)

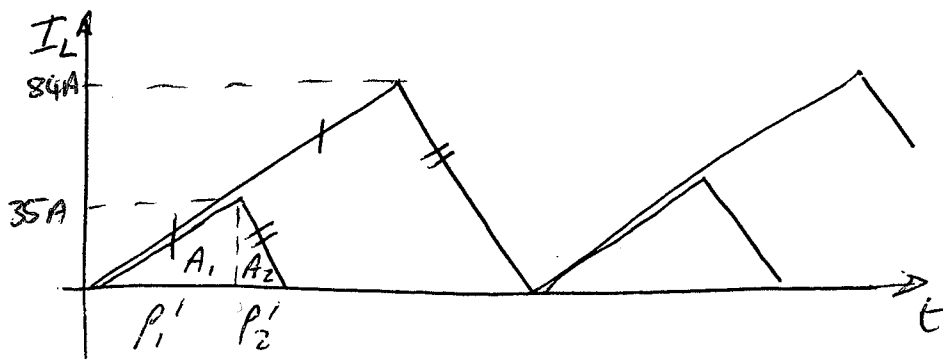
Discontinuous gives zero turn-on loss and smaller value of  $L$  (no saturation danger either).

$$|L \Delta i| = |12 pT| = |(42-12)(1-p)T|$$

$$\Rightarrow 12p = (42-12)(1-p) = 42-12-42p+12p$$

$$p = \frac{42-12}{42} = \underline{\underline{0.714}} \quad V = L \frac{\Delta i}{\Delta t}$$

$$L = 12 \cdot pT / 83.3 \quad \underline{\underline{L = 4.11 \mu H}}$$



$$I_{\max} = \frac{12}{L} \cdot P_1 T \left( \frac{V_{in} P_1 T}{L} \right)$$

Similarly  $P_2 T = \frac{I_{\max} L}{(V_o - V_{in})}$

Substituting  $P_2 T = \frac{V_{in} P_1 T}{L} \cdot \frac{L}{V_o - V_{in}}$

Energy taken from supply per cycle =  $A_1 + A_2$

$$A_1 + A_2 = \frac{1}{2} (P_1 + P_2) T \times I_{\max}$$

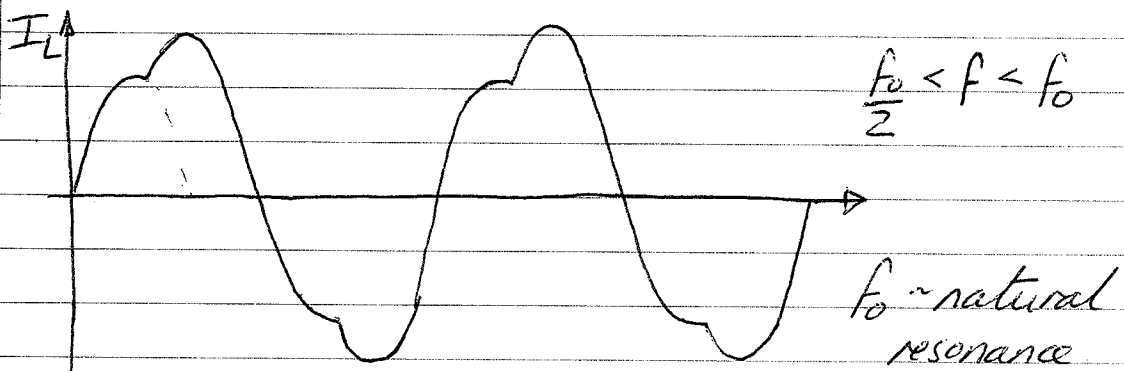
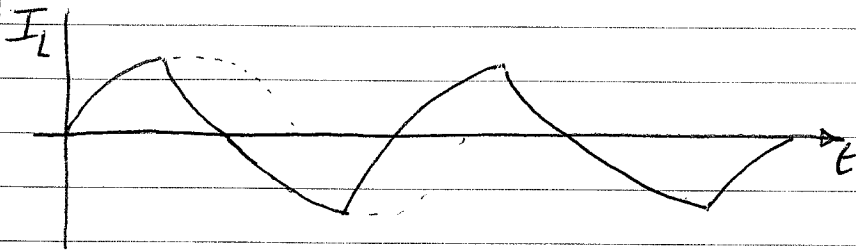
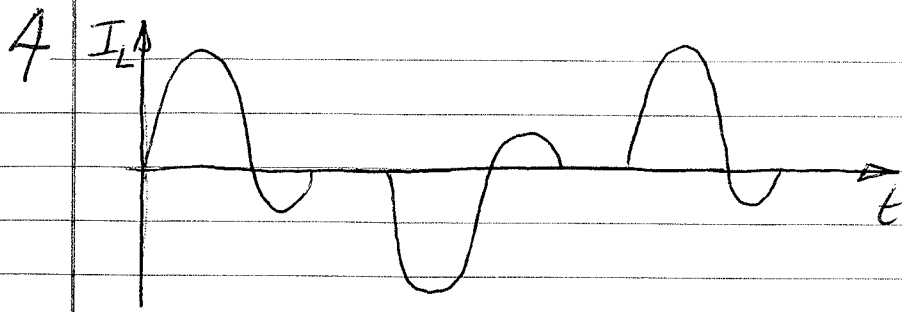
$$= \frac{1}{2} \left( P_1 + P_1 \frac{V_{in}}{V_o - V_{in}} \right) T \cdot \frac{V_{in} P_1 T}{L}$$

$$= \frac{1}{2L} P_1^2 T^2 \frac{V_o V_{in}}{V_o - V_{in}}$$

Everything is constant except  $P_1$ , so scale the power (energy per cycle  $\times f$ ) by  $P_1^2$

$$\frac{500}{0.71^2} \times 0.3^2 = \underline{\underline{89W}}$$

Obvious from the sketch above!  
( $\frac{1}{I}^2$  ratio.)

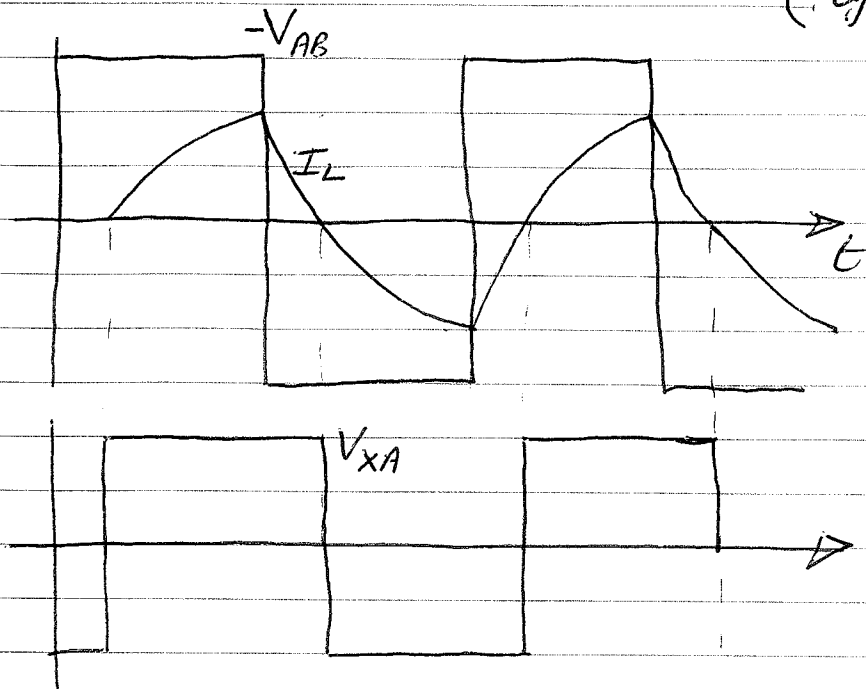


$f > f_0$  means hardswitched turn-off and soft switched turn-on, so no diode recovery problem and no turn-on losses. Both are important at high frequencies (high  $\frac{di}{dt}$  and losses  $\propto f$ )



cont/ Waveforms:

(eq.  $f \approx 2f_0$ )



Rectifier,  $C_0$  and  $R$  look like a resistor  $R_{eq}$  as the current  $I_L$  is in phase with the voltage  $V_{XA}$ .

So its a simple circuit:

$$\left| \frac{V_{XA}}{-V_{AB}} \right| = \left| \frac{R_{eq}}{R_{eq} + sL + 1/sC} \right| = \left| \frac{R_{eq} sC}{1 + s^2LC + sR_{eq}C} \right|$$

$$= \frac{1}{\sqrt{1 + \frac{(1 - \omega^2LC)^2}{\omega^2 R_{eq}^2 C^2}}}$$

Note:  $\frac{4}{\pi}$  cancels.

To reduce the turn-off losses add a small capacitor to each leg output A-zero B-zero to act as a snubber