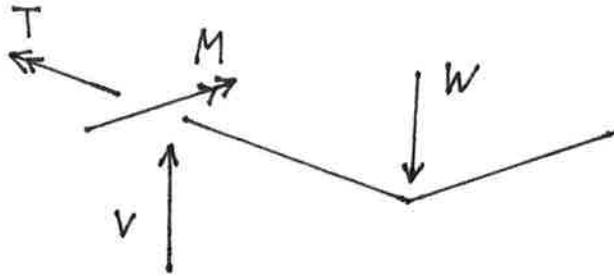
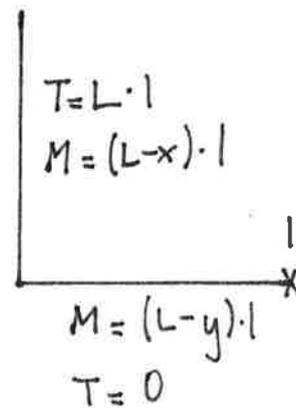
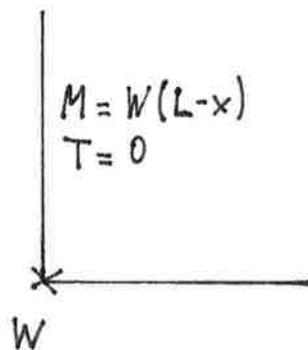


1a)



- i) The non-zero boundary reactions at the built-in support are V , M and T .
- ii) The degree of redundancy is one. We can, for example, remove the roller support.



Tip deflection (Principle of virtual work)

$$\delta_{10} = \frac{1}{EI} \int_0^L W(L-x)^2 dx = \frac{1}{3EI} WL^3$$

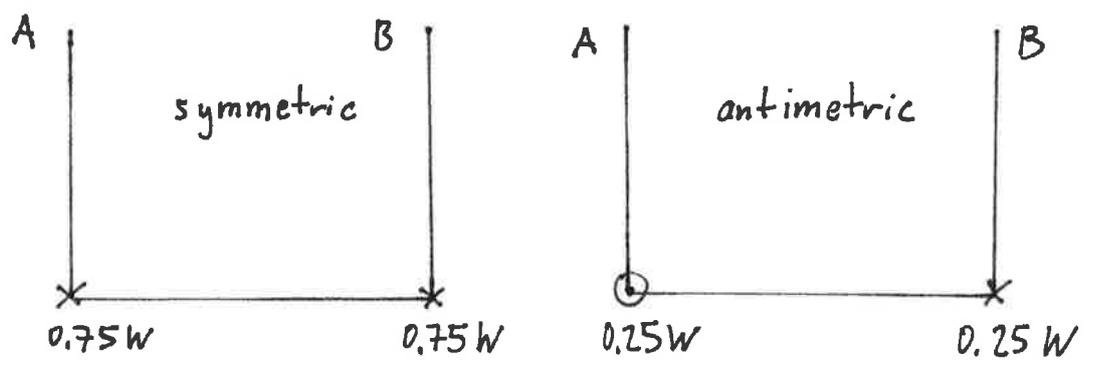
Tip deflection due to unit load at tip.

$$\begin{aligned} \delta_{11} &= \frac{1}{EI} \int_0^L (L-x)^2 dx + \frac{1}{EI} \int_0^L (L-y)^2 dy + \frac{1}{GJ} \int_0^L L^2 dx \\ &= \frac{1}{EI} \frac{1}{3} L^3 + \frac{1}{EI} \frac{1}{3} L^3 + \frac{1}{GJ} L^3 \\ &= \frac{2}{3} \frac{L^3}{EI} + \frac{L^3}{GJ} = \frac{7}{6} \frac{L^3}{EI} \end{aligned}$$

$$\Rightarrow X = \frac{1}{3} WL^3 \cdot \frac{6}{7L^3} = \frac{2}{7} W$$

$$\Rightarrow M = WL - \frac{2}{7} WL = \underline{\underline{\frac{5}{7} WL}}$$

(k) The loading can be decomposed in a symmetric and antimetric component.



Moments for symmetric loading

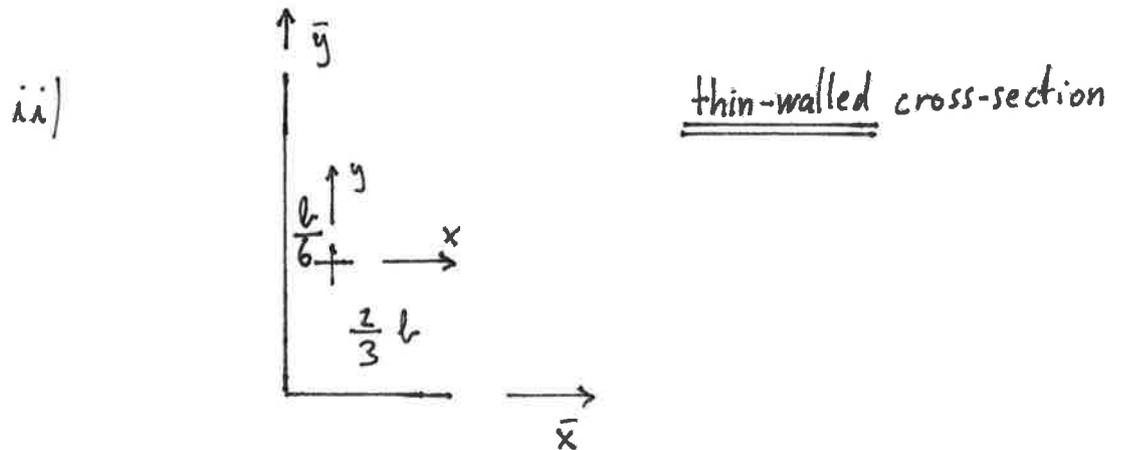
$$M_A = M_B = 0.75 LW$$

Moments for antisymmetric loading like in a)

$$\Rightarrow M_A = 0.75 LW - \frac{5}{7} WL \frac{1}{4} = \underline{0.5714 W}$$

$$\Rightarrow M_B = 0.75 LW + \frac{5}{7} WL \frac{1}{4} = \underline{0.9286 W}$$

2a) i) $J = \sum \frac{1}{3} b t^3 = \frac{1}{3} 2 b t^3 + \frac{1}{3} b t^3 = \underline{b t^3}$



Centre of gravity:

$$3 b t y_s = 2 b t b \Rightarrow y_s = \frac{2}{3} b$$

$$3 b t x_s = b t \frac{b}{2} \Rightarrow x_s = \frac{b}{6}$$

$$I_{xx} = \frac{(2b)^3 t}{12} + 2bt \left(b - \frac{2}{3}b\right)^2 + bt \left(\frac{2}{3}b\right)^2$$

$$= b^3 t \left(\frac{2}{3} + \frac{2}{9} + \frac{4}{9}\right) = 1,333 b^3 t$$

$$I_{yy} = 2bt \left(\frac{b}{6}\right)^2 + \frac{b^3 t}{12} + bt \left(\frac{b}{2} - \frac{b}{6}\right)^2$$

$$= b^3 t \left(\frac{1}{18} + \frac{1}{12} + \frac{1}{9}\right) = 0,25 b^3 t$$

$$I_{xy} = 2bt \left(-\frac{b}{6}\right) \left(\frac{1}{3}b\right) + bt \left(-\frac{2}{3}b\right) \left(\frac{1}{3}b\right)$$

$$= -0,333 b^3 t$$

Centre of Mohr's circle

$$\frac{1}{2} (1,333 b^3 t + 0,25 b^3 t) = 0,7917 b^3 t$$

Radius of Mohr's circle

$$\frac{b^3 t}{2} \sqrt{0,1111 + (1,333 - 0,7917)^2} = 0,6357 b^3 t$$

$$\Rightarrow I_{\xi\xi} = \underline{1,427 b^3 t} \quad I_{\eta\eta} = \underline{0,156 b^3 t}$$

2b)

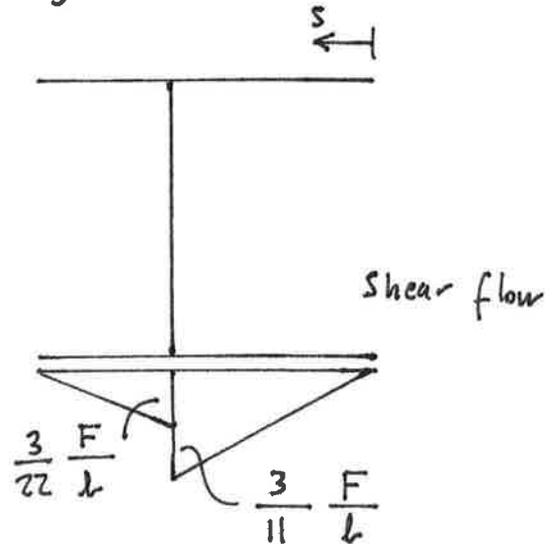
5

$$q = \frac{FS}{I}$$

$$I = 2 \cdot \frac{3}{2} b^3 t + (2b)^3 t \frac{1}{12} = \frac{11}{3} b^3 t$$

$$S = s \cdot t \cdot b$$

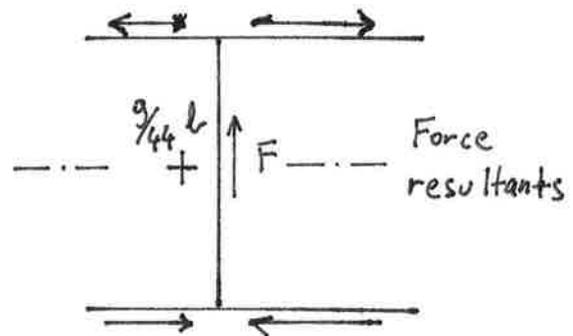
$$q = \frac{F s t b^3}{11 b^3 t}$$



Moment equilibrium

$$\left(\frac{3}{22} F - \frac{3}{88} F \right) \cdot 2b = F x_s$$

$$\Rightarrow x_s = \frac{9}{44} b$$



3a)

6

$$\Pi(w) = \frac{1}{2} \int_0^L (EI w''^2 - P w'^2 + k w^2) dx$$

$$w = \sum a_n \sin \frac{n\pi x}{L}$$

$$w' = \sum a_n \frac{n\pi}{L} \cos \frac{n\pi x}{L}$$

$$w'' = -\sum a_n \left(\frac{n\pi}{L}\right)^2 \sin \frac{n\pi x}{L}$$

$$\frac{1}{2} \int_0^L EI w''^2 dx = \frac{1}{2} EI \sum_n \sum_m a_n a_m \left(\frac{n\pi}{L}\right)^2 \left(\frac{m\pi}{L}\right)^2 \int_0^L \sin \frac{n\pi x}{L} \sin \frac{m\pi x}{L} dx$$

$$\text{with } \int_0^L \sin \frac{n\pi x}{L} \sin \frac{m\pi x}{L} dx = \begin{cases} L/2 & n=m \\ 0 & n \neq m \end{cases}$$

$$\text{First term of } \Pi(w) \quad \frac{1}{2} EI \left(\frac{L}{2}\right) \sum a_n^2 \left(\frac{n\pi}{L}\right)^4$$

$$\text{Second term of } \Pi(w) \quad -\frac{1}{2} P \left(\frac{L}{2}\right) \sum a_n^2 \left(\frac{n\pi}{L}\right)^2$$

$$\text{Third term of } \Pi(w) \quad \frac{1}{2} k \left(\frac{L}{2}\right) \sum a_n^2$$

We can write for $\Pi(w)$

$$\Pi(a_n) = \frac{1}{2} \underline{a}^T \underline{K} \underline{a}$$

$$\text{with } K_{nn} = \frac{L}{2} \left[\left(\frac{n\pi}{L}\right)^4 EI - \left(\frac{n\pi}{L}\right)^2 P + k \right]$$

Instability when $K_m = 0$

$$\Rightarrow P_{cr} = \left(\frac{L}{n\pi}\right)^2 \left[\left(\frac{n\pi}{L}\right)^4 EI + k \right]$$

$$= \left(\frac{n\pi}{L}\right)^2 EI + \left(\frac{L}{n\pi}\right)^2 k$$

For given n , the length that minimises P_{cr}

$$\frac{dP_{cr}}{dL} = 0 \Rightarrow -\frac{2}{L^3} n^2 \pi^2 EI + \frac{2L}{n^2 \pi^2} k = 0$$

whence

$$L_{cr}^4 = \frac{n^4 \pi^4 EI}{k} \Rightarrow L_{cr} = n\pi \left(\frac{EI}{k}\right)^{\frac{1}{4}}$$

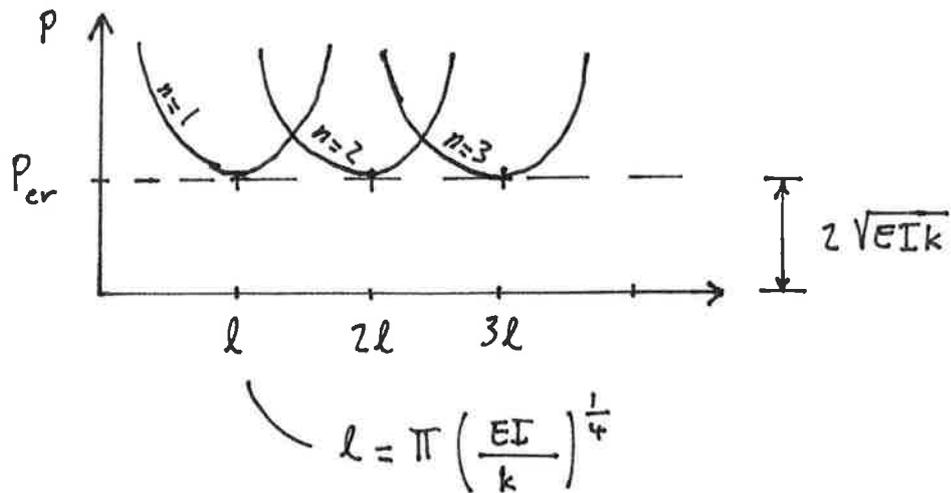
The minimum value of P_{cr} at this length L_{cr}

$$= \left(\frac{n\pi}{L_{cr}}\right)^2 EI + \left(\frac{L_{cr}}{n\pi}\right)^2 k$$

$$= \frac{n^2 \pi^2}{n^2 \pi^2} \frac{\sqrt{k}}{\sqrt{EI}} EI + \frac{n^2 \pi^2}{n^2 \pi^2} \frac{\sqrt{EI}}{\sqrt{k}} k$$

$$= \sqrt{k} \sqrt{EI} + \sqrt{k} \sqrt{EI}$$

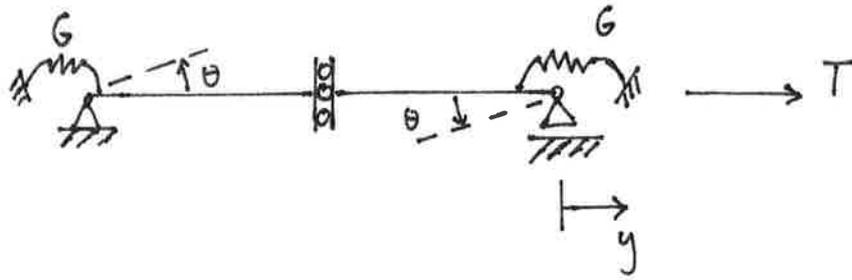
$$\Rightarrow P_{cr \min} = 2 \sqrt{EI k}$$



- 3b) 1) The analysis assumes only radially symmetric modes, but modes which also have circumferential wave numbers - e.g. checkerboard modes - might be relevant. Such modes were seen in the 3D4 buckling lab.
- 2) Thin-walled cylinders are very sensitive to imperfections, thus any theoretical prediction using 'perfect' elastic stability theory is likely to be significantly greater than the actual load-carrying capacity of the real cylinder. Again, this was observed in the 3D4 buckling lab.

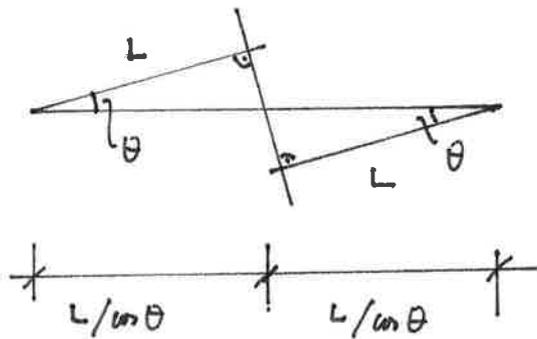
4a)

9



$$\text{Total potential energy} = \underbrace{\left(\frac{1}{2} G \theta^2\right) \cdot 2}_{\text{internal}} - \underbrace{T y}_{\text{external}}$$

Deflected shape



$$\text{Extension } y = 2 \left(\frac{L}{\cos \theta} - L \right)$$

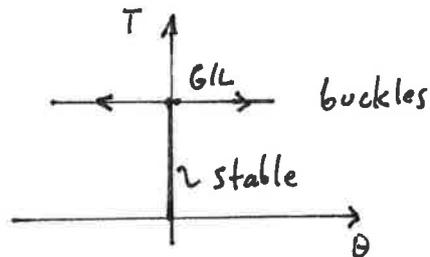
$$\text{Small angles } \cos \theta = 1 - \frac{\theta^2}{2} + \dots$$

$$\text{Binomial theorem } \frac{1}{\cos \theta} = \left(1 - \frac{\theta^2}{2} + \dots \right)^{-1} = 1 + \frac{\theta^2}{2} + \dots$$

$$\begin{aligned} \text{Total P.E.} &= G \theta^2 - 2T \left(L \left(1 + \frac{\theta^2}{2} + \dots \right) - L \right) \\ &= G \theta^2 - T L \theta^2 \end{aligned}$$

Equilibrium from $\frac{\partial \Pi(\theta)}{\partial \theta} = 2\theta(G - TL) = 0$

Solutions $\theta = 0$ unless $G - TL = 0 \implies T = \frac{G}{L}$ critical tension



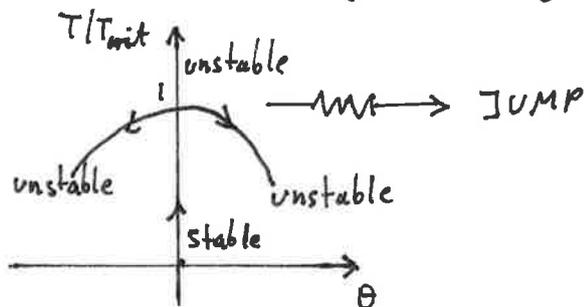
To determine bifurcation type, need large angle theory

$$\Pi(\theta) = G\theta^2 - 2TL \left(\frac{1}{\cos\theta} - 1 \right)$$

Equilibrium from $\frac{\partial \Pi}{\partial \theta} = 2\theta G - 2TL \left(\frac{\sin\theta}{\cos^2\theta} \right) = 0$

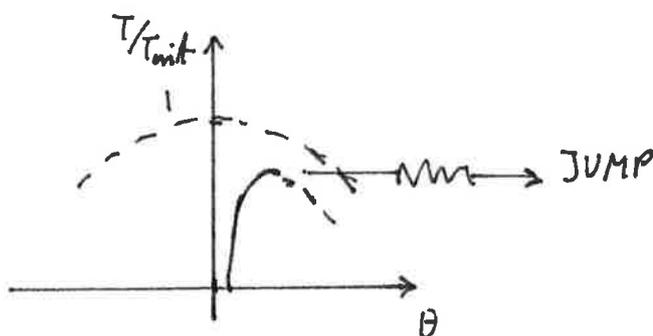
Solutions $\theta = 0$ unless $\frac{T}{T_{crit}} = \frac{\theta \cos^2\theta}{\sin\theta}$

Now just plot it by evaluating few points



Unstable symmetric bifurcation

And with imperfections



4b)

11

Shanley's resolution to the Column Paradox involved the notion that a structure could undergo a deformation $d\underline{w}$ during a loading increment $d\underline{F}$. This differs from basic elastic stability theory which tends to start from the premise that the structure is carrying a fixed load \underline{F} and then virtual (or small) displacements $d\underline{w}$ are explored about the equilibria to determine stability. It is Shanley's joint combination of $d\underline{w}$ and $d\underline{F}$ that is the crucial difference. Looking at $d\underline{w}$ alone does not find all possible solutions in case of inelastic buckling.

4c)

$$\begin{bmatrix} M_B \\ M_C \end{bmatrix} = \begin{bmatrix} K_1 & K_2 \\ K_2 & K_3 \end{bmatrix} \begin{bmatrix} \theta_B \\ \theta_C \end{bmatrix}$$

Beam AB provides $\begin{bmatrix} 4 & 0 \\ 0 & 0 \end{bmatrix} \frac{EI}{L}$

BC provides $\begin{bmatrix} 4 & 2 \\ 2 & 4 \end{bmatrix} \frac{EI}{L}$

CD provides $\begin{bmatrix} 0 & 0 \\ 0 & 3 \end{bmatrix} \frac{EI}{L}$

Column BE provides $\begin{bmatrix} 5 & 0 \\ 0 & 0 \end{bmatrix} \frac{EI}{L}$

Column CF:

$$\begin{bmatrix} M_C \\ M_F \end{bmatrix} = \frac{EI}{L} \begin{bmatrix} s & sc \\ sc & s \end{bmatrix} \begin{bmatrix} \theta_C \\ \theta_F \end{bmatrix}$$

but $M_F = 0$

$$0 = \frac{EI}{L} (sc \theta_C + s \theta_F)$$

$$\Rightarrow \theta_F = -c \theta_C$$

Substituting into first equation yields

$$\begin{aligned} M_C &= \frac{EI}{L} [s \theta_C + sc (-c \theta_C)] \\ &= \frac{EI}{L} s (1 - c^2) \theta_C \end{aligned}$$

\Rightarrow

Total stiffness
matrix

$$\frac{EI}{L} \begin{bmatrix} 8+s & 2 \\ 2 & 7+s(1-c^2) \end{bmatrix}$$

Numerical answers for 3D4

$$1a) \text{ ii) } M = \frac{5}{7} WL$$

$$1b) \quad M_A = 0.5714 W$$

$$M_B = 0.9286 W$$

$$2a) \text{ i) } J = b t^3$$

$$\text{ii) } I_{\xi\xi} = 1.427 b^3 t$$

$$I_{\eta\eta} = 0.156 b^3 t$$

$$2b) \quad x_s = \frac{9}{44} b$$

$$3a) \quad P_{cr, \min} = 2 \sqrt{EI k}$$

$$4a) \quad T_{\min} = \frac{G}{L}$$

$$4c) \quad \begin{bmatrix} 8+s & 2 \\ 2 & 7+s(1-c^2) \end{bmatrix} \frac{EI}{L}$$

