

ENGINEERING TRIPOS  
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PART IIB  
PART IIA

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Friday 6 May 2005

14.30 to 16.00

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Module 4C14

MECHANICS OF BIOLOGICAL SYSTEMS

*Answer not more than three questions.*

*All questions carry the same number of marks.*

*The approximate percentage of marks allocated to each part of a question is indicated in the right margin.*

*Attachments:*

*Special datasheet (2 pages)*

**You may not start to read the questions  
printed on the subsequent pages of this  
question paper until instructed that you may  
do so by the Invigilator**

(TURN OVER)

- 1 (a) Summarise the main mechanical functions of the cytoskeleton within a cell, by reference to the microtubules, actin cortex and intermediate filaments. [30%]
- (b) Outline the structure of a *sarcomere* and explain the role of the thick filaments, thin filaments and the Z-discs. [30%]
- (c) What is the significance of the *persistence length* in dictating the properties of biological fibres? [20%]
- (d) Explain the significance of the stiffness of the wall of a blood vessel in determining the blood flow rate. [20%]

2 A two dimensional biological network has the microstructure shown in Fig. 1. It can be treated as a periodic assembly of elastic-ideally plastic struts, with cell wall Young's modulus  $E_S$  and yield strength  $\sigma_{YS}$ . The struts are of uniform thickness  $t$ .

(a) Obtain an expression for the relative density  $\bar{\rho}$  in terms of  $t$  and the cell size  $\ell$ . [15%]

(b) Calculate the effective modulus  $E_2$  and the effective yield strength  $\sigma_{2Y}$  along the  $x_2$ -direction. The contribution from bending of the struts may be neglected. [30%]

(c) The effective strength of the network along the  $x_1$ -direction is dictated by plastic bending of the hinges at the ends of each inclined strut.

(i) Use a velocity diagram to relate the rate of rotation of the inclined struts to the resulting macroscopic strain rate  $\dot{\epsilon}_{11}$  along the  $x_1$ -direction. [15%]

(ii) Use virtual work to obtain an expression for the macroscopic effective strength  $\sigma_{1Y}$  along the  $x_1$ -direction in terms of the relative density and the cell wall strength  $\sigma_{YS}$ . [20%]

(iii) Calculate the nominal tensile strain along the  $x_1$ -direction in order for the structure to switch from a bending dominated response to a stretching dominated response. [20%]

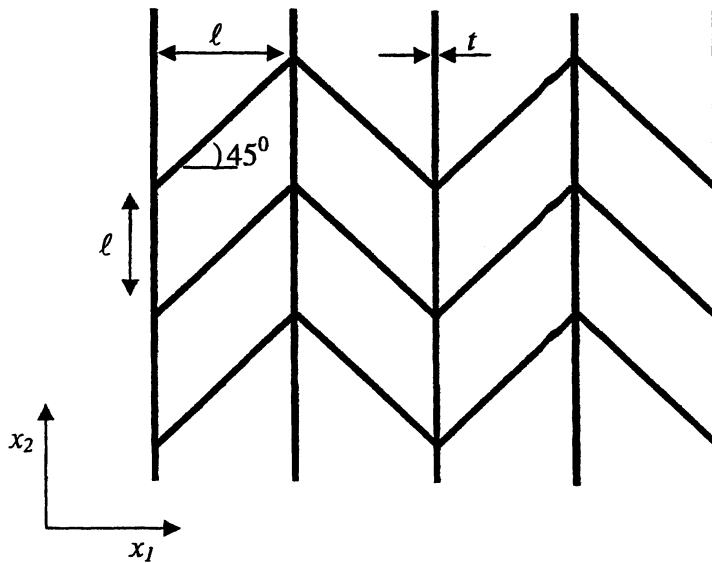


Fig. 1

(TURN OVER)

3 (a) Physiologists have long known that muscle speed  $v$  decreases with increasing load  $T$  according to the Hill equation

$$(T + a)v = b(T_o - T)$$

where  $a$  and  $b$  are constants and  $T_o$  is the isometric tetanic tension.

(i) Use the Hill equation to derive an expression for the power output of the muscle as a function of the muscle load  $T$ . [10%]

(ii) Determine the muscle speed  $v$  at which the muscle power is maximised. What is the implication of this in selecting a gear on a bicycle when riding up an incline? [30%]

(b) In the Huxley sliding filament model for a muscle, the fraction  $n(x)$  of attached crossbridges is given by

$$n(x) = \begin{cases} n_o \exp(kx/v) & x < 0 \\ n_o & 0 \leq x \leq h \\ 0 & x > h \end{cases}$$

where  $n_o$  and  $k$  are constants,  $x$  is the position of an actin binding site from the equilibrium position of a myosin head and  $v \equiv -dx/dt$  is the shortening velocity of the muscle. The muscle under consideration has a cross-sectional area  $A$ , sarcomere length  $s$ , and  $m$  crossbridges per unit volume. Assume that a linear spring with stiffness  $\lambda$  connects the myosin head to the thick filament.

(i) Determine the tension-velocity relation for this muscle. You may assume that the myosin sites  $M$  and the actin sites  $A$  have a separation  $l$  which is much greater than  $h$ . [40%]

(ii) Sketch the tension-velocity relation determined above and briefly discuss the quality of the agreement of this model with the Hill equation. [20%]

Hint:  $\int x e^{qx} dx = \frac{1}{q^2} [qxe^{qx} - e^{qx}]$

4 (a) Describe the role of the respiratory system and its principle of operation. [20%]

(b) Describe and account for the variations of partial pressure of  $O_2$  and  $CO_2$  in the blood when entering and leaving the alveolar capillaries. [20%]

(c) Explain the mechanism of  $CO_2$  removal from the blood. [20%]

(d) Oxygen is dissolved at concentration  $U$  uniformly across the cross-section of a capillary; steady state conditions are assumed such that  $U$  is independent of time  $t$  but can vary with the axial co-ordinate  $x$  along the capillary, of length  $L$ , uniform cross-sectional area  $A$  and perimeter  $C$ . The partial pressure  $P$  of the gas and the velocity  $v$  of blood flow can be taken as constant along the capillary. Diffusion of oxygen across the capillary wall is governed by

$$\frac{\partial U}{\partial t} + v \frac{\partial U}{\partial x} = D(\sigma P - U)$$

where  $D$  is the diffusion constant and  $\sigma$  is the solubility of oxygen in blood.

(i) Obtain an expression for  $U(x)$ , with the end condition  $U(0) = U_0$ . [20%]

(ii) Use mass conservation to calculate the rate of loss of oxygen across the wall of an infinitely long capillary. [20%]

**END OF PAPER**



**Paper G4: Mechanics of Solids**  
**ELASTICITY and PLASTICITY FORMULAE**

**1. Axi-symmetric deformation : discs, tubes and spheres**

	<u>Discs and tubes</u>	<u>Spheres</u>
Equilibrium	$\sigma_{\theta\theta} = \frac{d(r\sigma_r)}{dr} + \rho\omega^2 r^2$	$\sigma_{\theta\theta} = \frac{1}{2r} \frac{d(r^2\sigma_r)}{dr}$
Lamé's equations (in elasticity)	$\sigma_r = A - \frac{B}{r^2} - \frac{3+\nu}{8} \rho\omega^2 r^2 - \frac{E\alpha}{r^2} \int_r^c rTdr$	$\sigma_r = A - \frac{B}{r^3}$
	$\sigma_{\theta\theta} = A + \frac{B}{r^2} - \frac{1+3\nu}{8} \rho\omega^2 r^2 + \frac{E\alpha}{r^2} \int_r^c rTdr - E\alpha T$	$\sigma_{\theta\theta} = A + \frac{B}{2r^3}$

**2. Plane stress and plane strain**

	<u>Cartesian coordinates</u>	<u>Polar coordinates</u>
Strains	$\epsilon_{xx} = \frac{\partial u}{\partial x}$ $\epsilon_{yy} = \frac{\partial v}{\partial y}$ $\gamma_{xy} = \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x}$	$\epsilon_r = \frac{\partial u}{\partial r}$ $\epsilon_{\theta\theta} = \frac{u}{r} + \frac{1}{r} \frac{\partial v}{\partial \theta}$ $\gamma_{r\theta} = \frac{\partial v}{\partial r} + \frac{1}{r} \frac{\partial u}{\partial \theta} - \frac{v}{r}$
Compatibility	$\frac{\partial^2 \gamma_{xy}}{\partial x \partial y} = \frac{\partial^2 \epsilon_{xx}}{\partial y^2} + \frac{\partial^2 \epsilon_{yy}}{\partial x^2}$	$\frac{\partial}{\partial r} \left\{ r \frac{\partial \gamma_{r\theta}}{\partial \theta} \right\} = \frac{\partial}{\partial r} \left\{ r^2 \frac{\partial \epsilon_{\theta\theta}}{\partial r} \right\} - r \frac{\partial \epsilon_r}{\partial r} + \frac{\partial^2 \epsilon_r}{\partial \theta^2}$
or (in elasticity)	$\left\{ \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right\} (\sigma_{xx} + \sigma_{yy}) = 0$	$\left\{ \frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} \right\} (\sigma_r + \sigma_{\theta\theta}) = 0$
Equilibrium	$\frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \sigma_{xy}}{\partial y} = 0$ $\frac{\partial \sigma_{xy}}{\partial y} + \frac{\partial \sigma_{yy}}{\partial x} = 0$	$\frac{\partial}{\partial r} (r\sigma_r) + \frac{\partial \sigma_{r\theta}}{\partial \theta} - \sigma_{\theta\theta} = 0$ $\frac{\partial \sigma_{\theta\theta}}{\partial \theta} + \frac{\partial}{\partial r} (r\sigma_{r\theta}) + \sigma_{r\theta} = 0$
$\nabla^4 \phi = 0$ (in elasticity)	$\left\{ \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right\} \left\{ \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} \right\} = 0$	$\left\{ \frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} \right\}$ $\times \left\{ \frac{\partial^2 \phi}{\partial r^2} + \frac{1}{r} \frac{\partial \phi}{\partial r} + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2} \right\} = 0$
Airy Stress Function	$\sigma_{xx} = \frac{\partial^2 \phi}{\partial y^2}$ $\sigma_{yy} = \frac{\partial^2 \phi}{\partial x^2}$ $\sigma_{xy} = -\frac{\partial^2 \phi}{\partial x \partial y}$	$\sigma_r = \frac{1}{r} \frac{\partial \phi}{\partial r} + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2}$ $\sigma_{\theta\theta} = \frac{\partial^2 \phi}{\partial r^2}$ $\sigma_{r\theta} = -\frac{\partial}{\partial r} \left\{ \frac{1}{r} \frac{\partial \phi}{\partial \theta} \right\}$

### 3. Torsion of prismatic bars

Prandtl stress function:  $\sigma_{zx} (= \tau_x) = \frac{dF}{dy}$  ,  $\sigma_{zy} (= \tau_y) = -\frac{dF}{dx}$

Equilibrium:  $T = 2 \int_A F dA$

Governing equation for elastic torsion:  $\nabla^2 F = -2G\beta$  where  $\beta$  is the angle of twist per unit length.

### 4. Total potential energy of a body

$$\Pi = U - W$$

where  $U = \frac{1}{2} \int_V \underline{\underline{\varepsilon}}^T [D] \underline{\underline{\varepsilon}} dV$  ,  $W = \underline{\underline{P}}^T \underline{\underline{u}}$  and  $[D]$  is the elastic stiffness matrix.

### 5. Principal stresses and stress invariants

Values of the principal stresses,  $\sigma_p$ , can be obtained from the equation

$$\begin{vmatrix} \sigma_{xx} - \sigma_p & \sigma_{xy} & \sigma_{xz} \\ \sigma_{xy} & \sigma_{yy} - \sigma_p & \sigma_{yz} \\ \sigma_{xz} & \sigma_{yz} & \sigma_{zz} - \sigma_p \end{vmatrix} = 0$$

This is equivalent to a cubic equation whose roots are the values of the 3 principal stresses, i.e. the possible values of  $\sigma_p$ .

Expanding:  $\sigma_p^3 - I_1 \sigma_p^2 + I_2 \sigma_p - I_3 = 0$  where  $I_1 = \sigma_{xx} + \sigma_{yy} + \sigma_{zz}$ ,

$$I_2 = \begin{vmatrix} \sigma_{yy} & \sigma_{yz} \\ \sigma_{yz} & \sigma_{zz} \end{vmatrix} + \begin{vmatrix} \sigma_{xx} & \sigma_{xz} \\ \sigma_{xz} & \sigma_{zz} \end{vmatrix} + \begin{vmatrix} \sigma_{xx} & \sigma_{xy} \\ \sigma_{xy} & \sigma_{yy} \end{vmatrix} \quad \text{and} \quad I_3 = \begin{vmatrix} \sigma_{xx} & \sigma_{xy} & \sigma_{xz} \\ \sigma_{xy} & \sigma_{yy} & \sigma_{yz} \\ \sigma_{xz} & \sigma_{yz} & \sigma_{zz} \end{vmatrix}$$

### 6. Equivalent stress and strain

$$\text{Equivalent stress } \bar{\sigma} = \sqrt{\frac{1}{2} \{ (\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2 \}}^{1/2}$$

$$\text{Equivalent strain increment } d\bar{\varepsilon} = \sqrt{\frac{2}{3} \{ d\varepsilon_1^2 + d\varepsilon_2^2 + d\varepsilon_3^2 \}}^{1/2}$$

### 7. Yield criteria and flow rules

#### Tresca

Material yields when maximum value of  $|\sigma_1 - \sigma_2|$ ,  $|\sigma_2 - \sigma_3|$  or  $|\sigma_3 - \sigma_1| = Y = 2k$ , and then,

if  $\sigma_3$  is the intermediate stress,  $d\varepsilon_1 : d\varepsilon_2 : d\varepsilon_3 = \lambda(1 : -1 : 0)$  where  $\lambda \neq 0$ .

#### von Mises

Material yields when,  $(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2 = 2Y^2 = 6k^2$ , and then

$$\frac{d\varepsilon_1}{\sigma_1} = \frac{d\varepsilon_2}{\sigma_2} = \frac{d\varepsilon_3}{\sigma_3} = \frac{d\varepsilon_1 - d\varepsilon_2}{\sigma_1 - \sigma_2} = \frac{d\varepsilon_2 - d\varepsilon_3}{\sigma_2 - \sigma_3} = \frac{d\varepsilon_3 - d\varepsilon_1}{\sigma_3 - \sigma_1} = \lambda = \frac{3}{2} \frac{d\bar{\varepsilon}}{\bar{\sigma}}$$