

Part IA Module 3C6 2008: crib

1(a) From data sheet, $EI \frac{\partial^2 w}{\partial x^4} + m \frac{\partial^2 w}{\partial t^2} = 0$

So if $w = u(x)e^{int}$, $u''' = f(t)$ where $f = \frac{m\omega^2}{EI}$

General solution $u = A\cos\omega x + B\sin\omega x + C\cosh\omega x + D\sinh\omega x$

At $x=0$: $w=0 \rightarrow A+C=0$

$w' = 0 \rightarrow \omega(B+D)=0$

At $x=L$: $w=0 \rightarrow A\cos\omega L + B\sin\omega L - A\cosh\omega L - B\sinh\omega L = 0$

$w' = 0 \rightarrow \omega\{-A\sin\omega L + B\cosh\omega L - A\sinh\omega L - B\cosh\omega L\} = 0$

For non-trivial solution (A, B not both zero) need $\det[\cdot] = 0$

$$\therefore (\cosh\omega L - \sinh\omega L)(\cosh\omega L + \sinh\omega L) = (\sin\omega L - \sinh\omega L)(-\sin\omega L - \sinh\omega L)$$

$$\therefore \cosh^2\omega L - 2\cosh\omega L\cosh\omega L + \cosh^2\omega L = \sinh^2\omega L - \sin^2\omega L$$

$$\therefore 2\cosh\omega L\cosh\omega L = 2, \text{ ie } \cosh\omega L\cosh\omega L = 1$$

(b) Start as above, but different boundary condition at $x=L$:

$$\left\{ \begin{array}{l} w=0 \rightarrow A\cos\omega L + B\sin\omega L - A\cosh\omega L - B\sinh\omega L = 0 \\ w''=0 \rightarrow \omega^2\{-A\sin\omega L - B\cosh\omega L - A\sinh\omega L - B\cosh\omega L\} = 0 \end{array} \right.$$

so $\det[\cdot] = 0 \rightarrow$

$$(\cosh\omega L - \sinh\omega L)(\sin\omega L + \sinh\omega L) = (\sin\omega L - \sinh\omega L)(\cosh\omega L + \cosh\omega L)$$

$$\therefore \cosh\omega L\sin\omega L + \cosh\omega L\sinh\omega L - \cosh\omega L\sin\omega L - \cosh\omega L\sinh\omega L$$

$$= \cosh\omega L\sin\omega L + \sin\omega L\cosh\omega L - \cosh\omega L\sinh\omega L - \sin\omega L\cosh\omega L$$

$$\therefore \cosh\omega L\sin\omega L = \sin\omega L\cosh\omega L$$

$$\therefore \tan\omega L = \tanh\omega L$$

(c)

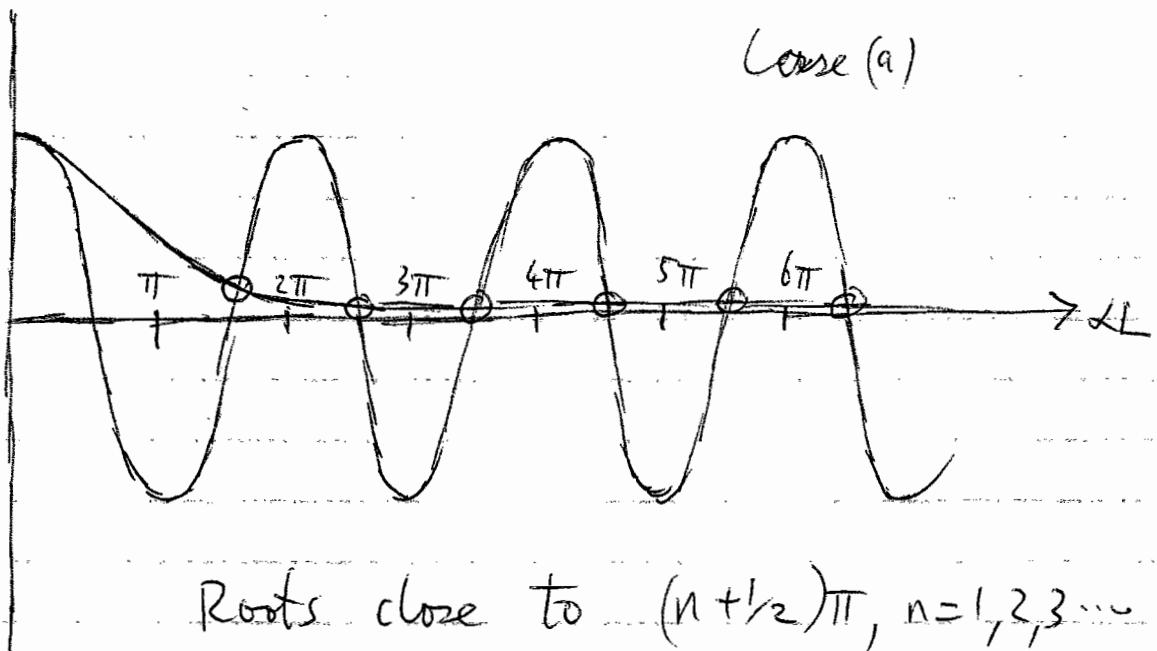
To check for interesting behaviour, rearrange as

$$(a) \quad \cosh\omega L = \frac{1}{\tanh\omega L}, \quad (b) \quad \tan\omega L = \tanh\omega L$$

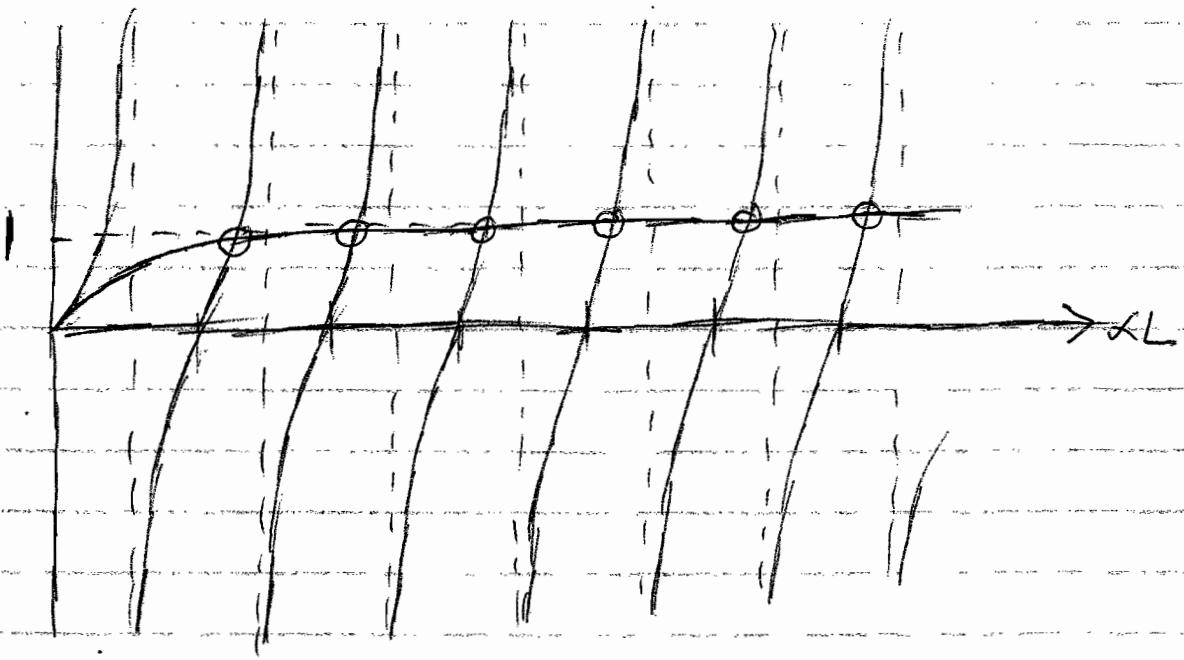
+ plot on matching scales

I (cont.)

Case (a)

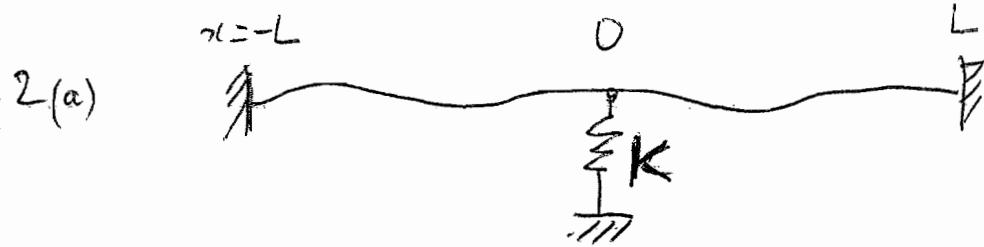


Roots close to $(n + \frac{1}{2})\pi$, $n=1, 2, 3, \dots$



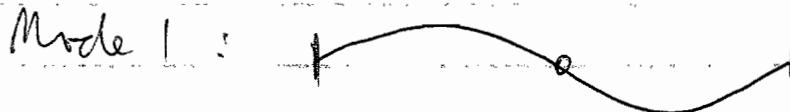
$\tanh \alpha L \rightarrow 1$ as αL increases, so roots are close to $(n + \frac{1}{4})\pi$

So interesting behavior is clear



System is symmetric in line $x=0$. So behavior must be unchanged when it is reflected in this line. Symmetric modes are identical, antisymmetric modes are the same except for a 180° phase reversal in the motion. Any other motion would change in a non-trivial way on reflection, so is not possible.

Antisymmetric modes have nodes at the spring, so are not influenced by it - they are the same as modes of a non-constrained string.



(c) For free string, $P \frac{d^2w}{dx^2} = m \frac{d^2w}{dt^2}$ (data sheet)

so if $w = u(x) e^{i\omega t}$, $u'' = -\frac{m\omega^2}{P} u = -k^2 u$ say

Then $u = A \cos kx + B \sin kx$ in general.

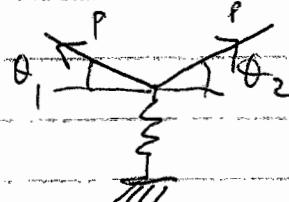
But antisymmetric, so $u = \sin kx$

$$u=0 \text{ at } x=L \rightarrow \sin kl = 0$$

$$\therefore k = \frac{n\pi}{L}, \text{ so } w = \sqrt{\frac{P}{m}} = \frac{n\pi}{L} \sqrt{\frac{P}{m}}$$

(b) At $x=0$ must have force balance

$$P \sin \theta_1 + P \sin \theta_2 = KW$$



2(b) cont. But θ_1, θ_2 small

$$\text{So } \sin \theta_1 \approx \theta_1 \approx -\frac{\partial w}{\partial x} \Big|_{x=0^-}$$

$$\left. \sin \theta_2 \approx \theta_2 \approx +\frac{\partial w}{\partial x} \right|_{x=0^+}$$

$$\therefore P \left[\frac{\partial w}{\partial x} \right]_{0^-}^{0^+} = Kw$$

For symmetric modes, let $w(x) = \sin k(x+L)$ $-L \leq x \leq 0$

with k as in (a) - This is a combination of $\sinh kL, \cosh kL$
which automatically satisfies $w=0$ at $x=-L$.

Now use b.c. at $x=0$:

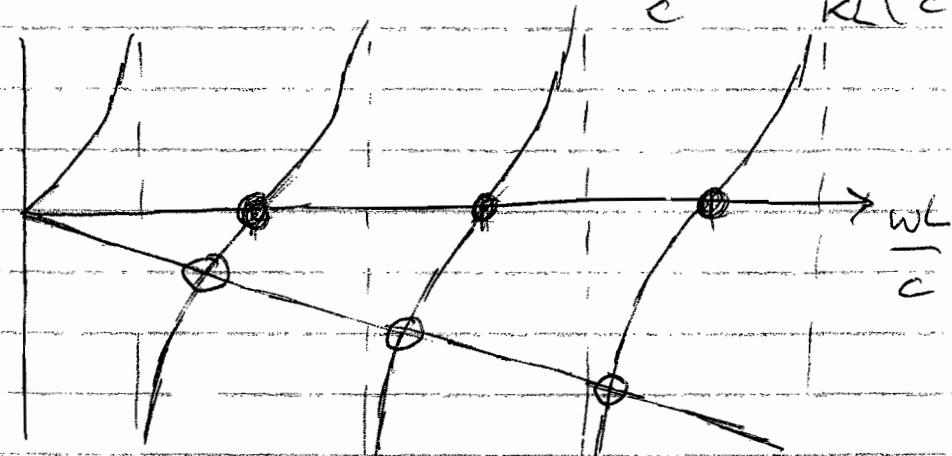
$$-2Pk \cosh kL = K \sin kL$$

$$\text{where } k = \omega/c$$

$$\therefore \tan \frac{\omega L}{c} = -\frac{2Pw}{Kc}$$

(c) From (a), antisymmetric frequencies satisfy $\frac{\omega L}{c} = n\pi$.

From (b), draw plots of $\tan \frac{\omega L}{c}$, $-\frac{2P}{Kc} \left(\frac{\omega L}{c} \right)^2$:



○ = symmetric root

◎ = anti-symmetric solution

2(c) (cont.)

(i) $K \rightarrow 0$ means the straight line tends towards a vertical slope, and so the roots tend towards the asymptotes of the tan function, ie to $(n - \frac{1}{2})\pi$, $n=1, 2, 3 \dots$. These are the frequencies for an unstrained string, as expected.

(ii) $K \rightarrow \infty$ means the straight line becomes horizontal, so the roots tend to the same values as for the antisymmetric modes. The spring has become a rigid constraint so it divides the string into 2 separate portions. The two modes

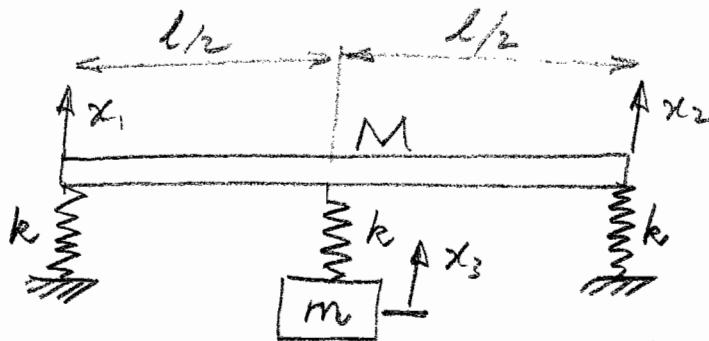


and can then be combined via sum and difference to give



at the same frequency.

3. (a)



$$KE: T = \frac{1}{2}m\dot{x}_3^2 + \frac{1}{2}M\left(\frac{\dot{x}_1 + \dot{x}_2}{2}\right)^2 + \frac{1}{2}I\left(\frac{\dot{x}_2 - \dot{x}_1}{l}\right)^2$$

$$\text{with } I = \frac{1}{12}Ml^2$$

$$\text{So } T = \frac{1}{2}m\dot{x}_3^2 + \frac{1}{8}M(\dot{x}_1^2 + \dot{x}_2^2 + 2\dot{x}_1\dot{x}_2)$$

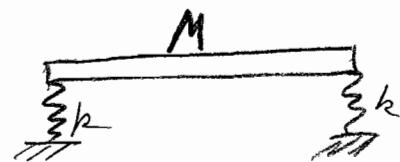
$$+ \frac{M}{24}(\dot{x}_2^2 + \dot{x}_1^2 - 2\dot{x}_1\dot{x}_2)$$

$$= \frac{1}{2}m\dot{x}_3^2 + \frac{1}{6}M(\dot{x}_1^2 + \dot{x}_2^2 + \dot{x}_1\dot{x}_2) //$$

$$PE: V = \frac{1}{2}kx_1^2 + \frac{1}{2}kx_2^2 + \frac{1}{2}k\left(\frac{x_1 + x_2}{2} - x_3\right)^2$$

$$= \frac{1}{2}k\left(x_1^2 + x_2^2 + \frac{x_1^2}{4} + \frac{x_2^2}{4} + \frac{x_1x_2}{2} - (x_1 + x_2)x_3 + x_3^2\right)$$

$$= \frac{1}{2}k\left(\frac{5}{4}x_1^2 + \frac{5}{4}x_2^2 + \frac{x_1x_2 - x_1x_3 - x_2x_3 + x_3^2}{2}\right) //$$

(b)(i) $\frac{m}{M} \ll 1$: System is \approx 

$$\begin{Bmatrix} 1 \\ 1 \\ 1+\epsilon \end{Bmatrix}$$


Mode

'bounce'
of M with
 m "stuck" on

Frequency

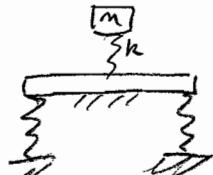
$$\omega_1 \approx \sqrt{\frac{2k}{M}}$$

(approx)

$$\begin{Bmatrix} -1 \\ 1 \\ 0 \end{Bmatrix}$$


pure 'pitch'

$$\frac{1}{12}Ml^2\ddot{\theta} + \frac{kl^2}{2}\ddot{\theta} = 0 \Rightarrow \omega_2 = \sqrt{\frac{6k}{M}}$$

$$\begin{Bmatrix} -\epsilon \\ -\epsilon \\ 1 \end{Bmatrix}$$


bounce of m
 M is \approx inertial

$$\omega_3 = \sqrt{\frac{k}{m}} \text{ (approx)}$$

$$3(b)(ii) \quad \frac{m}{M} \gg 1$$

Mode

Frequency

$$\begin{Bmatrix} k \\ k \\ 1 \end{Bmatrix} \quad k_t \quad \left\{ \begin{array}{c} m \\ \boxed{m} \\ \sum k \\ k \\ k \\ k \end{array} \right\} \quad \frac{1}{k_t} = \frac{1}{k} + \frac{1}{2k} \Rightarrow k_t = \frac{2}{3}k \Rightarrow \omega_1 = \sqrt{\frac{2k}{3m}} \quad (\text{approx})$$

bounce of m on combined stiffness

$$\begin{Bmatrix} 1 \\ -1 \\ 0 \end{Bmatrix} \quad \begin{array}{c} I \\ \diagdown \\ k \\ \diagup \\ k \end{array} \quad \text{pure pitch} \quad \omega_3 = \sqrt{\frac{6k}{M}} \quad (\text{exact, uncharged})$$

$$\begin{Bmatrix} 1 \\ 1 \\ -\epsilon \end{Bmatrix} \quad \begin{array}{c} M \\ \sum k \\ m \end{array} \quad \begin{array}{l} \text{bounce of } M \\ (m \text{ is inertial}) \end{array} \quad \omega_2 = \sqrt{\frac{3k}{M}} \quad (\text{approx})$$

(c) For $M/m \ll 1$ $(x_1, x_2, x_3)^T = (1, 1, \alpha)^T$

$$\omega^2 = \frac{V_{max}}{T^2} = \frac{\frac{1}{2}k(5/4 + 5/4 + 1/2 - \alpha - \alpha + \alpha^2)}{\frac{1}{2}[m\alpha^2 + \frac{M}{3}(1 + 1 + 1)]} = \frac{k(3 - 2\alpha + \alpha^2)}{m\alpha^2 + M}$$

Find exact frequencies by minimizing Rayleigh's quotient

$$\frac{d\omega^2}{d\alpha} = \frac{(m\alpha^2 + M)k(-2 + 2\alpha) - k(3 - 2\alpha + \alpha^2)(2m\alpha)}{(m\alpha^2 + M)^2}$$

$$\frac{d\omega^2}{d\alpha} = 0 \Rightarrow -2m\alpha^2 - 2M + 2m\alpha^3 + 2M\alpha - 6m\alpha + 4m\alpha^2 - 2m\alpha^3 = 0$$

$$\Rightarrow 2m\alpha^2 + \alpha(M - \frac{3}{2}m) - 2M = 0$$

$$\alpha = -\frac{(M - 3m)}{2m} \pm \sqrt{\frac{(M - 3m)^2 + 4mM}{4m}}$$

$$= \frac{3}{2} - \frac{M}{2m} \pm \sqrt{\left(\frac{M}{2m}\right)^2 - \frac{M}{2m} + \frac{9}{4}}$$

3. Gnt

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$$\text{If } \frac{M}{m} \rightarrow 0, \quad \alpha = \frac{3}{2} \pm \frac{3}{2} = 3, 0$$

$$\text{So modes are } \begin{Bmatrix} 1 \\ 1 \\ 3 \end{Bmatrix} \text{ & } \begin{Bmatrix} 1 \\ 1 \\ 0 \end{Bmatrix} \quad \checkmark$$

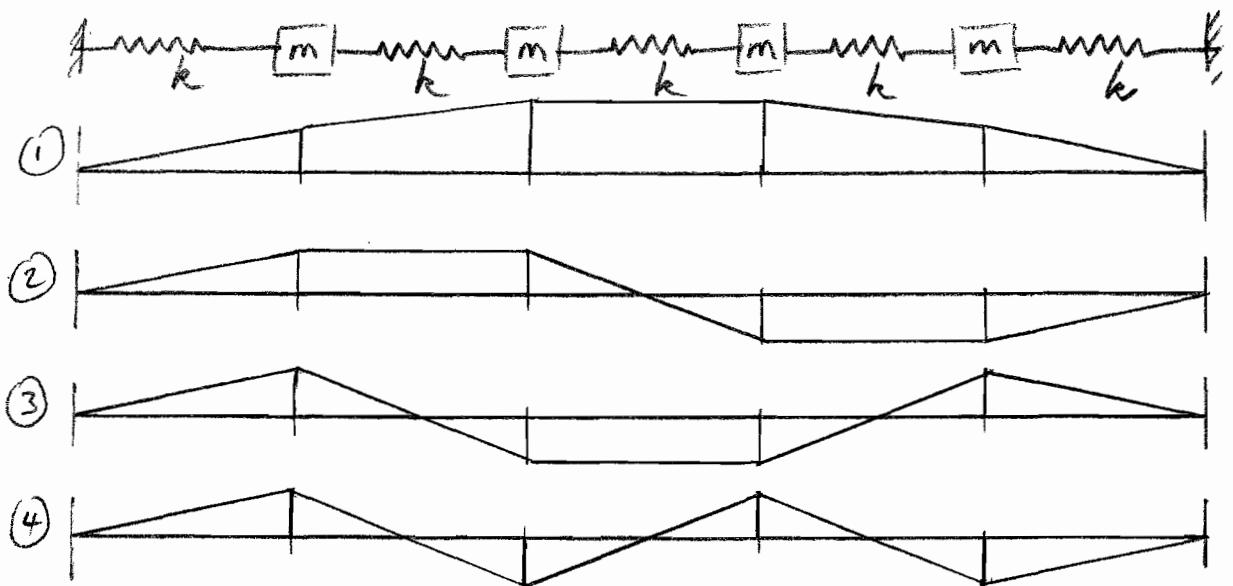
$$\alpha = 0 \rightarrow \omega_2^2 = \frac{3k}{M} \quad \checkmark$$

$$\alpha = 3 \rightarrow \omega_1^2 = \frac{k(3-6+9)}{9m+M} = \frac{6k}{m(9+\frac{M}{m})} = \frac{2}{3} \frac{k}{m} \quad \checkmark$$

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4. (a)



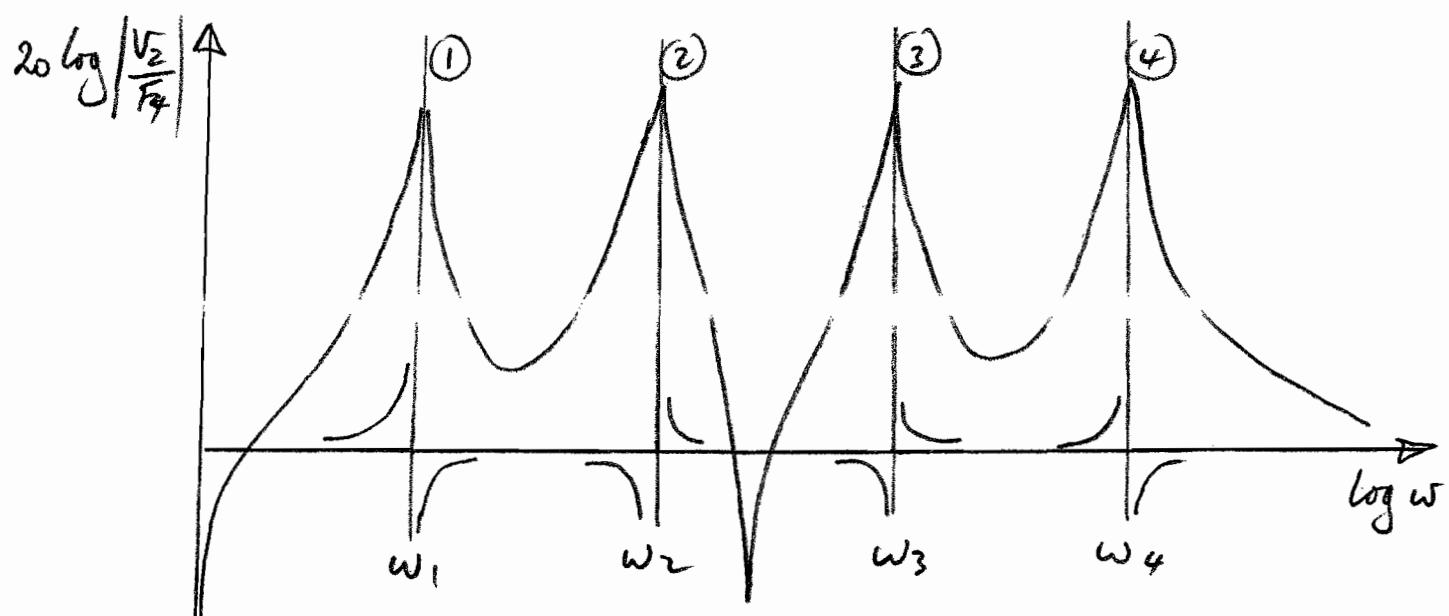
Modes ① & ④ will be symmetric and a mode shape of the form $[1 \ \alpha \ \alpha \ 1]^T$ will be suitable for both

Modes ② & ③ will be anti-symmetric

(b) Products of modal amplitudes for parts 2 & 4

- ① +
- ② -
- ③ -
- ④ +

So there is an anti-resonance between modes ② & ③ and minima elsewhere



4(c)

$$KE: T = \frac{1}{2}m[\dot{x}_1^2 + \dot{x}_2^2 + \dot{x}_3^2 + \dot{x}_4^2]$$

$$PE: V = \frac{1}{2}k[x_1^2 + (x_1 - x_2)^2 + (x_2 - x_3)^2 + (x_3 - x_4)^2 + x_4^2]$$

$$\text{So } [M] = m[I] \text{ & } [K] = k \begin{bmatrix} 2 & -1 & 0 & 0 \\ -1 & 2 & -1 & 0 \\ 0 & -1 & 2 & -1 \\ 0 & 0 & -1 & 2 \end{bmatrix}$$

(d) For mode $[1 \ \alpha \ \alpha \ 1]^T$, Rayleigh's quotient is:

$$R = \omega^2 = \frac{V}{T^*} = \frac{\frac{1}{2}k[1 + (\alpha-1)^2 + \alpha^2 + (\alpha+1)^2 + 1]}{\frac{1}{2}m[1 + \alpha^2 + \alpha^2 + 1]}$$

$$= \frac{k}{m} \left(\frac{\alpha^2 - 2\alpha + 2}{\alpha^2 + 1} \right)$$

Minimise R :

$$\frac{dR}{d\alpha} = 0 \Rightarrow (\alpha^2 + 1)(2\alpha - 2) - (\alpha^2 - 2\alpha + 2)(2\alpha) = 0$$

$$\Rightarrow (2\cancel{\alpha^3} - 2\alpha^2 + 2\alpha - 2) - (2\cancel{\alpha^3} - 4\alpha^2 + 4\alpha) = 0$$

$$\Rightarrow \alpha^2 - \alpha - 1 = 0$$

$$\therefore \alpha_{1,2} = \frac{1}{2}(1 \pm \sqrt{5}) = -0.618, 1.618$$

$$\text{Since } \alpha^2 = \alpha + 1, \quad \omega^2 = \frac{k}{m} \left(\frac{3-\alpha}{\alpha+1} \right)$$

$$\text{For } \alpha = \frac{1}{2}(1 + \sqrt{5}), \quad \omega_1^2 = \frac{k}{m} \left(\frac{3 - \frac{1}{2}(1 + \sqrt{5})}{2 + \frac{1}{2}(1 + \sqrt{5})} \right) = \frac{k}{m} \left(\frac{5 - \sqrt{5}}{5 + \sqrt{5}} \right)$$

$$0.38 \text{ k/m}$$

$$\text{for } \alpha = \frac{1}{2}(1 - \sqrt{5}), \quad \omega_3^2 = \frac{k}{m} \left(\frac{5 + \sqrt{5}}{5 - \sqrt{5}} \right) = 2.618 \text{ k/m}$$

Both modes are exact because the true mode shape is among the family of assumed modes, due to symmetry.