

ENGINEERING TRIPOS PART IIA

Friday 12 May 2006 2.30 to 4.00

Module 3C4

MACHINE DESIGN - TRANSMISSIONS

*Answer not more than **three** questions.*

All questions carry the same number of marks.

*The **approximate** percentage of marks allocated to each part of a question is indicated in the right margin.*

Attachments:

Special datasheet (10 pages).

STATIONERY REQUIREMENTS

Single-sided script paper

SPECIAL REQUIREMENTS

Engineering Data Book

CUED approved calculator allowed

Supplementary pages: One extra copy of Fig. 3 (Question 3).

You may not start to read the questions printed on the subsequent pages of this question paper until instructed that you may do so by the Invigilator

1 (a) A cam is required to lift a roller follower according to a specified lift curve $y = f(\theta)$, where y is the lift and θ is the cam rotation angle. Outline the difficulty associated with deriving the required cam shape, and describe a possible solution. [15%]

(b) Figure 1 shows a cam rotating at constant angular velocity ω lifting a follower pivoted at O. Point A on the follower is directly above the centre of rotation of the cam and is distance $6a$ from O. The cam radius r as a function of angular position ϕ is

$$r = \frac{15}{4}a + \frac{5}{4}a \sin(2\phi - \pi/2).$$

The follower has mass m centred at G and moment of inertia ma^2 about G, where G is $4a$ from O. A spring at O exerts a restoring torque Q on the follower. The follower AO is horizontal and at the top of its travel when $\phi = \pi/2$, as shown in the figure. For this position:

- (i) show that the radius of curvature R of the cam at the point of contact is $5a/2$; (Results in the Mechanics Data Book may be used without proof.) [20%]
- (ii) sketch the equivalent mechanism of the cam and follower; [20%]
- (iii) find an expression, in terms of m , a and ω , for the minimum restoring torque Q needed to maintain contact between the cam and the follower. Gravity and friction are negligible. [45%]

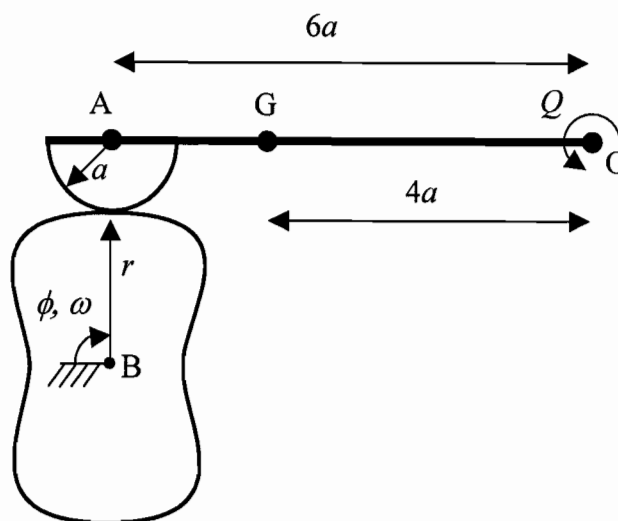


Fig. 1

2 Figure 2 shows the layout (not drawn to scale) of a rubber belt drive from a motor drive shaft to a pulley on the drum of a washing machine. The tensions in the belt on the tight and slack sides are T_1 and T_2 respectively. The drive shaft and drum pulley have radii R and $20R$ respectively, and their centres are a fixed distance $38R$ apart. The belt and drive shaft have grooves with 90° included angle, while the drum pulley has a flat contact area, as illustrated in the cross-sections of Fig. 2. Belt inertia effects can be ignored.

(a) Explain why there might be grooves on the belt and drive shaft, but not on the drum pulley. [10%]

(b) Show that when the belt is on the point of slipping around the total length of contact with the drive shaft, the ratio of belt tensions is given by

$$\frac{T_1}{T_2} = \exp(\mu' \theta_c)$$

where μ' is the effective limiting friction coefficient and θ_c is the angle of contact between the drive shaft and the belt. [30%]

(c) Derive an expression for the maximum torque that can be supplied by the drive shaft before complete slip, in terms of R , T_1 and the limiting friction coefficient μ between the contacting surfaces of the drive shaft and the belt. [30%]

(d) Sketch the variation of tension along the length of the belt for the case when the driving torque is well below that required for complete slip on the drive shaft. Give special attention to the regions of the belt in contact with the drive shaft and with the drum pulley. [30%]

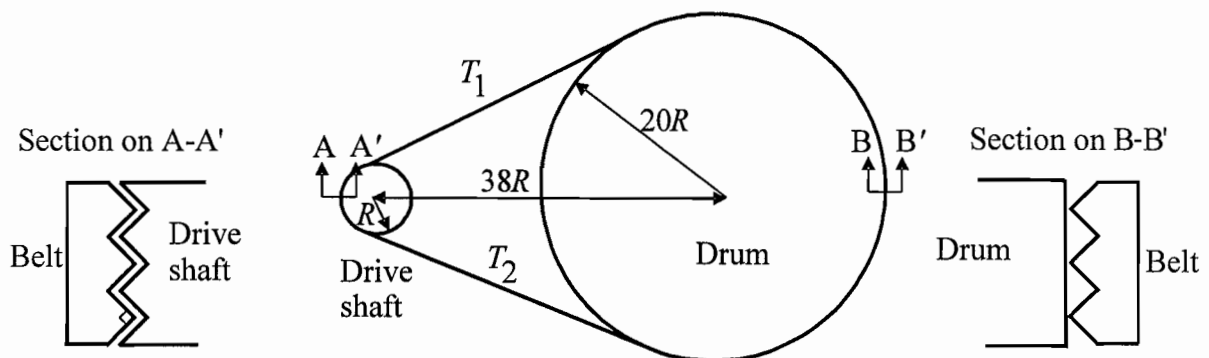


Fig. 2

(TURN OVER)

3 (a) The powertrain of a typical passenger car consists of an internal combustion engine and a gearbox with manually selectable fixed ratios. Explain why a range of gear ratios is provided. [20%]

(b) A hydrostatic motor is used to drive an agricultural vehicle. The characteristics of the motor are given in Fig. 3(a). The output shaft of the motor drives the vehicle wheels, which are of radius 0.5 m, via a gear ratio G equal to 10, where G is the motor shaft angular velocity divided by the wheel angular velocity. The force F resisting the motion of the vehicle is given by

$$F = 500 + 100 V$$

where F is in Newtons and the vehicle speed V is in m s^{-1} .

(i) Determine the vehicle speed at which the motor operates at greatest efficiency, and state the corresponding value of motor efficiency. [40%]

(ii) The motor is driven by a swash plate pump with characteristics given in Fig. 3(b). Determine the overall efficiency of the transmission when the gear ratio G is equal to 10 and the vehicle speed V is equal to 5 m s^{-1} . [15%]

(iii) Estimate the gear ratio G that allows the *motor* to operate at greatest efficiency when the vehicle speed V is equal to 5 m s^{-1} . [25%]

[Note: a loose copy of Fig. 3 is provided and should be handed in with your answer.]

(cont.)

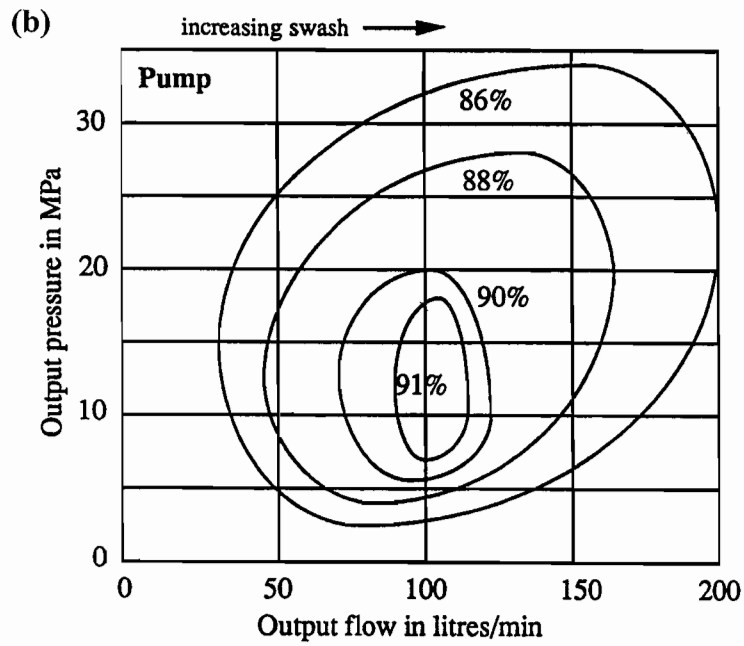
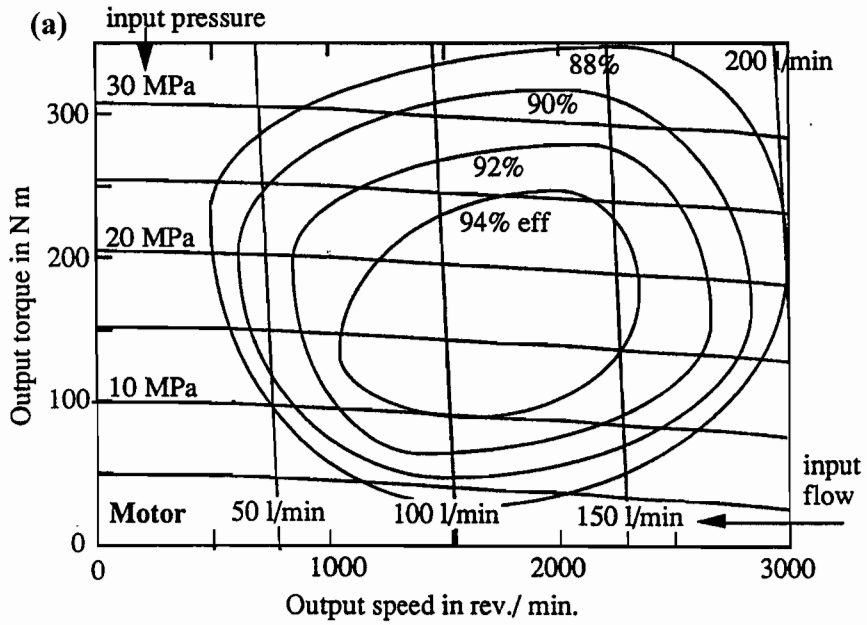


Fig. 3

(TURN OVER

4 (a) In the form of a table, compare the performance of deep groove ball bearings, cylindrical roller bearings, taper roller bearings and spherical roller bearings in terms of their ability to accommodate radial load, axial load, angular misalignment, and axial displacement. [20%]

(b) Calculate the life (in revolutions) of a taper roller bearing type 33112 when the equivalent radial load is 10 kN, the oil viscosity is $8 \text{ mm}^2 \text{ s}^{-1}$ and the rotation speed is 1000 revolutions per minute. The reliability is required to be 95%. [25%]

(c) Figure 3 shows a rotating shaft supported by two taper roller bearings. Bearing A has axial stiffness 50 MN m^{-1} . Bearing B has axial stiffness 25 MN m^{-1} . External axial and radial forces P_a and P_r can be applied to the shaft. The shaft and bearings are initially assembled with zero preload and zero axial clearance.

(i) State the disadvantages of having zero preload when external axial force P_a is applied to the rotating shaft. What additional problem can arise when external radial force P_r is applied to the shaft? [20%]

(ii) Determine the minimum preload force and the corresponding preload displacement necessary to ensure that there is no axial clearance in either bearing when an external axial force P_a of 10 kN is applied to the shaft in the direction shown in the figure. [35%]

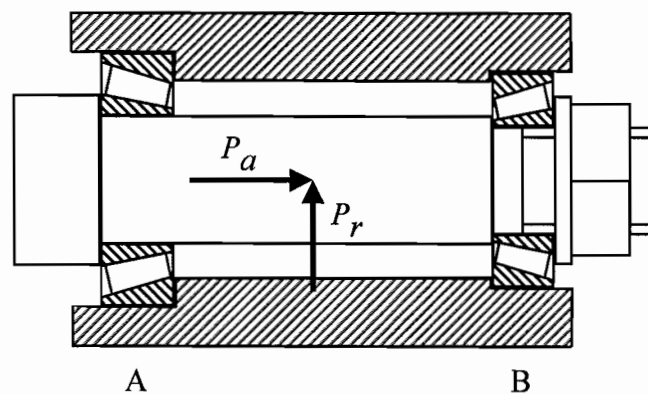
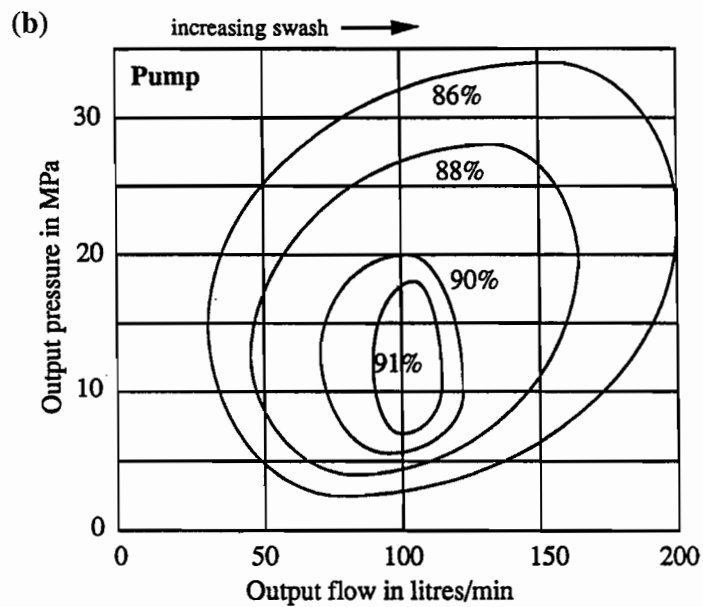
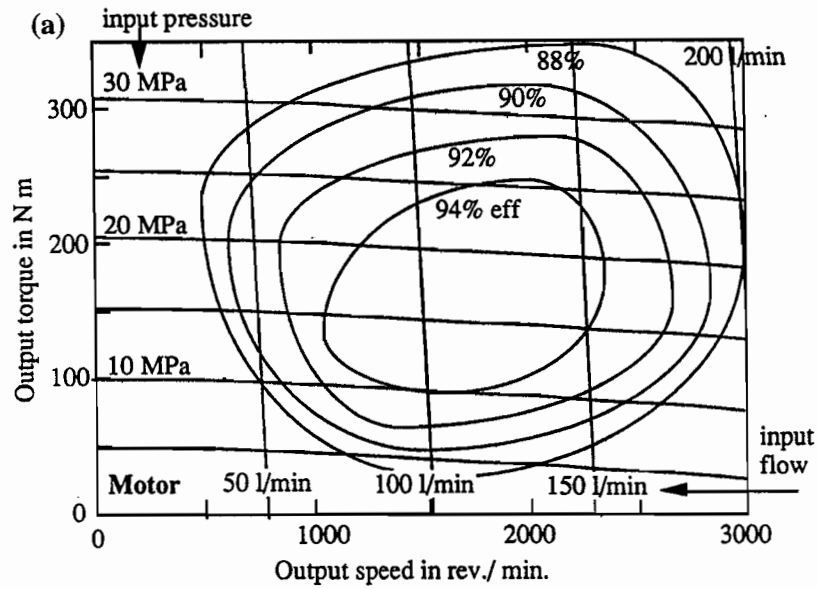


Fig. 4

END OF PAPER

ENGINEERING TRIPOS PART IIA
 Friday 12 May 2006 2.30 to 4.00
 Module 3C4
 MACHINE DESIGN – TRANSMISSIONS

Candidate number: _____



Working sheet for Q3
 (should be handed in with your answer)

ENGINEERING TRIPOS Part IIA

Modules 3C3 and 3C4 Data Sheet

HYDRODYNAMIC LUBRICATION

Viscosity: temperature and pressure effects

$$\text{Vogel formula } \eta = \eta_0 \exp\left\{\frac{b}{T + T_c}\right\}$$

$$\text{Barus equation } \eta = \eta_0 \exp\{\alpha p\}$$

$$\text{Roelands equation } \eta = \eta_0 \exp\left\{\left[9.67 + \ln \eta_0\right] \left[\left(1 + \frac{p}{p_0^*}\right)^\beta - 1\right]\right\}$$

Viscous pressure flow

Rate of flow q_x per unit width of fluid of viscosity η down a channel of height h due to

$$\text{pressure gradient, } q_x = -\frac{h^3}{12\eta} \frac{dp}{dx}$$

Reynolds' Equation for a steady configuration

$$\text{1-D flow: } \frac{dp}{dx} = 12\eta\bar{U} \left\{ \frac{h - h^*}{h^3} \right\}$$

\bar{U} is the entraining velocity so that $|\bar{U}h^*|$ is flow per unit width through the contact.

$$\text{2-D flow: } \frac{\partial}{\partial x} \left\{ \frac{h^3}{\eta} \frac{\partial p}{\partial x} \right\} + \frac{\partial}{\partial y} \left\{ \frac{h^3}{\eta} \frac{\partial p}{\partial y} \right\} = 12\bar{U} \frac{\partial h}{\partial x}$$

Hydrodynamic lubrication of discs

$$\frac{h}{R} = C \frac{\eta\bar{U}}{W'} \text{ where } R \text{ is the reduced or effective radius and } W' \text{ the load per unit length}$$

$$C_{\min} = 4.00 \text{ for half Sommerfeld boundary conditions}$$

$$C_{\min} = 4.89 \text{ for half Reynolds' boundary conditions}$$

ELASTIC CONTACT STRESS FORMULAE

Suffixes 1, 2 refer to the two bodies in contact.

Effective curvature $\frac{1}{R} = \frac{1}{R_1} + \frac{1}{R_2}$

where R_1, R_2 are the radii of curvature of the two bodies (convex positive).

Contact modulus $\frac{1}{E^*} = \frac{1-\nu_1^2}{E_1} + \frac{1-\nu_2^2}{E_2}$

where E_1, E_2 and ν_1, ν_2 are Young's moduli and Poisson's ratios.

	<u>Line contact</u>	<u>Circular contact</u>
	(width $2b$; load W' per unit length)	(diameter $2a$; load W)
Semi contact width or contact radius	$b = 2 \left\{ \frac{W'R}{\pi E^*} \right\}^{1/2}$	$a = \left\{ \frac{3WR}{4E^*} \right\}^{1/3}$
Maximum contact pressure ("Hertz stress")	$p_0 = \left\{ \frac{W'E^*}{\pi R} \right\}^{1/2}$	$p_0 = \frac{1}{\pi} \left\{ \frac{6WE^{*2}}{R^2} \right\}^{1/3}$
Approach of centres	$\delta = \frac{2W'}{\pi} \left[\frac{1-\nu_1^2}{E_1} \left\{ \ln \left(\frac{4R_1}{b} \right) - \frac{1}{2} \right\} + \frac{1-\nu_2^2}{E_2} \left\{ \ln \left(\frac{4R_2}{b} \right) - \frac{1}{2} \right\} \right]$	$\delta = \frac{a^2}{R} = \frac{1}{2} \left\{ \frac{9}{2} \frac{W^2}{E^{*2} R} \right\}^{1/3}$
Mean contact pressure	$\bar{p} = \frac{W'}{2b} = \frac{\pi}{4} p_0$	$\bar{p} = \frac{W}{\pi a^2} = \frac{2}{3} p_0$
Maximum shear stress	$\tau_{\max} = 0.300 p_0$ at $(x = 0, z = 0.79b)$	$\tau_{\max} = 0.310 p_0$ at $(r = 0, z = 0.48a)$ for $\nu = 0.3$
Maximum tensile stress	zero	$\frac{1}{3}(1-2\nu)p_0$ at $(r = a, z = 0)$

Mildly elliptical contacts

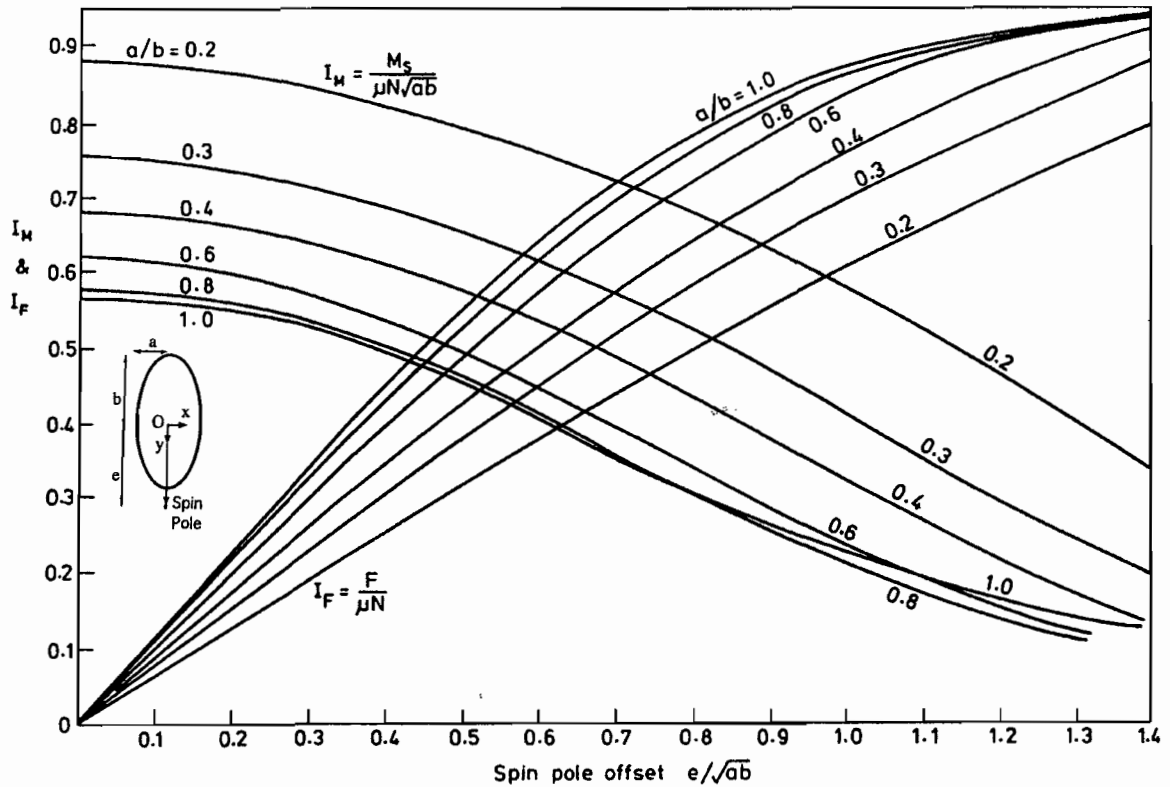
If the gap at zero load is $h = \frac{1}{2}Ax^2 + \frac{1}{2}By^2$, and $0.2 < A/B < 5$

Ratio of semi-axes $b/a \cong (A/B)^{2/3}$

To calculate the contact **area** or Hertz **stress** use the circular contact equations with $R = (AB)^{-1/2}$ or better $R_e = [AB(A+B)/2]^{-1/3}$.

For **approach** use circular contact equation with $R = (AB)^{-1/2}$ (**not** R_e)

Hertzian contact frictional losses



INVOLUTE GEARING

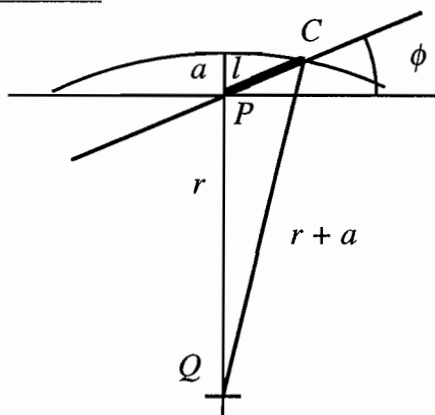
Spur gears

pitch cylinder radii r
 base cylinder radii r_b
 addendum cylinder radii r_a
 number of teeth N
 addendum $a = r_a - r$
 pressure angle ϕ

} with suffix 1 or 2

circumferential pitch $p = 2\pi r/N$
 base pitch $p_b = p \cos \phi$
 module $m = p/\pi = 2r/N$
 ratio of contact r_c
 radius of curvature at pitch point $\rho = r \sin \phi$

Path of contact



$$l = \left\{ r^2 \sin^2 \phi + a(2r + a) \right\}^{1/2} - r \sin \phi$$

For a standard 20° spur wheel with N teeth of module m this becomes

$$\frac{l}{m} = \left(0.02924N^2 + N + 1 \right)^{1/2} - 0.1710N$$

Standard tooth forms

Addendum $a = m$, Dedendum $= \frac{7}{6}m$, pressure angle $= 20^\circ$.

Modules:	0.3 – 1.0 mm in 0.1 mm steps
1.0 – 4.0 mm in 0.25 mm steps	4.0 – 7.0 mm in 0.5 mm steps
7.0 – 16.0 mm in 1.0 mm steps	16.0 – 24.0 mm in 2.0 mm steps
24.0 – 45.0 mm in 3.0 mm steps	45.0 – 75.0 mm in 5.0 mm steps

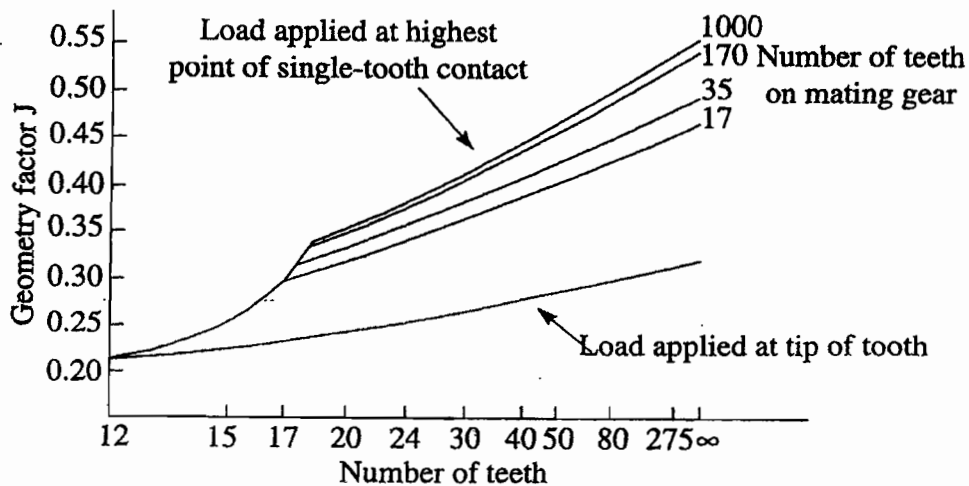
Friction in spur gears

$$\frac{\text{average friction loss}}{\text{power transmitted}} \approx \mu\pi \left\{ \frac{1}{N_1} + \frac{1}{N_2} \right\}$$

Tooth failure

Allowable bending stress σ_b according to AGMA guidelines given by $\sigma_b = \frac{P'_T}{Jm}$

where P'_T is force per unit face-width acting tangentially to pitch circle and J given in the figure below for 20° spur gears. Typical values of σ_b shown in table.



Typical allowable tooth stresses (AGMA)

Material	Condition	Bending fatigue strength σ_b (MPa)	Surface fatigue strength σ_s (MPa)
Steel	Through hardened and tempered	170-390	590-1200
	Carburised and case hardened	380-480	1250-1550
Cast iron	As cast	69-90	450-590
Nodular iron	Quenched, annealed and tempered	150-300	500-800
Malleable iron	Pearlitic	70-145	500-650

EPICYCLIC SPEED RULE

$$\omega_s = (1 + R)\omega_c - R\omega_a \quad \text{where } R = \frac{A}{S}$$

ROLLING ELEMENT BEARINGS

Fatigue life

$$L = a_1 a_{23} (C/P)^p \quad p = 3 \text{ for ball and } 10/3 \text{ for roller bearings}$$

Fatigue probability %	10	5	4	3	2	1
Life adjust factor a_1	1	0.62	0.53	0.44	0.33	0.21

Minimum radial load F_{rm}

$$\text{For a ball bearing } F_{rm} = k_r \left(\frac{vn}{1000} \right)^{2/3} \left(\frac{d_m}{100} \right)^2$$

$$\text{For a roller bearing } F_{rm} = k_r \left(6 + \frac{4n}{n_r} \right) \left(\frac{d_m}{100} \right)^2$$

F_{rm} is the minimum radial load in N, d_m is the mean bearing diameter in mm, v is the kinematic viscosity in mm^2s^{-1} , n the speed in rpm and n_r the limiting speed for oil lubrication. k_r is typically 25 for ball bearings and 150 for roller bearings.

Bearing choice

The information on the following pages concerning minimum loads, viscosities and standard bearing sizes and ratings is extracted from the SKF General Bearing Catalogue and is copied with permission. It is SKF copyright and is not to be further reproduced.

Required viscosities and the effect of viscosity ratio on a_{23}

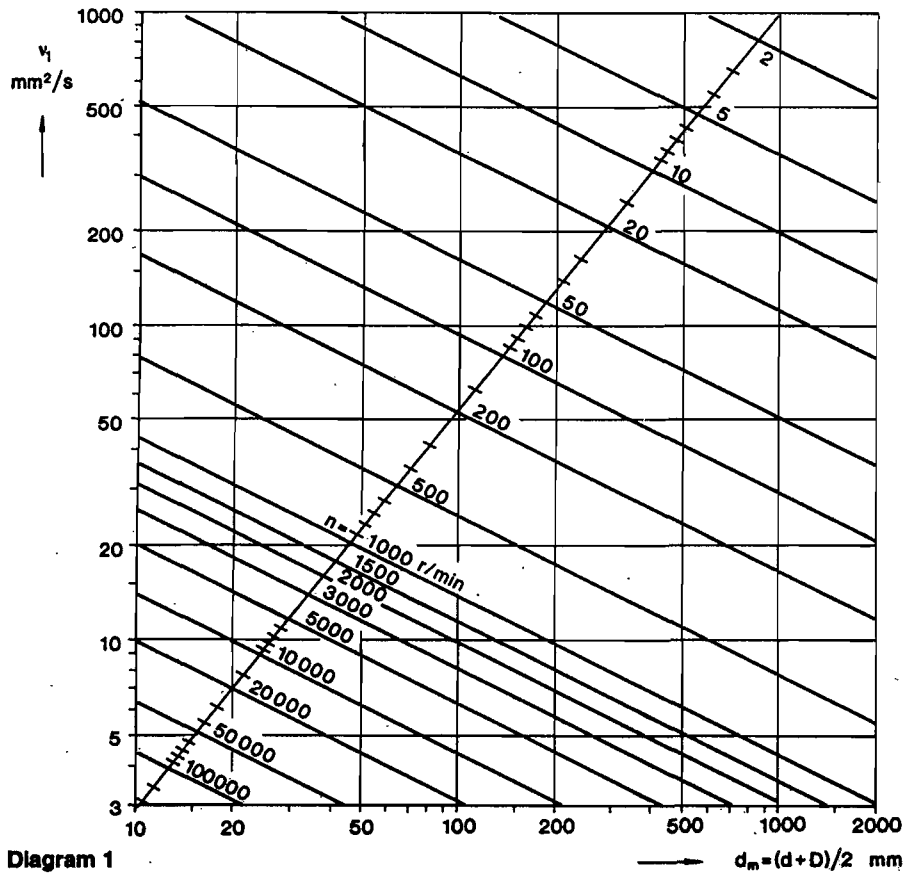


Diagram 1

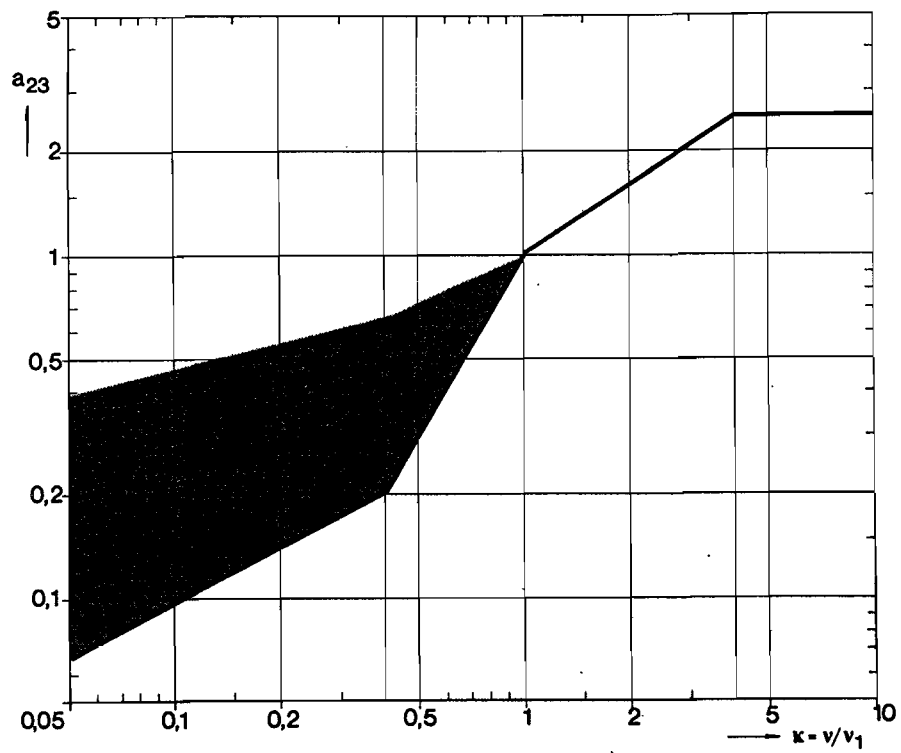
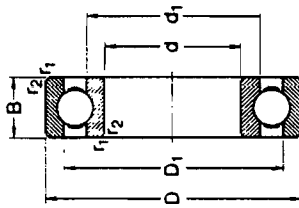
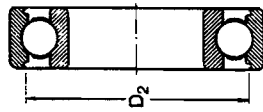


Diagram 3

**Deep groove ball bearings
single row
d 35-55 mm**



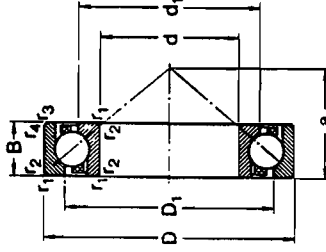
With full outer
ring shoulders



With recessed outer
ring shoulders

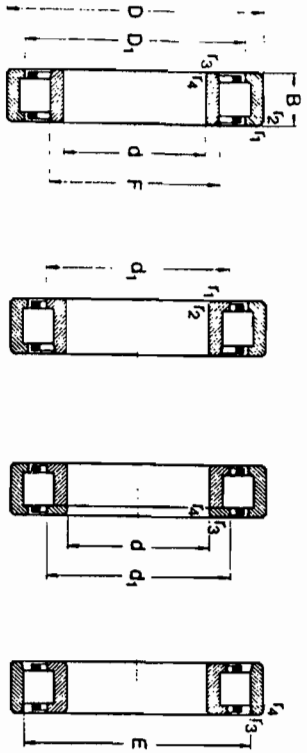
Principal dimensions	Basic load ratings			Fatigue load limit P_u	Speed ratings Lubrication grease oil	Mass	Designation
	d	D	B				
35	47	7	4 750	3 200	166	13 000	61807
	55	10	9 560	6 200	290	11 000	61907
	62	9	12 400	8 150	375	10 000	16007
	62	14	15 900	10 200	440	10 000	6007
	72	17	25 500	15 300	655	9 000	6207
	80	21	33 200	19 000	815	8 500	6307
	100	25	55 300	31 000	1 290	7 000	6407
	52	7	4 940	3 450	186	11 000	61808
	62	12	13 800	9 300	425	10 000	61908
	68	9	13 300	9 150	440	9 500	16008
	68	15	16 800	11 600	490	9 500	6008
	80	18	30 700	19 000	800	8 500	6208
	90	23	41 000	24 000	1 020	7 500	6308
	110	27	63 700	36 500	1 530	6 700	6408
	45	7	6 050	4 300	228	9 500	61809
	58	12	10 100	6 700	265	9 000	61909
	75	10	15 600	10 800	520	8 000	16009
	75	16	20 800	14 600	640	11 000	6009
	85	19	33 200	21 600	915	7 500	6209
	100	25	52 700	31 500	1 340	6 700	6309
	120	29	76 100	45 000	1 900	6 000	6409
	50	7	6 240	4 750	250	9 000	61810
	72	12	14 600	10 400	500	8 500	61910
	80	10	16 300	11 400	560	8 500	16010
	80	16	21 600	16 000	710	8 500	6010
	90	20	35 100	23 200	980	7 000	6210
	110	27	61 800	38 000	1 600	6 300	6310
	130	31	87 100	52 000	2 200	5 300	6410
	55	7	8 320	6 200	325	8 500	61811
	80	13	15 900	11 400	560	8 000	61911
	90	11	19 500	14 000	685	7 500	16011
	90	18	28 100	21 200	800	7 500	6011
	100	21	43 600	29 000	1 250	6 300	6211
	120	29	71 500	45 000	1 900	5 600	6311
	140	33	99 500	62 000	2 600	5 000	6411

**Angular contact ball bearings
single row
d 10-65 mm**



Principal dimensions	Basic load ratings			Fatigue load limit P_u	Speed ratings Lubrication grease oil	Mass	Designation
	d	D	B				
10	30	9	7 020	3 350	140	19 000	7200 BE
12	32	10	7 610	3 800	160	18 000	7201 BE
	37	12	10 600	5 000	208	17 000	7301 BE
15	35	11	8 940	4 800	204	17 000	7202 BE
	42	13	13 000	6 700	280	15 000	7302 BE
17	40	12	11 100	6 100	260	15 000	7203 BE
	47	14	15 900	8 300	355	13 000	7303 BE
20	47	14	14 000	8 300	355	12 000	7204 BE
	52	15	19 000	10 400	440	11 000	7304 BE
25	52	15	15 600	10 200	430	10 000	7205 BE
	62	17	26 000	15 600	655	9 000	7305 BE
30	62	16	23 800	15 600	655	8 500	7206 BE
	72	18	34 500	21 200	900	8 000	7306 BE
35	72	17	30 700	20 800	880	8 000	7207 BE
	80	21	39 000	24 500	1 040	7 500	7307 BE
40	80	18	36 400	26 000	1 100	7 000	7208 BE
	90	23	48 400	33 500	1 400	6 700	7308 BE
45	85	19	37 700	28 000	1 200	6 700	7209 BE
	100	25	60 500	41 500	1 730	6 000	7309 BE
50	90	20	39 000	30 500	1 280	6 000	7210 BE
	110	27	74 100	51 000	2 200	5 300	7310 BE
55	100	21	48 800	38 000	1 630	5 600	7211 BE
	120	28	85 200	60 000	2 550	4 800	7311 BE
60	110	22	57 200	45 500	1 930	5 000	7212 BE
	130	31	95 600	69 500	3 000	4 500	7312 BE
65	120	23	66 300	54 000	2 280	4 500	7213 BE
	140	33	108 000	80 000	3 350	4 300	7313 BE

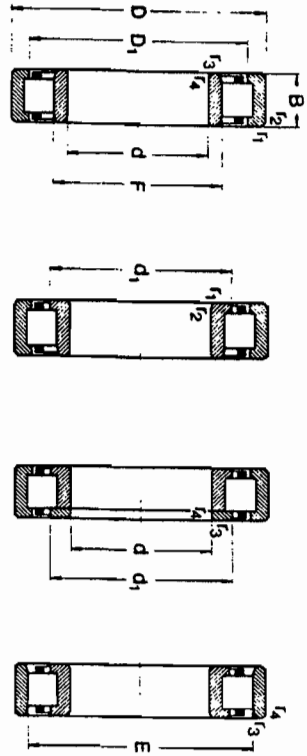
Cylindrical roller bearings single row d 40-45 mm



Principal dimensions	Type NU	Type NUJ	Type NUP	Type N	Basic load ratings		Fatigue load limit P_u	Speed ratings		Mass	Designation
					dynamic	static		Lubrication	grease		
d	D	B	C	C	C_0	P_u	r/min	r/min	kg	-	
mm	mm	mm	mm	mm	N	N	N	r/min	kg	-	

40 (cont.)	90	23	80 900	78 000	10 200	6 700	8 000	0.65	NU 308 EC
	90	23	80 900	78 000	10 200	6 700	8 000	0.67	NJ 308 EC
	90	23	80 900	78 000	10 200	6 700	8 000	0.68	NUP 308 EC
	90	23	80 900	78 000	10 200	6 700	8 000	0.64	N 308 EC
	90	33	112 000	120 000	15 300	6 300	7 500	0.94	NU 2308 EC
	90	33	112 000	120 000	15 300	6 300	7 500	0.96	NJ 2308 EC
	90	33	112 000	120 000	15 300	6 300	7 500	0.98	NUP 2308 EC
	110	27	96 800	90 000	11 600	6 000	7 000	1.30	NU 408
	110	27	96 800	90 000	11 600	6 000	7 000	1.30	NJ 408
	110	27	96 800	90 000	11 600	6 000	7 000	1.35	NUP 408
	45	16	4 600	52 000	6 300	9 000	11 000	0.26	NU 1009 EC
	85	19	60 500	64 000	8 150	6 700	8 000	0.43	NU 209 EC
	85	19	60 500	64 000	8 150	6 700	8 000	0.44	NJ 209 EC
	85	19	60 500	64 000	8 150	6 700	8 000	0.45	NUP 209 EC
	85	19	60 500	64 000	8 150	6 700	8 000	0.43	N 209 EC
	85	23	73 700	81 500	10 600	6 700	8 000	0.52	NU 2209 EC
	85	23	73 700	81 500	10 600	6 700	8 000	0.54	NJ 2209 EC
	85	23	73 700	81 500	10 600	6 700	8 000	0.55	NUP 2209 EC
	85	23	73 700	81 500	10 600	6 700	8 000	0.52	N 2209 EC
	100	25	99 000	100 000	12 900	6 300	7 500	0.90	NU 309 EC
	100	25	99 000	100 000	12 900	6 300	7 500	0.92	NJ 309 EC
	100	25	99 000	100 000	12 900	6 300	7 500	0.95	NUP 309 EC
	100	25	99 000	100 000	12 900	6 300	7 500	0.88	N 309 EC
	100	36	138 000	153 000	20 000	5 600	6 700	1.30	NU 2309 EC
	100	36	138 000	153 000	20 000	5 600	6 700	1.30	NJ 2309 EC
	100	36	138 000	153 000	20 000	5 600	6 700	1.35	NUP 2309 EC
	100	36	138 000	153 000	20 000	5 600	6 700	1.30	N 2309 EC
	120	29	106 000	102 000	13 400	5 600	6 700	1.65	NU 409
	120	29	106 000	102 000	13 400	5 600	6 700	1.65	NJ 409
	120	29	106 000	102 000	13 400	5 600	6 700	1.70	NUP 409
	120	29	106 000	102 000	13 400	5 600	6 700	1.65	N 409

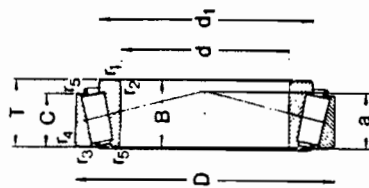
Cylindrical roller bearings single row d 50-55 mm



Principal dimensions	Type NU	Type NUJ	Type NUP	Type N	Basic load ratings		Fatigue load limit P_u	Speed ratings		Mass	Designation
					dynamic	static		Lubrication	grease		
d	D	B	C	C	C_0	P_u	r/min	r/min	kg	-	
mm	mm	mm	mm	mm	N	N	N	r/min	kg	-	

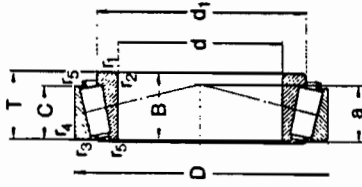
50	80	16	30 800	34 500	4 000	8 500	10 000	0.31	NU 1010
	80	20	64 400	69 500	8 800	6 300	7 500	0.48	NU 210 EC
	80	20	64 400	69 500	8 800	6 300	7 500	0.49	NJ 210 EC
	80	20	64 400	69 500	8 800	6 300	7 500	0.51	NUP 210 EC
	80	20	64 400	69 500	8 800	6 300	7 500	0.48	N 210 EC
	90	23	78 100	88 000	11 400	6 300	7 500	0.56	NU 2210 EC
	90	23	78 100	88 000	11 400	6 300	7 500	0.58	NJ 2210 EC
	90	23	78 100	88 000	11 400	6 300	7 500	0.59	NUP 2210 EC
	110	27	110 000	112 000	15 000	5 000	6 000	1.15	NU 310 EC
	110	27	110 000	112 000	15 000	5 000	6 000	1.15	NJ 310 EC
	110	27	110 000	112 000	15 000	5 000	6 000	1.20	NUP 310 EC
	110	27	110 000	112 000	15 000	5 000	6 000	1.15	N 310 EC
	110	40	161 000	186 000	24 500	5 000	6 000	1.70	NU 2310 EC
	110	40	161 000	186 000	24 500	5 000	6 000	1.75	NJ 2310 EC
	110	40	161 000	186 000	24 500	5 000	6 000	1.80	NUP 2310 EC
	110	40	161 000	186 000	24 500	5 000	6 000	1.80	N 2310 EC
	130	31	130 000	127 000	16 800	5 000	6 000	2.00	NU 410
	130	31	130 000	127 000	16 800	5 000	6 000	2.05	NJ 410
	130	31	130 000	127 000	16 800	5 000	6 000	2.05	NUP 410
	130	31	130 000	127 000	16 800	5 000	6 000	2.05	N 410
	150	18	57 200	69 500	8 300	7 000	8 500	0.40	NU 1011 EC
	100	21	84 200	95 000	12 200	6 000	7 000	0.66	NU 211 EC
	100	21	84 200	95 000	12 200	6 000	7 000	0.67	NJ 211 EC
	100	21	84 200	95 000	12 200	6 000	7 000	0.67	NUP 211 EC
	100	21	84 200	95 000	12 200	6 000	7 000	0.69	N 211 EC
	100	25	99 000	118 000	15 300	6 000	7 000	0.66	NU 2211 EC
	100	25	99 000	118 000	15 300	6 000	7 000	0.79	NJ 2211 EC
	100	25	99 000	118 000	15 300	6 000	7 000	0.81	NUP 2211 EC
	100	25	99 000	118 000	15 300	6 000	7 000	0.82	N 2211 EC
	120	29	138 000	143 000	18 600	4 800	5 600	1.45	NU 311 EC
	120	29	138 000	143 000	18 600	4 800	5 600	1.50	NJ 311 EC
	120	29	138 000	143 000	18 600	4 800	5 600	1.55	NUP 311 EC
	120	29	138 000	143 000	18 600	4 800	5 600	1.45	N 311 EC

Taper roller bearings
single row
d 35-50 mm



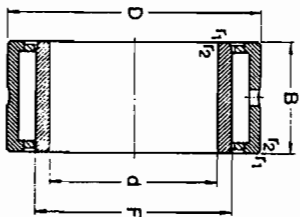
Principal dimensions	Basic load ratings			Fatigue load limit P_u	Speed ratings	Mass	Designation	Dimension Series to ISO 355
	d	D	T					
	mm	N	C	C ₀	r/min	kg	-	-
35 (cont.)	80 80 80	22,75 61 600 95 200	72 100 67 000 95 200	73 500 67 000 106 000	5 000 4 500 4 500	0,52 0,52 0,73	30307 31307 32307 B	2FB 7FB 2FE 5FE
40	68 75 80 80 80 85 90 90 90 90	19 26 19,75 24,75 32 33 25,25 25,25 35,25	52 800 79 200 61 600 74 800 105 000 121 000 85 800 73 700 117 000	71 000 104 000 68 000 86 500 132 000 150 000 95 000 81 500 140 000	5 300 5 000 4 800 4 800 4 300 4 500 4 000 4 000 4 000	0,27 0,51 0,42 0,53 0,77 0,90 0,72 1,00 1,10	32008 X 33108 30208 32208 33208 T2EE 040 30308 31308 32308 B	3CD 2CE 3DB 3DC 2DE 2EE 2FB 7FB 2FD 5FD
45	75 80 85 85 90 95 100 100 100 108	20 26 20,75 24,75 32 36 27,25 27,25 38,25	58 300 84 200 66 000 73 700 108 000 147 000 108 000 91 300 140 000	80 000 114 000 76 500 93 000 143 000 186 000 120 000 102 000 170 000	4 800 4 500 4 500 4 300 3 600 4 000 4 000 3 600 3 600	0,34 0,56 0,48 0,58 0,82 1,20 1,20 0,97 1,35	32009 X 33109 30209 32209 B 33209 T2ED 045 T2ED 046 30309 31309 32309 B	3CC 3CE 3DB 3DC 3DE 7FC 2ED 2EB 7FB 2FD 5FD
50	80 80 85 90 90 90 100 100 100 105	20 24 21,5 26 24,75 24,75 27,25 27,25 38,25	60 500 69 300 72 100 85 800 82 500 105 000 108 000 91 300 140 000	88 000 102 000 100 000 122 000 100 000 150 000 140 000 140 000 170 000	4 500 4 500 4 500 4 300 4 300 4 000 4 000 3 600 3 600	0,37 0,45 0,43 0,59 0,54 0,61 0,85 0,90 1,30	32010 X 33010 K-JLM 104948/K-JLM 104910 30210 33110 32210 B K-JM 205149/K-JM 205110 K-JM 205149/K-JM 205110 A T2ED 050 T7FC 050	3CC 2CE 3CE 3DB 3DC 3DE 2ED 7FC

Taper roller bearings
single row
d 50-65 mm

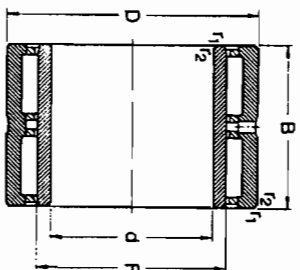


Principal dimensions	Basic load ratings			Fatigue load limit P_u	Speed ratings	Mass	Designation	Dimension Series to ISO 355
	d	D	T					
	mm	N	C <th>C₀</th> <td>r/min</td> <td>kg</td> <td>-</td> <td>-</td>	C ₀	r/min	kg	-	-
50 (cont.)	110 110 110	29,25 42,25 42,25	125 000 106 000 172 000	140 000 120 000 212 000	3 600 3 200 3 200	1,25 1,20 1,80	30310 31310 32310 B	2FB 7FB 2FD 5FD
55	90 90 95 100 100 100 110 115 120 120 120	23 23 27 27,5 26,75 26,75 39 34 31,5	78 100 60 900 89 700 89 700 106 000 101 000 138 000 125 000 142 000 198 000	112 000 116 000 137 000 156 000 129 000 127 000 190 000 232 000 183 000 163 000	4 000 4 000 3 600 3 600 3 800 3 600 3 400 3 400 3 200 2 800	0,56 0,56 0,67 0,88 0,70 0,83 0,87 1,20 1,60 1,55	K-JLM 506649/K-JLM 506610 32011 X 33011 30211 32211 B T2ED 055 T7FC 055 30311 31311 32311 B	3CC 2CE 3CE 3DB 3DC 3DE 7FC 2ED 2FB 2FD 5FD
60	95 95 95 100 110 110 115 115 125	23 24 27 30 28,75 28,75	82 500 84 200 91 300 117 000 99 000	122 000 132 000 143 000 170 000	3 800 3 600 3 600 3 400	0,59 0,62 0,71 0,88	32012 X K-JLM 508748/K-JLM 508710 33012 30212 33112 30212	4CC 2CE 3CE 3EB 3EC 3EE 5ED 2EE 7FC
65	100 100 110 110 120 120	23 23 28 28 32,75	84 200 96 800 123 000 142 000	126 000 157 000 208 000 203 000	3 400 3 400 3 200 3 000	0,63 0,78 1,05 1,15	32013 X 33013 K-JM 511946/K-JM 511910 30213 B 30213	4CC 2CE 3DE 3EB 3EC 5ED

**Needle roller bearings with flanges
with inner ring
d 40-65 mm**



Series NK(S), NA 49



Series NA 69

Principal dimensions	d	D	B	C	Basic load ratings		Fatigue load limit P_u	Speed ratings Lubrication grease oil	Mass	Designation
					dynamic	static C_0				
	mm				N	N	N	r/min	kg	
40	55	20	27	500	57 000	7 200	6 300	9 000	0.14	NKI 40/20
	55	30	40	200	93 000	12 000	6 300	9 000	0.22	NKI 40/30
	62	22	42	800	71 000	9 150	5 600	8 000	0.23	NA 4908
	62	40	67	100	125 000	16 000	5 600	8 000	0.43	NA 6908
	65	22	42	900	72 000	9 150	5 600	8 000	0.28	NK(S) 40
42	57	20	29	200	61 000	7 650	6 000	8 500	0.15	NKI 42/20
	57	30	41	800	98 000	12 900	6 000	8 500	0.22	NKI 42/30
45	62	25	38	000	78 000	10 000	5 600	8 000	0.23	NKI 45/25
	62	35	49	500	110 000	14 300	5 600	8 000	0.32	NKI 45/35
	68	22	45	700	78 000	10 000	5 300	7 500	0.27	NA 4909
	68	40	70	400	137 000	17 300	5 300	7 500	0.50	NA 6909
	72	22	44	600	78 000	10 000	5 000	7 000	0.34	NK(S) 45
50	68	25	40	200	88 000	11 200	5 300	7 500	0.27	NKI 50/25
	68	35	52	300	122 000	16 000	5 300	7 500	0.38	NKI 50/35
	72	22	47	300	85 000	11 000	5 000	7 000	0.27	NA 4910
	72	40	73	700	150 000	19 000	5 000	7 000	0.52	NA 6910
	80	28	62	700	104 000	13 700	4 500	6 300	0.52	NK(S) 50
55	72	25	41	800	96 500	12 200	4 800	6 700	0.27	NKI 55/25
	72	35	55	000	134 000	17 600	4 800	6 700	0.38	NKI 55/35
	80	25	57	200	106 000	13 700	4 500	6 300	0.40	NA 4911
	80	45	89	700	190 000	24 000	4 500	6 300	0.78	NA 6911
	85	28	68	000	114 000	15 000	4 300	6 000	0.56	NK(S) 55
60	82	25	44	000	95 000	12 000	4 300	6 000	0.40	NKI 60/25
	82	35	60	500	146 000	19 000	4 300	6 000	0.55	NKI 60/35
	85	25	60	500	114 000	14 600	4 300	6 000	0.43	NA 4912
	85	45	93	500	204 000	26 000	4 300	6 000	0.81	NA 6912
	90	28	68	200	120 000	15 600	4 000	5 600	0.56	NK(S) 60
65	90	25	61	600	120 000	15 300	4 000	5 600	0.46	NA 4913
	90	35	82	800	106 000	13 700	4 000	5 600	0.47	NKI 65/25
	90	45	73	700	163 000	21 600	4 000	5 600	0.66	NKI 65/35
	95	28	95	200	212 000	27 000	4 000	5 600	0.83	NA 6913
	95	45	70	400	132 000	17 000	3 800	5 300	0.64	NK(S) 65

Engineering Tripos Part IIA 2006

Module 3C4

Machine Design – Transmissions

1 (b) (iii) $Q = \frac{85}{7} \omega^2 a^2 m$

2 (c) $Q = T_1 R \left(1 - \exp \left(-\frac{2\sqrt{2}}{3} \mu \pi \right) \right)$

3 (b) (i) 9.2 m/s 92%

(ii) 76%

(iii) 15

4 (b) infinite

(c) (ii) 0.2 mm 3.3 kN