

ENGINEERING TRIPOS PART IIA

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Tuesday 29 April 2008 9 to 10.30

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Module 3F1

SIGNALS AND SYSTEMS

*Answer not more than **three** questions.*

*All questions carry the same number of marks.*

*The **approximate** percentage of marks allocated to each part of a question is indicated in the right margin.*

*There are no attachments.*

STATIONERY REQUIREMENTS

Single-sided script paper

SPECIAL REQUIREMENTS

Engineering Data Book

CUED approved calculator allowed

**You may not start to read the questions  
printed on the subsequent pages of this  
question paper until instructed that you  
may do so by the Invigilator**

1 Consider the following difference equation:

$$y_{k+1} + ay_k = bu_k, \quad y_0 = \beta$$

where  $a$ ,  $b$  and  $\beta$  are real valued constants.

(a) Take the  $z$ -transform of the above difference equation to find  $Y(z)$  as a function of  $U(z)$  and  $\beta$ . [15%]

(b) With  $u_k = 0$  for all  $k \geq 0$ , find  $y_k$  for all  $k \geq 0$ . Assuming  $\beta > 0$ , draw graphs of  $y_k$  versus  $k$  for each of the five cases: (i)  $a < -1$ , (ii)  $-1 < a < 0$ , (iii)  $a = 0$ , (iv)  $0 < a < 1$  and (v)  $a > 1$ . [30%]

(c) Let  $\beta = 0$  and consider the feedback law  $u_k = -cy_k + r_k$ , where  $c$  is a real number and  $r_k$  is an input to the system.

(i) Show that the transfer function  $T(z)$  from  $R(z)$  to  $Y(z)$  is given by

$$T(z) = \frac{b}{z + a + bc}$$

and write down a necessary and sufficient condition for  $T(z)$  to be stable. [20%]

(ii) Assuming that  $T(z)$  is stable show that

$$\frac{|b|}{2} \leq |T(e^{j\theta})| \leq \frac{|b|}{1 - |a + bc|}$$

for all  $\theta$  with  $0 \leq \theta \leq \pi$ . [35%]

- 2 (a) (i) State the Nyquist stability criterion for a discrete time system  $G(z)$  and a constant gain feedback controller  $k$  in the usual negative feedback configuration. [10%]

- (ii) Sketch the Nyquist diagram for the open-loop system

$$G(z) = \frac{4}{z-2} \quad (1)$$

clearly labelling any intersections with the real axis and the direction of encirclement. [20%]

- (iii) Use the Nyquist stability criterion to determine the closed-loop stability of the feedback loop with  $G(z)$  given by (1) and with  $k = 0.5$  and  $k = 2$  in the usual negative feedback configuration. [20%]

- (b) The Characteristic Function of a random variable  $X$  is defined to be

$$\Phi_X(u) = E[e^{juX}]$$

where  $E[.]$  is the expectation operator.

- (i) Calculate the Characteristic Function of the random variable  $X$  whose probability density function is given by

$$f_X(x) = \begin{cases} ae^{-ax} & \text{for } x \geq 0 \\ 0 & \text{for } x < 0 \end{cases}$$

where  $a$  is a positive constant. [20%]

- (ii) Show that, for any random variable  $X$ ,

$$\frac{d^n \Phi_X(u)}{du^n} = j^n \int_{-\infty}^{\infty} x^n e^{jux} f_X(x) dx$$

Hence calculate the first and second moments of the random variable  $X$  in part (b)(i). [30%]

(TURN OVER)

3 (a) What is the form of the resulting probability density function (pdf) when independent random variables with Gaussian pdfs are added together? Give brief reasons for this result. [20%]

(b) The autocorrelation function (ACF) of a zero-mean ergodic random signal  $X(t)$  is the triangular function

$$r_{XX}(\tau) = \begin{cases} A \left(1 - \frac{|\tau|}{T}\right) & \text{for } |\tau| \leq T \\ 0 & \text{for } |\tau| > T \end{cases}$$

where  $A$  and  $T$  are positive constants.

(i) Calculate the mean power of  $X(t)$ , assuming it represents the signal voltage across a one ohm resistor. [10%]

(ii) The signal  $X(t)$  is the input signal to a linear system whose impulse response is given by

$$h(t) = \delta(t) + \delta(t - T)$$

and whose output is denoted by  $Y(t)$ . Calculate and sketch the ACF of the output signal,  $r_{YY}(\tau)$ . Hence obtain the mean power of  $Y(t)$ . [50%]

(iii) Assuming that  $X(t)$  and  $X(t - T)$  are independent and Gaussian, give an expression for  $f_Y(y)$ , the pdf of  $Y(t)$ . [20%]

4 (a) A message source  $S$  has  $M$  symbols, with probabilities  $p_i$ ,  $i = 1, \dots, M$ . In a Shannon-Fano code the codeword lengths  $l_i$  for  $S$  are chosen such that

$$\log_2(1/p_i) \leq l_i < \log_2(1/p_i) + 1 \quad \text{for } i = 1, \dots, M$$

Show that

$$H(S) \leq L < H(S) + 1$$

where  $H(S)$  is the entropy of the source and  $L$  is the mean code length.

[25%]

(b) A first-order Markov source has a joint probability table given by

		$X_{n-1}$	
		$A$	$B$
$P(X_n, X_{n-1}) :$	$A$	0.84	0.06
	$B$	0.06	0.04

(i) Determine the equilibrium probabilities,  $P(A)$  and  $P(B)$ , and create a conditional probability table,  $P(X_n|X_{n-1})$ , for this source. [20%]

(ii) Calculate the conditional entropy  $H(X_n|X_{n-1})$  and the mutual information between consecutive symbols  $I(X_n; X_{n-1})$ , and obtain an expression for the total entropy of  $N$  consecutive symbols from this source. [40%]

(iii) Assuming a Shannon-Fano code for a string of  $N$  consecutive symbols, give bounds on the mean code length per symbol  $L/N$ . [15%]

**END OF PAPER**

