

ENGINEERING TRIPOS PART IIA 2004

Solutions to Module 3D7

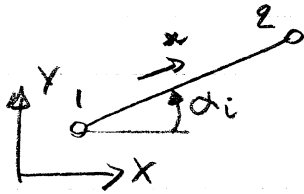
Finite Element Methods

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I

(a) Stiffness matrix for a pin-jointed element, in global coordinate system, is given as above sheet.



$$\frac{AE}{l_i} \begin{bmatrix} u^2 & uv & -u^2 & -uv \\ & v^2 & -uv & -v^2 \\ \text{---} & \text{---} & \text{---} & \text{---} \\ \text{symm.} & \begin{bmatrix} u^2 & uv \\ & v^2 \end{bmatrix} & & \end{bmatrix}$$

Where:

$$u = \cos d_i$$

$$v = \sin d_i$$

$$\underbrace{\quad}_{K'_{22}}$$

For convenience, arrange all local member axes to go towards joint B \therefore overall stiffness matrix is obtained by superposing matrices \underline{K}'_{22} for the members I, ... IV

I	$d_I = 0^\circ$	$u = 1, v = 0$	$\underline{K}'_{22} = \frac{AE}{L} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$
II	$d_{II} = 90^\circ$	$u = 0, v = 1$	$\frac{AE}{L} \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$
III	$d_{III} = 135^\circ$	$u = -\frac{\sqrt{2}}{2}, v = \frac{\sqrt{2}}{2}$	$\frac{AE}{\sqrt{2}L} \begin{bmatrix} \frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix}$
IV	$d_{IV} = 180^\circ$	$u = -1, v = 0$	$\frac{AE}{L} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$

Stiffness equations for node B:

$$\frac{AE}{L} \begin{bmatrix} 1 + \frac{1}{2\sqrt{2}} + 1 & -\frac{1}{2\sqrt{2}} \\ -\frac{1}{2\sqrt{2}} & 1 + \frac{1}{2\sqrt{2}} \end{bmatrix} \begin{bmatrix} d_{BX} \\ d_{BY} \end{bmatrix} = \begin{bmatrix} P_{BX} \\ P_{BY} \end{bmatrix}$$

(b) $P_{BX} = F/\sqrt{2}, P_{BY} = F/\sqrt{2}$

$$\frac{AE}{L} \begin{bmatrix} 2.3536 & -0.3536 \\ -0.3536 & 1.3536 \end{bmatrix} \begin{bmatrix} d_{BX} \\ d_{BY} \end{bmatrix} = \begin{bmatrix} F/\sqrt{2} \\ F/\sqrt{2} \end{bmatrix}$$

$$\therefore \begin{bmatrix} d_{BX} \\ d_{BY} \end{bmatrix} = \frac{FL}{AE} \begin{bmatrix} 0.3943 \\ 0.6254 \end{bmatrix}$$

(c) Element compatibility matrix in global coordinates relates nodal displacements to extension:

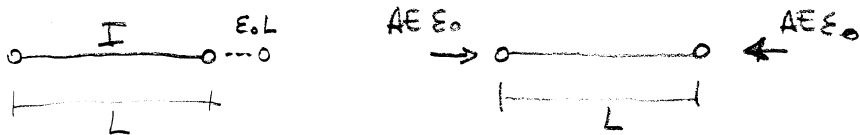
$$\underbrace{\begin{bmatrix} H' \\ \sim \\ i \end{bmatrix}}_{\text{compatibility matrix}} \underbrace{\begin{bmatrix} d_i' \\ \sim \\ i \end{bmatrix}}_{\text{displ. components of nodes 1, 2 of element } i} = \underbrace{e_i}_{\text{extension}}$$

from definition $H_i^{iT} = [-u \ -v \ u \ v]$

Node 1 of bar III is fixed; displacement comp. of node 2 are d_{2X}, d_{2Y} \therefore

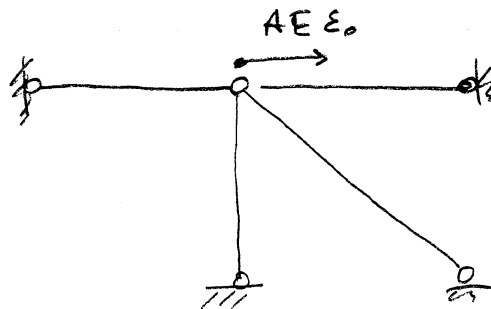
$$e_{III} = \begin{bmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 0.3943 \\ 0.6254 \end{bmatrix} \frac{FL}{AE} = 0.1634 \frac{FL}{AE}$$

(d) We could begin by considering bar I in isolation, and then apply two equal and opposite forces to make its length = L:



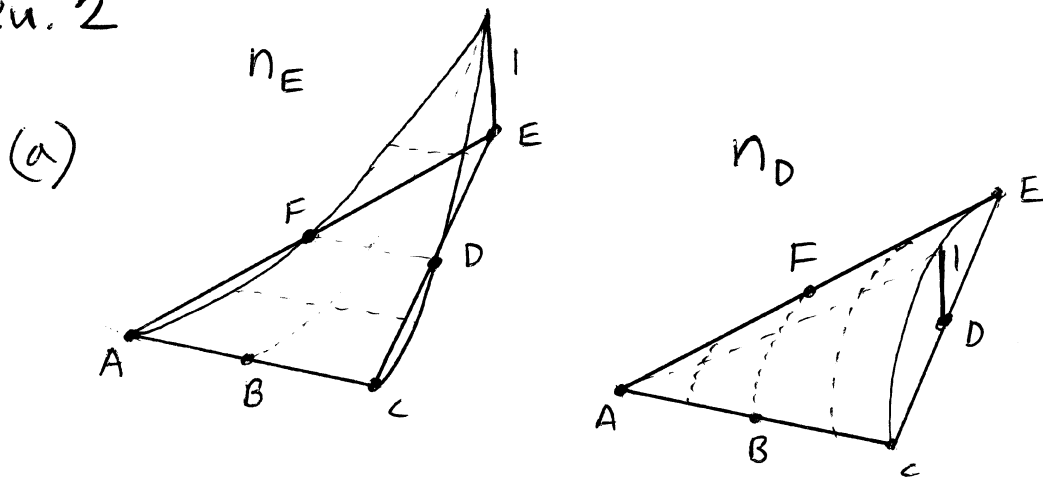
Next, connect bar I to rest of structure (while keeping the opposite forces on it). Structure fits together perfectly.

Finally, remove forces, hence need to analyze effect of removing AEE_0 . Therefore, the load case to be analyzed is:



3D7

Qu. 2



Convert data sheet shape functions ($x = 2\xi, y = 4\eta$)

$$n_E = \eta(2\eta - 1)$$

$$= \frac{y}{4} \left(\frac{y}{2} - 1 \right)$$

$$n_D = 4\xi\eta$$

$$= 4 \frac{x}{2} \frac{y}{4}$$

$$= \frac{1}{2}xy$$

(b)

Displacement field:

$$u_x = n_D u_{Dx} + n_E u_{Ex}$$

$$= \left[\frac{1}{2}xy \times 3 + \frac{y}{4} \left(\frac{y}{2} - 1 \right) \times -2 \right] \times 10^{-4}$$

$$= \left[\frac{3}{2}xy + \frac{y}{2} - \frac{y^2}{4} \right] \times 10^{-4}$$

$$u_y = n_D u_{Dy} + n_E u_{Ey}$$

$$= \left[\frac{1}{2}xy \times 1 + \frac{y}{4} \left(\frac{y}{2} - 1 \right) \times -2 \right] \times 10^{-4}$$

$$= \left[\frac{1}{2}xy + \frac{y}{2} - \frac{y^2}{4} \right] \times 10^{-4}$$

307 Qu. 2 (cont.)

Strain field: ϵ @ P $x=1$ $y=0.5$

$$\epsilon_x = \frac{\partial u_x}{\partial x} = 10^{-4} \left[\frac{3}{2} y \right] \left(= \frac{3}{4} \times 10^{-4} \text{ @ P} \right)$$

$$\epsilon_y = \frac{\partial u_y}{\partial y} = 10^{-4} \left[\frac{1}{2} x + \frac{1}{2} - \frac{y}{2} \right] \left(= \frac{3}{4} \times 10^{-4} \text{ @ P} \right)$$

$$\begin{aligned} \gamma_{xy} &= \frac{\partial u_x}{\partial y} + \frac{\partial u_y}{\partial x} = 10^{-4} \left[\frac{3}{2} x + \frac{1}{2} - \frac{y}{2} + \frac{1}{2} y \right] \\ &= 10^{-4} \left[\frac{3}{2} x + \frac{1}{2} \right] \left(= 2 \times 10^{-4} \text{ @ P} \right) \end{aligned}$$

Stress: $\underline{\sigma} = \underline{D} \underline{\epsilon}$

$$\begin{aligned} \sigma_x &= \frac{E}{1-\nu^2} (\epsilon_x + \nu \epsilon_y) = \frac{200 \times 10^3}{1-0.3^2} \left(\frac{3}{4} + 0.3 \times \frac{3}{4} \right) \times 10^{-4} \\ &= 21.43 \text{ N/mm}^2 \end{aligned}$$

$$\sigma_y = \frac{E}{1-\nu^2} (\epsilon_y + \nu \epsilon_x) = 21.43 \text{ N/mm}^2$$

$$\begin{aligned} \tau_{xy} &= \frac{E}{(1-\nu^2)} \frac{(1-\nu)}{2} \gamma_{xy} = \frac{E}{2(1+\nu)} \gamma_{xy} = \frac{200 \times 10^3}{2(1+0.3)} \times 2 \times 10^{-4} \\ &= 15.38 \text{ N/mm}^2 \end{aligned}$$

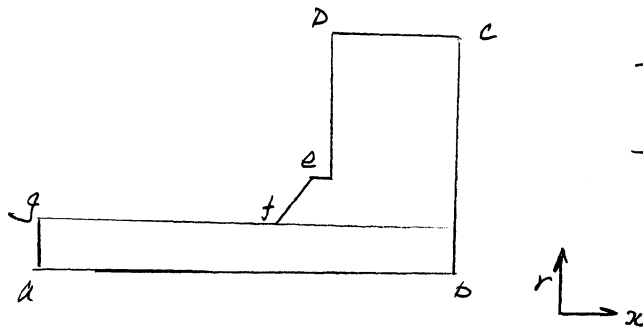
(c) Consistent mass matrix \underline{M} (where $\underline{M} \dot{\underline{d}} + \underline{K} \underline{d} = \underline{P}$) is obtained by calculating the kinetic energy of the element using the same shape functions as used for the displacement field (and stiffness matrix \underline{K})

Hence
$$\underline{M} = \int_V \underline{N}^T \rho \underline{N} dV = \rho \int_A \underline{N}^T \underline{N} dA \text{ for a 2D element}$$

3

(a)

(i)



- Two dimensional

- axisymmetric

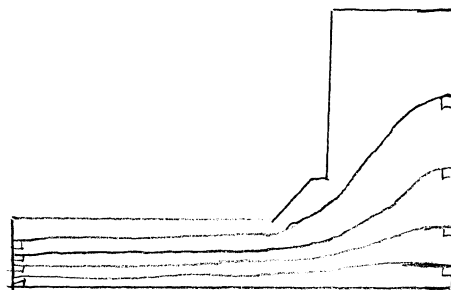
Boundary ab - $T = 50^\circ\text{C}$

Boundary bc - $\frac{\partial T}{\partial x} = 0$

Boundary c-d-e-f-g - $T = 0^\circ\text{C}$

Boundary ga - $\frac{\partial T}{\partial x} = 0$

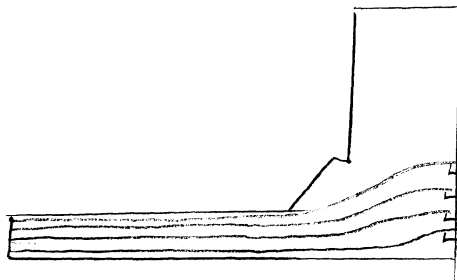
(ii)



← contours normal to this plane

not equally spaced because of radial direction

(iii)



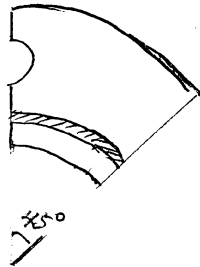
(iv) Need to apply convection boundary conditions and heat transfer coefficients are needed.

Flux boundary

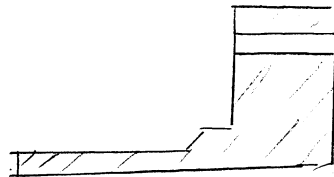
$$f = k \frac{\partial T}{\partial r} = h (T_{fl} - T_s)$$

where T_{fl} is the temperature of the fluid and T_s is the temperature of the pipe surface.

(b) (i) Need to model the section in three dimension, but only need to model $1/16$ of the section by taking into account of the symmetry.



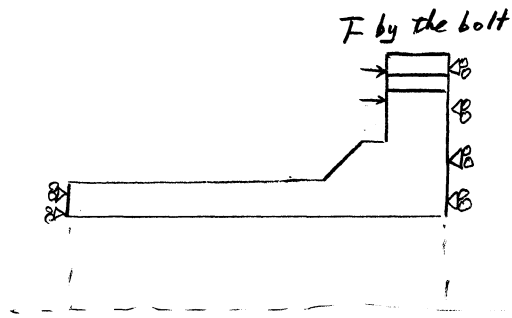
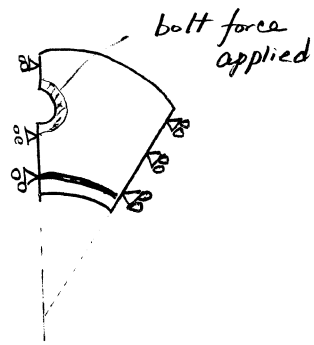
Cross-sectional view



Cross-section in longitudinal direction



3D view



(11) The reduced element uses smaller number of integration points to calculate the stiffness matrix.

Advantages

- improve the accuracy of the results by offsetting the overstiffness associated with compatible elements based on assumed displacement field
- computationally faster because of less calculation to determine the stiffness matrix

Limitations

- A spurious mode which has no resistance to nodal loads may activate.

307 Qu. 4

- (a) $t =$ thickness
 $A =$ area of whole mesh
 $P_x, P_y =$ components of distributed load
 $n_j =$ shape functions
 ($n_j = 1$ @ node j , $n_j = 0$ at all other nodes)

(b) $P_x = 0 \quad \therefore \quad P_{Ax} = 0 \quad P_y = -Pg$

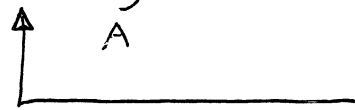
$$\begin{aligned}
 P_{Ay} &= t \int_A -Pg n_A dA & n_A &= 1 - 10x - 10y \\
 & & & (x, y \text{ in metres}) \\
 & & & \text{Area } A: \quad y = \frac{1}{10}, \quad x = \frac{1}{10} - y \\
 &= -tPg \int_{y=0}^{\frac{1}{10}} \int_{x=0}^{\frac{1}{10}-y} (1 - 10x - 10y) dx dy \\
 &= -tPg \int_{y=0}^{\frac{1}{10}} \left[x - 5x^2 - 10xy \right]_{x=0}^{x=\frac{1}{10}-y} dy \\
 &= -tPg \int_0^{\frac{1}{10}} \left(\frac{1}{10} - y - 5\left(\frac{1}{10} - y\right)^2 - 10\left(\frac{1}{10} - y\right)y \right) dy \\
 &= -tPg \int_0^{\frac{1}{10}} \left(\frac{1}{10} - y - \frac{5}{100} + 5 \times \frac{2}{10} y - 5y^2 - y + 10y^2 \right) dy \\
 &= -tPg \int_0^{\frac{1}{10}} \left(\frac{1}{20} - y + 5y^2 \right) dy \\
 &= -tPg \left[\frac{y}{20} - \frac{y^2}{2} + \frac{5}{3} y^3 \right]_0^{\frac{1}{10}}
 \end{aligned}$$

3D7 Qn. 4 (cont.)

$$P_{AY} = -t\rho g \left\{ \frac{1}{200} - \frac{1}{200} + \frac{5}{3000} \right\}$$

$$= -\frac{1}{1000} \times 2000 \times 10 \times \frac{5}{3000} = -\frac{1}{30} \text{ N}$$

$$P_{JY} = 2t \int -\rho g n_J dA \quad n_J = 10y$$



Elements ABJ and JBI have equal contributions

$$P_{JY} = -2t\rho g \int_0^{\frac{1}{10}} \int_0^{\frac{1}{10}-y} 10y \, dx \, dy$$

$$= -2t\rho g \int_0^{\frac{1}{10}} 10 [xy]_0^{\frac{1}{10}-y} \, dy$$

$$= -2t\rho g \int_0^{\frac{1}{10}} 10 \left(\frac{1}{10} - y\right) y \, dy$$

$$= -2t\rho g \int_0^{\frac{1}{10}} y - 10y^2 \, dy$$

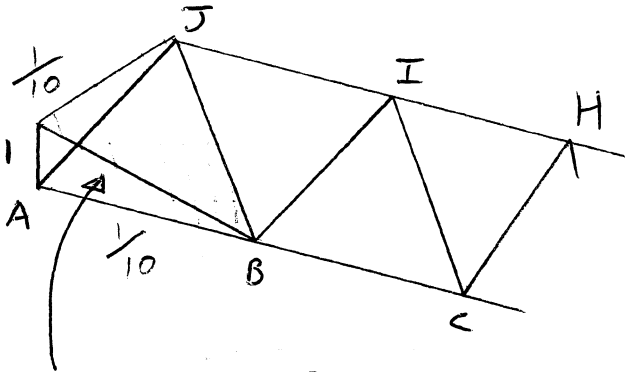
$$= -2t\rho g \left[\frac{y^2}{2} - 10\frac{y^3}{3} \right]_0^{\frac{1}{10}}$$

$$= -2 \times \frac{1}{1000} \times 2000 \times 10 \left\{ \frac{1}{200} - \frac{1}{300} \right\}$$

$$= -\frac{2}{30} \text{ N}$$

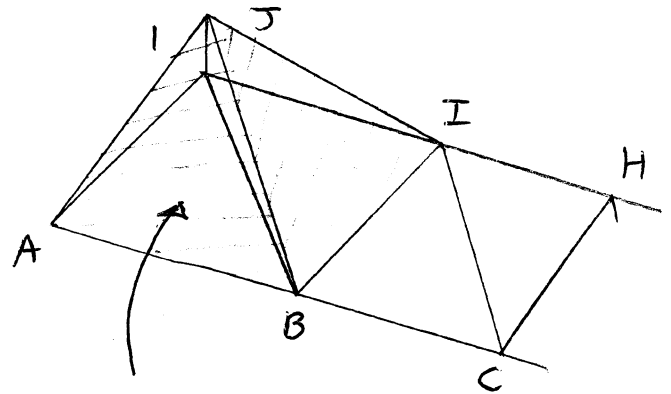
3D7 Qu. 4 (cont.)

Alternatively find P_{AY} and P_{JY} from the volume of the pyramidal shape functions:



$$\begin{aligned} \text{volume} &= \frac{1}{3} \left(\frac{1}{10}\right)^2 \frac{1}{2} \\ &= \frac{1}{600} \end{aligned}$$

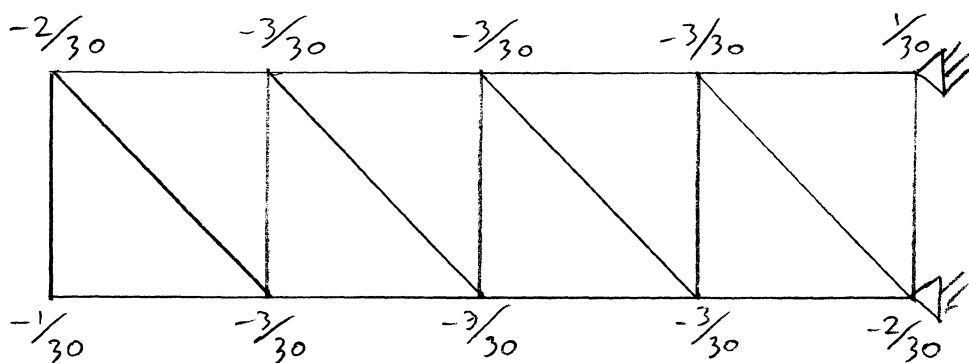
$$\begin{aligned} \therefore P_{AY} &= -\rho g t \times \frac{1}{600} \\ &= -2000 \times 10 \times \frac{1}{1000} \times \frac{1}{600} \\ &= -\frac{1}{30} N \end{aligned}$$



$$\begin{aligned} \text{volume} &= \frac{1}{3} \left(\frac{1}{10}\right)^2 \\ &= \frac{1}{300} \end{aligned}$$

$$\begin{aligned} \therefore P_{JY} &= -\rho g t \times \frac{1}{300} \\ &= -\frac{2}{30} N \end{aligned}$$

(c) Hence find P_{jY} for all nodes:



(all in N)

$$\begin{aligned} \text{Check total} &= -(2 \times 1 + 2 \times 2 + 6 \times 3) / 30 = -\frac{4}{5} N \\ &= -\rho g t A = -2000 \times 10 \times \frac{1}{1000} \times \frac{1}{10} \times \frac{4}{10} = -\frac{4}{5} N \end{aligned}$$

(d) Constant strain triangles - not good for linear stress distribution due to bending. Could improve mesh density but better to use higher order elements e.g. 6 node LSTs