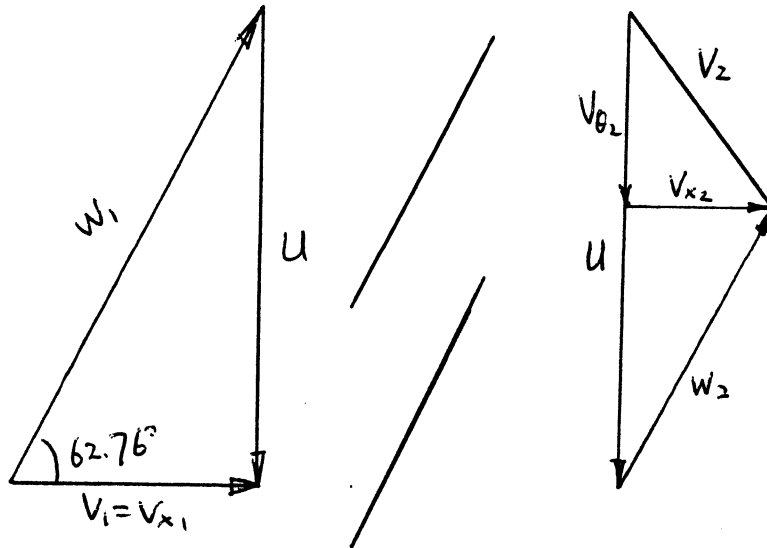


Solution:

1.

a).

b.) from table. $P_2/p_1 = 2.1858$ $\sigma = 0.9531$

$$P_1 = 0.7528 P_{01} = 76281.2 \text{ Pa}$$

$$T_1 = 0.9221 T_{01} = 265.56 \text{ K}$$

$$P_{01}^{\text{rel}} = \frac{76281.2}{0.3055} = 249692.96 \text{ Pa}$$

$$T_{01}^{\text{rel}} = \frac{265.56}{0.7126} = 372.27 \text{ K}$$

$$T_{02}^{\text{rel}} = T_{01}^{\text{rel}} = 372.27 \text{ K}$$

$$P_{s2} = 2.1858 \cdot 76281.2 = 166735.45 \text{ Pa}$$

$$T_{s2} = 1.2676 \cdot 265.56 = 336.62 \text{ K}$$

$$a_1 = \sqrt{\gamma R T_1} = 326.65 \text{ m/s}$$

$$U = 1.2625 \cdot 326.65 = 412.4 \text{ m/s}$$

$$V_{\theta 2} = U \left(1 - \frac{W_2}{W_1}\right) = U \left(1 - \frac{M_2}{M_1} \sqrt{\frac{T_1}{T_2}}\right) = 173.24 \text{ m/s}$$

$$U V_{\theta 2} = 71445.0 \text{ m}^2/\text{s}^2$$

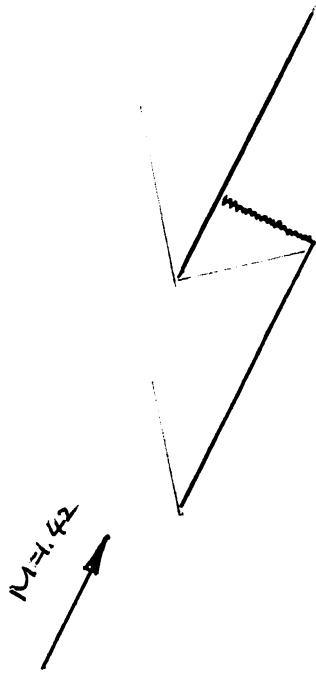
$$T_{02} = T_{01} + U V_{\theta 2} / c_p = 288 + 71445 / 1004.5 = 71.12 + 288 = 359.12 \text{ K}$$

$$P_{02} = P_2 \left(\frac{T_{02}}{T_2}\right)^{\frac{\gamma}{\gamma-1}} = 209111 \text{ Pa}, \quad \pi = 2.064$$

$$T_{02, \text{is}} = T_{01} \left(\frac{P_{02}}{P_{01}}\right)^{\frac{\gamma-1}{\gamma}} = 354.23, \quad \eta_{is} = \frac{354.23 - 288}{359.12 - 288} = \frac{66.23}{71.12} = 0.9312$$

$$\therefore \pi_s = 2.1858, \quad \pi = 2.064, \quad \eta_s = 0.9312$$

c).



d).

tangential momentum equation:

$$(\rho_1 V_{x1} \text{pitch}) \cdot (V_{\theta 2} - V_{\theta 1}) = \int_0^l \Delta p \cdot dx - C_x \quad (1)$$

$$\int_0^l \Delta p \cdot dx = (1-k)(P_2 - P_1) = P_1 (1-k)(\pi s - 1)$$

$$\frac{C_x}{\text{pitch}} = \frac{C \cdot \cos \beta}{\text{pitch}} = \sigma \cdot \cos \beta, \quad V_{\theta 1} = 0$$

(1) becomes:

$$V_{\theta 2} / V_{x1} = \frac{P_1}{\rho V_{x1}^2} \cdot (1-k)(\pi s - 1) \cdot \sigma \cdot \cos \beta = \frac{(1-k)(\pi s - 1) \sigma \cos \beta}{\gamma M_1^2}$$

$$\tan \alpha_2 = \frac{V_{\theta 2}}{V_{x2}} = \frac{V_{\theta 2}}{V_{x1}} \cdot \frac{V_{x1}}{V_{M2}} = \frac{W_1}{W_2} \cdot \frac{(1-k)(\pi s - 1) \sigma \cos \beta}{\gamma M_1^2} = (1-k)(\pi s - 1) \frac{\sigma \cos \beta}{M_1^2} \cdot \frac{M_1^{\text{rel}}}{M_2^{\text{rel}}} \sqrt{\frac{T_1}{T_2}}$$

end. q1.

2.

a). For free vortex design, $\frac{\partial rV_\theta}{\partial r} = 0$, with uniform inlet and cylindrical hub and casing line. $V_r \ll 1$ and $\frac{\partial V_r}{\partial r} \ll 1$ the only terms left in streamline curvature equation are $\frac{\partial p}{\partial r}$ and $\rho \frac{V_\theta^2}{r}$, thus simple radial equilibrium can be used.

The ~~flow~~ flow parameters at midspan:

$$V_1 = 10 \text{ m/s}. \quad V_2 = V_{\max} = V_x / \cos \beta_2 = 30 \text{ m/s}. \Rightarrow \text{flow is incompressible}$$

$$\text{incompressible. } V_{\theta \text{ mid}} = V_x \cdot \tan \beta_2 = 28.3 \text{ m/s}$$

$$rV_{\theta \text{ mid}} = rV_\theta(r) = 12.73 \text{ m}^2/\text{s}$$

from radial equilibrium, $\frac{dp}{dr} = \rho \frac{V_\theta^2}{r}$

$$\int dp = \int \rho \frac{(rV_\theta)^2}{r^3} dr = - \rho (rV_\theta)_{\text{mid}}^2 \frac{1}{2r^2} \Big|_{r_h}^{r_t}$$

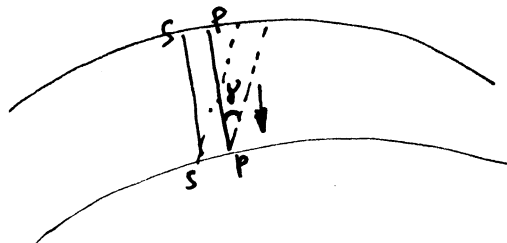
$$P(r) = P_{\text{hub}} + \frac{\rho (rV_\theta)_{\text{mid}}^2}{2} \left[\frac{1}{r_h^2} - \frac{1}{r^2} \right]$$

$$P_{\text{tip}} - P_{\text{hub}} = \Delta p = \frac{\rho (rV_\theta)_{\text{mid}}^2}{2} \cdot \frac{r_t^2 - r_h^2}{r_h^2 r_t^2} = \frac{\rho (rV_\theta)_{\text{mid}}^2 \cdot r_{\text{mid}} \cdot h}{r_h^2 r_t^2}$$

$$\rho \frac{\Delta p}{h} = \frac{\rho (rV_\theta)_{\text{mid}}^2 \cdot r_{\text{mid}}}{r_h^2 \cdot r_t^2} \quad ; \quad r_{\text{mid}} = 0.45, \quad r_h = 0.4, \quad r_t = 0.5$$

$$\frac{\Delta p}{h} = \frac{223.515}{0.1} = 2235.15 \text{ kg/m}^3$$

b). By leaning the blade, the radial component of the blade force is no longer zero and it acts to balance the centripetal acceleration term $\rho \frac{V_\theta^2}{r}$, thus the static pressure difference between the hub and the tip is off-set. However the blade should be leaned circumferentially in such a way to generate downward force; that is, to lean the blade to its pressure surface. Reaction at hub is increased as the static pressure there increases.



c). A body force represents the radial component of the blade force should be added. The mean blade force in circumference direction is $\overline{\Delta p|_c}$, its component in r direction is $\frac{\overline{\Delta p|_c} \cdot h}{S} \cdot \text{tg} \gamma$. h is the blade height and S the blade pitch. γ is the blade lean angle. Thus the ~~the~~ modified radial equilibrium equation takes form.

$$\rho \frac{V_0^2}{r} = \frac{dp}{dr} + \frac{\overline{\Delta p|_c} h}{S} \cdot \text{tg} \gamma$$

d). to reduce the $\Delta p|_{HT} = P_{tip} - P_{hub}$ by 50% :

$$\overline{\Delta p|_c} \cdot \frac{h}{S} \text{tg} \gamma = \frac{1}{2} \Delta p|_{HT}$$

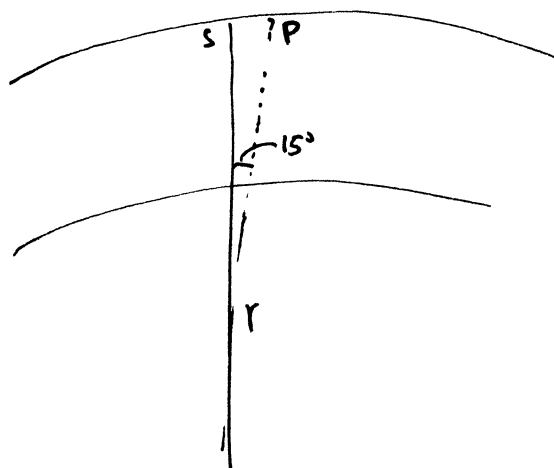
from tangential momentum equation at midspan:

$$S \cdot \rho V_x \cdot V_0 = \overline{\Delta p|_c} \cdot C_x \Rightarrow \overline{\Delta p|_c} = 468.95 \text{ Pa}$$

$$\text{tg} \gamma = \frac{1}{2} \cdot \Delta p|_{HT} \cdot \frac{S}{h} \cdot \frac{1}{\overline{\Delta p|_c}} = \frac{1}{2} \frac{\Delta p|_{HT}}{\overline{\Delta p|_c}} \cdot \frac{S}{C_x} \cdot \frac{C_x}{h} = \frac{1}{2} \frac{\Delta p|_{HT}}{\overline{\Delta p|_c}} \cdot \frac{S}{C_x} \left(\frac{h}{C_x} \right)^{-1}$$

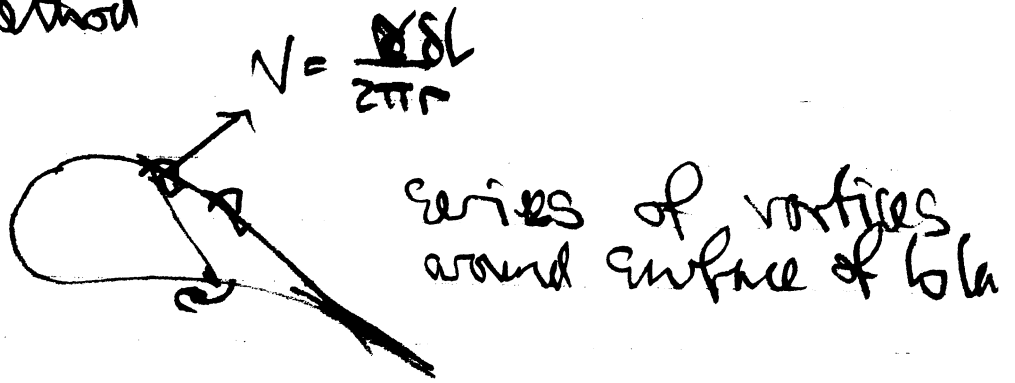
$$= \frac{1}{2} \frac{223.515}{468.95} \cdot \frac{1.35}{1.2} = 0.2681 \quad \gamma = 15^\circ$$

The blade should be leant by 15° to pressure surface (hub and pressure surface to form acute angle).

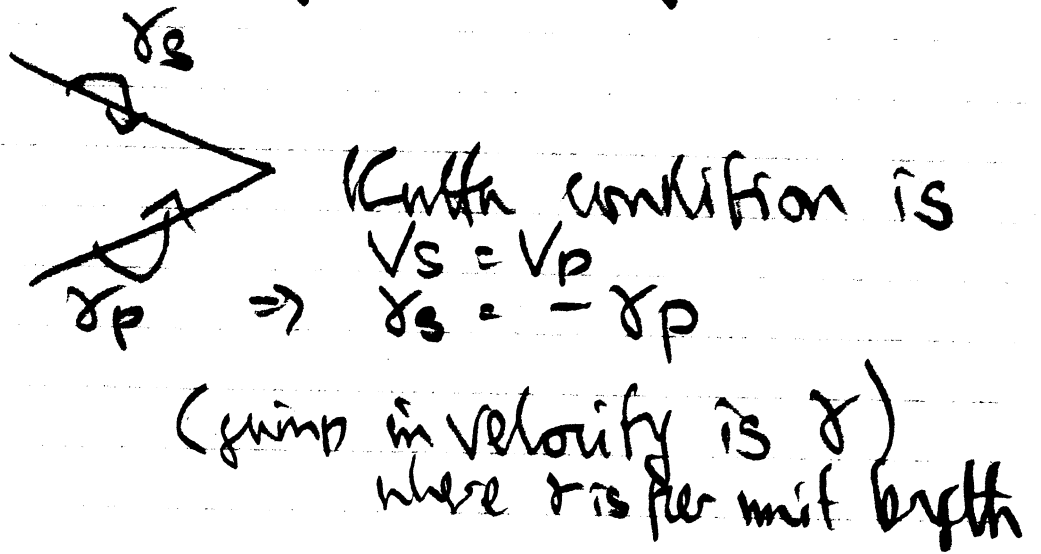


end q2.

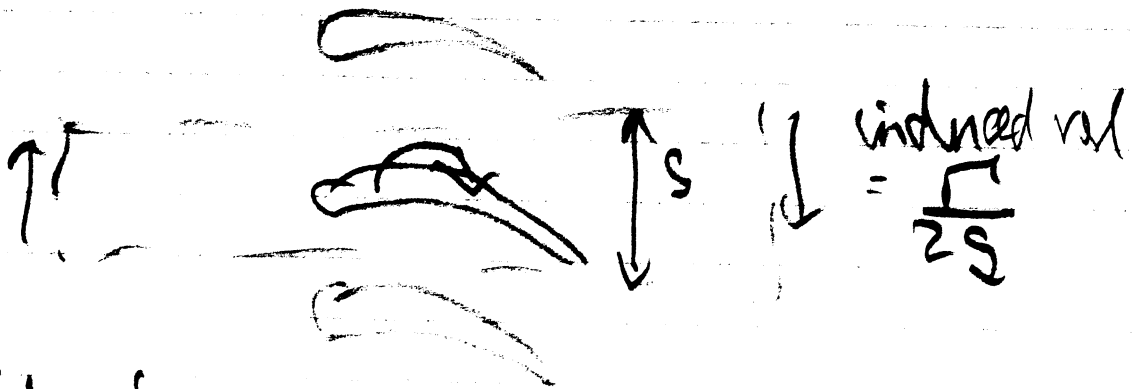
3. Panel method



interaction of all vortices is iterated to satisfy b.c. of zero tangential velocity inside blade



Turbomachinery b.c.



Advantages

- Fast
- simple
- good resolution
- good for inverse method

Disadvantages

no shocks / only potential flow

Euler/Navier Stokes

evolve $\frac{\partial \rho}{\partial t} \delta Vol + \sum \rho \underline{v} \cdot \underline{A} = 0$

& $\frac{\partial \rho \underline{v}}{\partial t} \delta Vol + \sum (\rho \underline{v} \cdot \underline{A}) \underline{v} = -\sum$

+ energy eqn & c

through small control volumes in the C

S.C. is periodic ^{u/s & d/s} & zero normal velocity against wall

flow (outflow) - follow characteristics

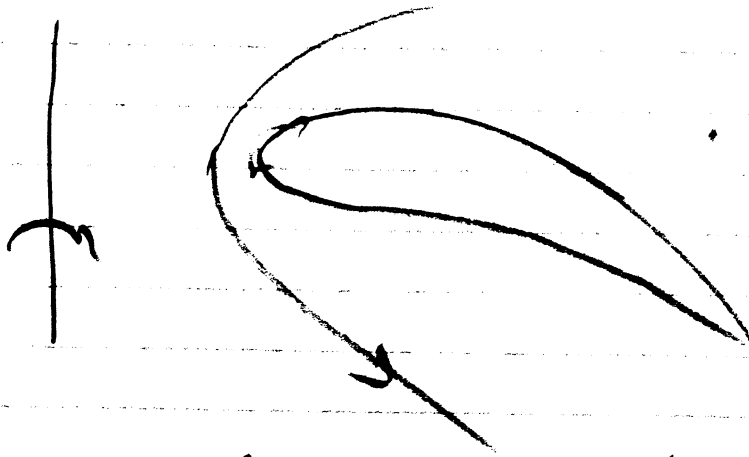
Advantages

robust, reliable
no constraints
fully compressible

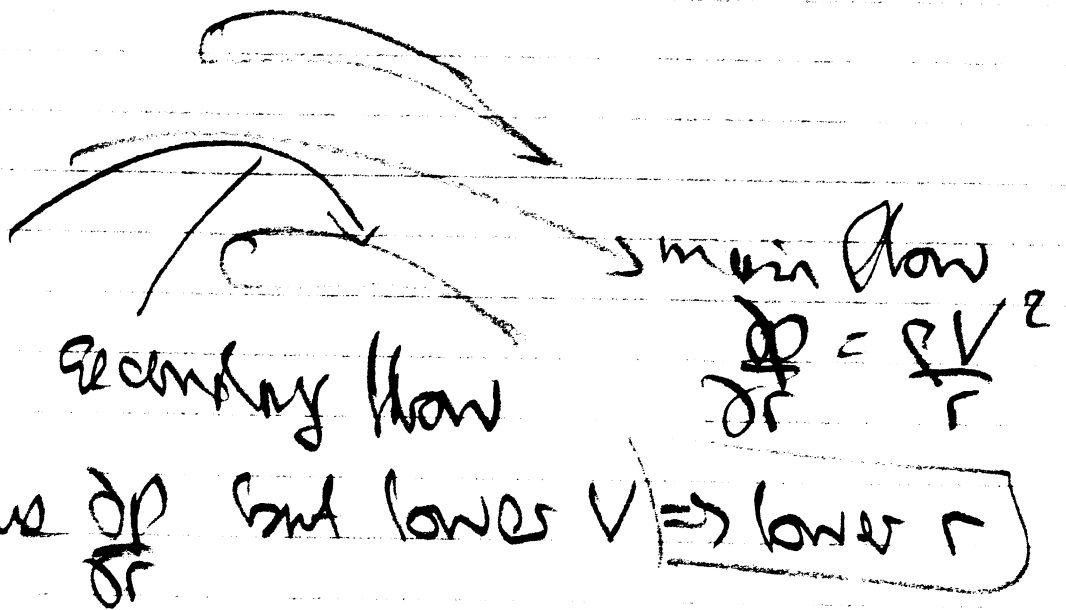
Disadvantages

relatively slow
mesh dependent in some cases

6) Secondary flow is any component of velocity that is not in the main flow direction
 suitable vorticity arguments are also



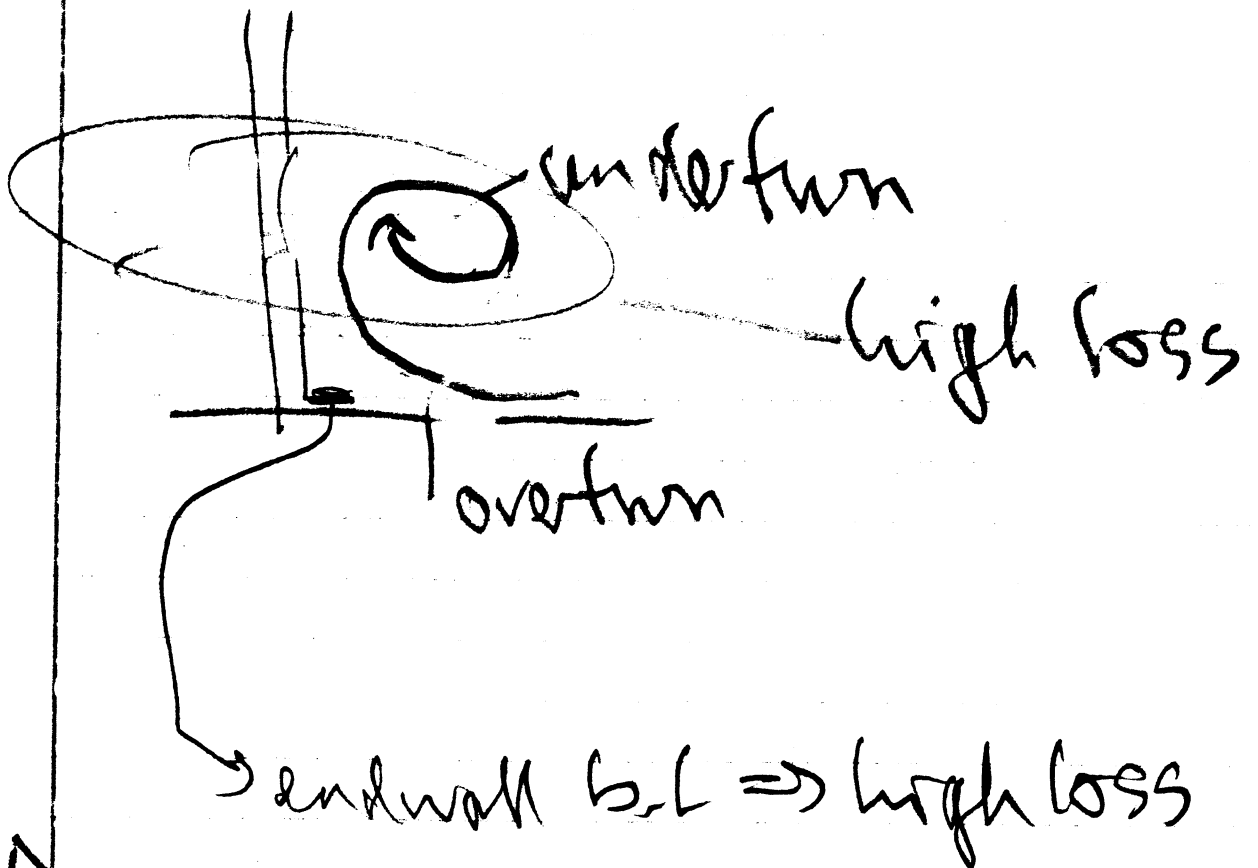
wrapping of modest vorticity around Γ to form horseshoe vortex



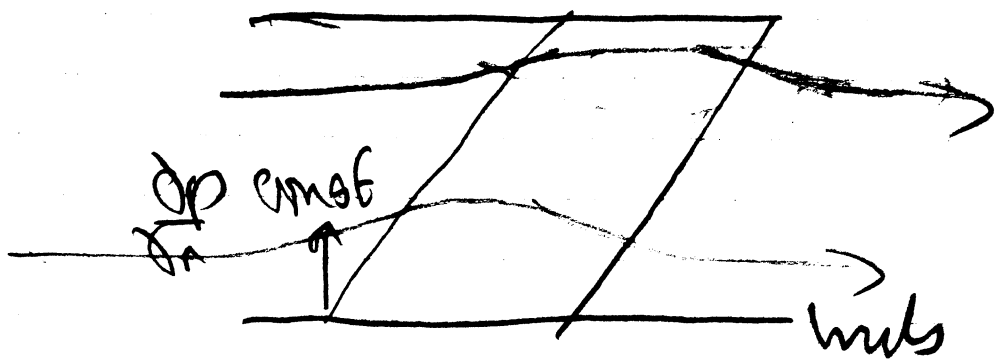
causes $\frac{dp}{dr}$ but lower $V \Rightarrow$ lower r

Most h.l. fluid ends up in the pressure vortex near the suction surface

c) endwalls: overturning



d) sweep: E.L. or E.L. not \perp to flow direction



=> low v at hubs high v at casing
& movement of streamlines as shown
& low hubs loading high casing loading