

ENGINEERING TRIPOS PART IIB

Module 4C10 Examination, 2003

Answers

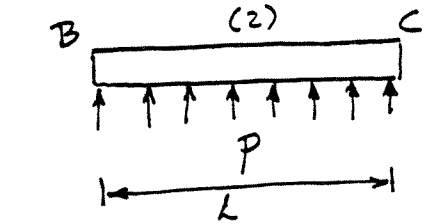
1. (a) $Q_B^{(2)} = Q_C^{(2)} = \frac{pL}{2}$; $M_B^{(2)} = -M_C^{(2)} = \frac{pL^2}{12}$
- (b) $K_r = \frac{2EI}{L^3} \begin{bmatrix} 4L^2 & L^2 \\ L^2 & 2L^2 \end{bmatrix} \begin{Bmatrix} \theta_B \\ \theta_C \end{Bmatrix}$; (c) $\begin{Bmatrix} \theta_B \\ \theta_C \end{Bmatrix} = \frac{pL^3}{24EI} \begin{Bmatrix} 3/7 \\ -5/7 \end{Bmatrix}$
- (d) $u(x) = \theta_B \left[x - \frac{2x^2}{L} + \frac{x^3}{L^2} \right] + \theta_C \left[-\frac{x^2}{L} + \frac{x^3}{L^2} \right]$; $0 \leq x \leq L$
2. (a) $N_4 = 9\xi\eta$; (b) $\begin{Bmatrix} X \\ Y \end{Bmatrix} = L \begin{Bmatrix} 2\xi \\ \xi + \eta \end{Bmatrix}$; $\left(L, \frac{3L}{4} \right)$
- (c) $J = L \begin{bmatrix} 2 & 1/2 \\ 0 & 1 \end{bmatrix}$; (d) $|J| = 2L^2$; (e) $\xi_{xx} = \frac{u_2}{4L} + \frac{3u_4}{4L}$
3. (c)(i) $\left\{ \frac{EI}{L^3} \begin{bmatrix} 12 & -6L \\ -6L & 8L^2 \end{bmatrix} + \frac{P}{30L} \begin{bmatrix} 36 & -3L \\ -3L & 4L^2 \end{bmatrix} \right\} \begin{Bmatrix} \delta v_2 \\ \delta \theta_2 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$; (ii) $P_{cr} = -\frac{20}{3} \frac{EI}{L^2}$
4. (b) $M_r = \frac{4m}{3} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{Bmatrix} u_2 \\ v_2 \end{Bmatrix}$;
- (c) $\omega_1^2 = 0.22 \frac{k}{m}$, $\frac{u_2}{v_2} = 0.414$; $\omega_2^2 = 1.28 \frac{k}{m}$, $\frac{u_2}{v_2} = -2.42$

① (a) equivalent loads

$$Q_B^{(2)} = \int_0^L p N(x) dx = \frac{pL}{2}$$

$$Q_C^{(2)} = \int_0^L p N_3(x) dx = \frac{pL}{2}$$

$$M_B^{(2)} = \int_0^L p N_2(x) dx = \frac{pL^2}{12}$$



$$M_C^{(2)} = \int_0^L p N_4(x) dx = -\frac{pL^2}{12} \quad (15^\circ)$$

(b) $u_2^{(1)} = u_1^{(2)}, \theta_2^{(1)} = \theta_1^{(2)}$

$$K = \frac{2EI}{L^3} \begin{bmatrix} 6 & 3L & -6 & 3L & 0 & 0 \\ 3L & 2L^2 & -3L & L^2 & 0 & 0 \\ -6 & -3L & 6+6 & -3L+3L & -6 & 3L \\ 3L & L^2 & -3L+3L & 2L^2+2L^2 & -3L & L^2 \\ 0 & 0 & -6 & -3L & 6 & -3L \\ 0 & 0 & 3L & L^2 & -3L & 2L^2 \end{bmatrix} \begin{matrix} u_A \\ \theta_A \\ u_B \\ \theta_B \\ u_C \\ \theta_C \end{matrix}$$

reduced stiffness matrix K_r from B.C. $u_A = u_B = u_C = \theta_A = 0$

$$K_r = \frac{2EI}{L^3} \begin{bmatrix} 4L^2 & L^2 \\ L^2 & 2L^2 \end{bmatrix} \begin{matrix} \theta_B \\ \theta_C \end{matrix}$$

(30^o)

(c) $K_r d = R$

$$\frac{2EI}{L} \begin{bmatrix} 4 & 1 \\ 1 & 2 \end{bmatrix} \begin{Bmatrix} \theta_B \\ \theta_C \end{Bmatrix} = \frac{pL^2}{12} \begin{Bmatrix} 1 \\ -1 \end{Bmatrix} \rightarrow \begin{Bmatrix} \theta_B \\ \theta_C \end{Bmatrix} = \frac{pL^3}{24EI} \begin{Bmatrix} 3/7 \\ -5/7 \end{Bmatrix} \quad (3)$$

(d) $\xi^{(1)} = x+L$

$$u_A = u_B = \theta_A = 0 \rightarrow u(x) = \theta_B N_4(x) = \theta_B \left[-\frac{(x+L)^2}{L} + \frac{(x+L)^3}{L^2} \right], -L \leq x \leq C$$

$\xi^{(2)} = x$

$$u_B = u_C = 0 \rightarrow u(x) = \theta_B N_2(x) + \theta_C N_4(x) = \theta_B \left[x - \frac{2x^2}{L} + \frac{x^3}{L^2} \right] + \theta_C \left[-\frac{x^2}{L} + \frac{x^3}{L^2} \right], 0 \leq x \leq L$$

(25)

(2)

(a)

$$N_4: \begin{array}{l} \text{node} \\ j=1 \\ j=2 \\ j=3 \\ j=4 \end{array} \begin{array}{l} N_4 = a + b\xi_j + c\eta_j + d\xi_j\eta_j \\ 0 = a + 0 + 0 + 0 \\ 0 = a + b + 0 + 0 \\ 0 = a + 0 + c + 0 \\ 1 = a + b/3 + c/3 + d/9 \end{array} \left. \begin{array}{l} \\ \\ \\ \\ \end{array} \right\} \begin{array}{l} a=0 \\ b=0 \\ c=0 \\ d=9 \end{array}$$

$$N_1 = 1 - \xi - \eta - 3\xi\eta, \quad N_2 = \xi - 3\xi\eta, \quad N_3 = \eta - 3\xi\eta, \quad \underline{N_4 = 9\xi\eta}$$

(20%)

(b)

$$\begin{Bmatrix} x \\ y \end{Bmatrix} = \begin{bmatrix} N_1 & 0 & N_2 & 0 & N_3 & 0 & N_4 & 0 \\ 0 & N_1 & 0 & N_2 & 0 & N_3 & 0 & N_4 \end{bmatrix} \begin{Bmatrix} x_1 \\ y_1 \\ x_2 \\ y_2 \\ x_3 \\ \vdots \end{Bmatrix}$$

$$= \begin{bmatrix} 1-\xi-\eta-3\xi\eta & 0 & \xi-3\xi\eta & 0 & \eta-3\xi\eta & 0 & 9\xi\eta & 0 \\ 0 & 1-\xi-\eta-3\xi\eta & 0 & \xi-3\xi\eta & 0 & \eta-3\xi\eta & 0 & 9\xi\eta \end{bmatrix} \begin{Bmatrix} 0 \\ 0 \\ 2 \\ 1/2 \\ 0 \\ 1 \\ 2/3 \\ 1/2 \end{Bmatrix}$$

$$\underline{\begin{Bmatrix} x \\ y \end{Bmatrix} = \begin{Bmatrix} 2\xi \\ \xi/2 + \eta \end{Bmatrix}}$$

for $\xi = \eta = 1/2$, $\underline{x = 1, y = 3/4}$

i.e. edge 2-3 maps as straight line

(30%)

$$\begin{aligned}
 \text{(c)} \quad \underline{J} &= \begin{bmatrix} \frac{\partial N_1}{\partial \xi} & \frac{\partial N_2}{\partial \xi} & \frac{\partial N_3}{\partial \xi} & \frac{\partial N_4}{\partial \xi} \\ \frac{\partial N_1}{\partial \eta} & \frac{\partial N_2}{\partial \eta} & \frac{\partial N_3}{\partial \eta} & \frac{\partial N_4}{\partial \eta} \end{bmatrix} \begin{bmatrix} x_1 & y_1 \\ x_2 & y_2 \\ x_3 & y_3 \\ x_4 & y_4 \end{bmatrix} \\
 &= L \begin{bmatrix} -1-3\eta & 1-3\eta & -3\eta & 9\eta \\ -1-3\xi & -3\xi & 1-3\xi & 9\xi \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 2 & 1/2 \\ 0 & 1 \\ 2/3 & 1/2 \end{bmatrix} = L \begin{bmatrix} 2 & 1/2 \\ 0 & 1 \end{bmatrix} \quad (20\%)
 \end{aligned}$$

$$\text{(d)} \quad |\underline{J}| = 2L; \text{ i.e. area of global element} \\
 = 2 \times \text{area parent element} \quad (10\%)$$

$$\text{(e)} \quad \underline{J}^{-1} = \begin{bmatrix} \frac{\partial \xi}{\partial x} & \frac{\partial \eta}{\partial x} \\ \frac{\partial \xi}{\partial y} & \frac{\partial \eta}{\partial y} \end{bmatrix} = \frac{1}{L} \begin{bmatrix} 1/2 & -1/4 \\ 0 & 1 \end{bmatrix}$$

$$\epsilon_{xx} = \frac{\partial u}{\partial x} = \underline{J}_{11}^{-1} \frac{\partial u}{\partial \xi} + \underline{J}_{12}^{-1} \frac{\partial u}{\partial \eta} = \underline{J}_{11}^{-1} \sum \frac{\partial N_i}{\partial \xi} u_i + \underline{J}_{12}^{-1} \sum \frac{\partial N_i}{\partial \eta} u_i$$

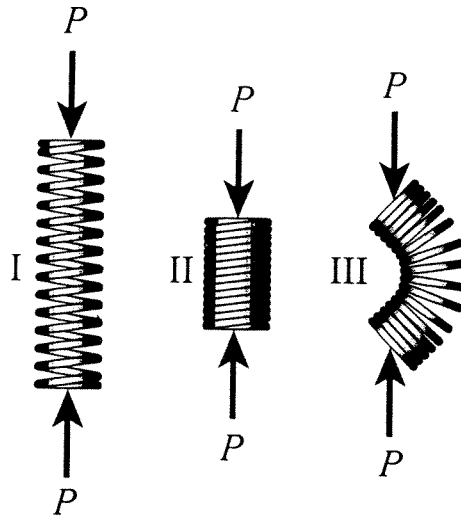
$$\text{with } u_1 = u_3 = 0 \\
 \epsilon_{xx} = \frac{1}{2L} [(1-3\eta)u_2 + 9\eta u_4] - \frac{1}{4L} [-3\xi u_2 + 9\xi u_4]$$

$$\text{at centroid } \xi = \eta = 1/3$$

$$\underline{\epsilon_{xx}} = \frac{u_2}{4L} + \frac{3u_4}{4L} \quad (20\%)$$

2. (a) Geometric (change of geometry important);
 3 Material (constitutive laws of flowing metal highly nonlinear);
 Displacement boundary conditions (contact conditions). (20%)

(b)



In state I, the spring behaves as a linear spring. In state II, the spring has "bottomed out" and is much stiffer. In state III, the spring has buckled as an Euler column and its load capacity rapidly diminishes. (20%)

(c) (i)

Element α

$$[k'] = \frac{EI}{L^3} \begin{bmatrix} 12 & 6L & -12 & 6L \\ & 4L^2 & -6L & 2L^2 \\ \text{sym.} & & 12 & -6L \\ & & & 4L^2 \end{bmatrix} \begin{matrix} v_1 \\ \theta_1 \\ v_2 \\ \theta_2 \end{matrix} \quad \begin{matrix} u_1 = u_2 = 0 \\ \text{(rigid beam)} \end{matrix}$$

$$[k'_\sigma] = \frac{P}{30L} \begin{bmatrix} 36 & 3L & -36 & 3L \\ & 4L^2 & -3L & -L^2 \\ \text{sym} & & 36 & -3L \\ & & & 4L^2 \end{bmatrix} \begin{matrix} v_1 \\ \theta_1 \\ v_2 \\ \theta_2 \end{matrix} \quad \text{(due to stress stiffening)}$$

3
p. (continued)

Element \textcircled{D}
(global coordinates)

$$[K^2] = \frac{EI}{L^3} \begin{bmatrix} 0 & 0 & 0 & 0 \\ & 4L^2 & 0 & 2L^2 \\ \text{sym.} & & 0 & 0 \\ & & & 4L^2 \end{bmatrix} \begin{matrix} v_2 \\ \theta_2 \\ v_3 \\ \theta_3 \end{matrix}$$

$[K^2]$ vanishes because there is no axial force on \textcircled{D} .

Assemble together to get (noting that $v_3 = \theta_3 = v_1 = \theta_1 = 0$)

$$\left\{ \begin{matrix} \frac{EI}{L^3} \begin{bmatrix} 12 & -6L \\ -6L & 8L^2 \end{bmatrix} \\ K \end{matrix} + \frac{P}{30L} \begin{bmatrix} 36 & -3L \\ -3L & 4L^2 \end{bmatrix} \right\} \begin{matrix} \delta v_2 \\ \delta \theta_2 \end{matrix} = \begin{matrix} 0 \\ 0 \end{matrix} \quad (35\%)$$

$K \qquad K_\sigma$

(ii) At a critical load P_{cr} the structure buckles, with

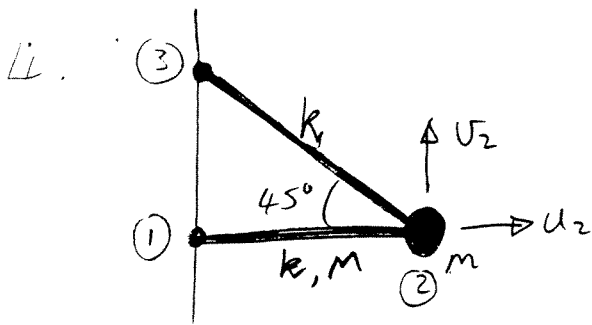
$$\det [K + K_\sigma] = 0$$

$$\Rightarrow \begin{vmatrix} 12(1+3\lambda) & -3L(2+\lambda) \\ -3L(2+\lambda) & 4L^2(2+\lambda) \end{vmatrix} = 0 \quad \left(\lambda = \frac{PL^2}{30EI} \right)$$

The lowest eigenvalue is $\lambda = -\frac{2}{9}$

$$\Rightarrow \boxed{P_{cr} = -\frac{20}{3} \frac{EI}{L^2}}$$

(25%)



(a) Stiffness matrix

$$[k_{12}] = k \begin{bmatrix} u_1 & v_1 & u_2 & v_2 \\ 1 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{matrix} u_1 \\ v_1 \\ u_2 \\ v_2 \end{matrix}$$

($c=1, s=0$)
(Cook p79)

$$[k_{23}] = \frac{k}{2} \begin{bmatrix} 1 & -1 & -1 & 1 \\ -1 & 1 & 1 & -1 \\ -1 & 1 & 1 & -1 \\ 1 & -1 & -1 & 1 \end{bmatrix} \begin{matrix} u_2 \\ v_2 \\ u_3 \\ v_3 \end{matrix}$$

$\theta = 135^\circ$
 $c = -\frac{1}{\sqrt{2}}$
 $s = \frac{1}{\sqrt{2}}$

$$\text{So } [K] = \frac{k}{2} \begin{bmatrix} u_1 & v_1 & u_2 & v_2 & u_3 & v_3 \\ 2 & 0 & -2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ -2 & 0 & 3 & -1 & -1 & 1 \\ 0 & 0 & -1 & 1 & 1 & -1 \\ 0 & 0 & -1 & 1 & 1 & -1 \\ 0 & 0 & 1 & -1 & -1 & 1 \end{bmatrix} \begin{matrix} u_1 \\ v_1 \\ u_2 \\ v_2 \\ u_3 \\ v_3 \end{matrix}$$

(30%)

(b) Mass matrix

$$[m_{12}] = m \begin{bmatrix} \ddot{u}_1 & \ddot{v}_1 & \ddot{u}_2 & \ddot{v}_2 \\ 1/3 & 0 & 1/6 & 0 \\ 0 & 1/3 & 0 & 1/6 \\ 1/6 & 0 & 1/3 & 0 \\ 0 & 1/6 & 0 & 1/3 \end{bmatrix} \begin{matrix} \ddot{u}_1 \\ \ddot{v}_1 \\ \ddot{u}_2 \\ \ddot{v}_2 \end{matrix}$$

(Cook p231)

$$[M_{lumped}] = m \begin{bmatrix} \ddot{u}_1 & \ddot{v}_1 & \ddot{u}_2 & \ddot{v}_2 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{matrix} \ddot{u}_1 \\ \ddot{v}_1 \\ \ddot{u}_2 \\ \ddot{v}_2 \end{matrix}$$

$$\text{So } [M] = m \begin{bmatrix} 1/3 & 0 & 1/6 & 0 \\ 0 & 1/3 & 0 & 1/6 \\ 1/6 & 0 & 1/3 & 0 \\ 0 & 1/6 & 0 & 1/3 \end{bmatrix} \begin{matrix} \ddot{u}_1 \\ \ddot{v}_1 \\ \ddot{u}_2 \\ \ddot{v}_2 \end{matrix}$$

(20%)

(c) Reduced equation of motion for free vibration.

$$\frac{4m}{3} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{Bmatrix} \ddot{u}_2 \\ \ddot{v}_2 \end{Bmatrix} + \frac{k}{2} \begin{bmatrix} 3 & -1 \\ -1 & 1 \end{bmatrix} \begin{Bmatrix} u_2 \\ v_2 \end{Bmatrix} = 0$$

The eigenvalue problem is $([K] - \omega^2 [M]) \underline{u} = 0$

$$\Rightarrow \begin{vmatrix} 3k/2 - \omega^2 4m/3 & -k/2 \\ -k/2 & k/2 - \omega^2 4m/3 \end{vmatrix} = 0$$

(c). cont

$$\left(3\frac{k}{2} - \omega^2 \frac{4m}{3}\right) \left(\frac{k}{2} - \omega^2 \frac{4m}{3}\right) - \frac{k^2}{4} = 0$$

$$\frac{k^2}{2} - \omega^2 \left(\frac{2mk}{3} + 2mk\right) + \omega^4 \frac{16m^2}{9} = 0$$

$$\omega^4 - \frac{8mk}{\frac{16}{9}m^2} + \frac{\frac{k^2}{2}}{\frac{16m^2}{9}} = 0$$

$$\frac{18}{3} - \frac{48}{8} = 0$$

$$\omega^4 - \frac{3}{2} \frac{k}{m} + \frac{9}{32} \frac{k^2}{m} = 0$$

$$\therefore \omega^2 = \frac{+\frac{3}{2} \frac{k}{m} \pm \sqrt{\left(\frac{3}{2} \frac{k}{m}\right)^2 - 4\left(\frac{9}{32}\right) \frac{k^2}{m}}}{2}$$

$$= \frac{k}{m} \left(\frac{3}{4} \pm \frac{3}{4\sqrt{2}} \right) = \frac{3}{4} \frac{k}{m} (1 \pm \frac{1}{\sqrt{2}})$$

$$\therefore \omega^2 = \underline{\underline{0.22 \frac{k}{m}, 1.28 \frac{k}{m}}}$$

e-vectors

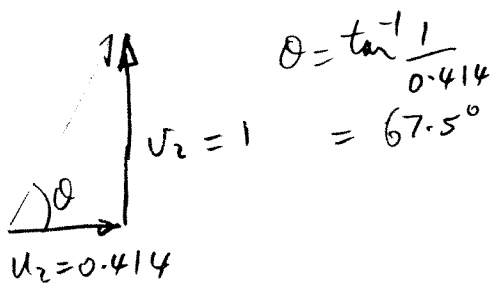
1st row of eqn of motion is

$$\left(3\frac{k}{2} - \omega^2 \frac{4m}{3}\right) u_2 - \frac{k}{2} v_2 = 0$$

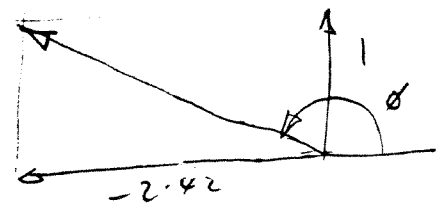
$$\omega \frac{u_2}{v_2} = \frac{k/2}{3k/2 - \omega^2 4m/3}$$

For $\omega_1^2 = 0.22 \frac{k}{m}$, this gives $\frac{u_2}{v_2} = \frac{1/2}{3/2 - 4/3(0.22)} = 0.414$

for $\omega_2^2 = 1.28 \frac{k}{m}$ $\frac{u_2}{v_2} = \frac{1/2}{3/2 - 4/3(1.28)} = -2.42$



@ $\omega_1^2 = 0.22 \frac{k}{m}$



$$\phi = 180 - \tan^{-1} \frac{1}{2.42} = 157.5^\circ$$

@ $\omega_2^2 = 1.28 \frac{k}{m}$

The two modes are geometrically orthogonal