$CKID$ **EERING TRIPOS PART IIB 2012** 4M13 COMPLEX ANALYSIS AND OPTIMIZATION Prof N A Fleck Module 4 M13: Complex Analysis $f(z) = z^2 \ln (z^2 + 1)^{1/3}$ $\overline{(\cdot)}$ $\overline{(\mathfrak{a})}$ 1 $f(z) = \frac{z^2}{2}$ $ln[(z+i)(z-i)]$ \Rightarrow = a zero at z = 0, branch points at z=t $\frac{7-a}{1}$ 0 $\frac{1}{1}$ (2) 0 $\frac{2}{1}$ $\frac{7}{1}$ $\frac{1}{1}$ $\frac{2}{1}$ As the $brank$ cut extends out to S o $\frac{1}{2}$ z - plane $f(z) = z - i$ (i) $7^2 + 12 + 2 =$ Now, $(z-i)$ $(z + z)$ $f(z) = 1$ \Rightarrow $\overline{?}$ S_{o} , $f(k)$ has a simple pole at $z=-2$; Residue is lim $[(z+i)]f(z) = 1$.

 $Cr1b$ for paper 4 M13 2012 1 (a) (iii) $f(z) = \frac{z^{1/3}}{s \cdot 1}$
 $\frac{s \cdot 1}{z-1}$ Branch points at Z = 0, 00 simple poles of $f(z)$ exist $\begin{array}{|c|c|c|c|}\hline \text{for each cut} \ \hline \text{(27+1)} & \text{(7-1)} & \text{(27-1)} & \text{(37-1)} \ \hline \end{array}$ Note that $sin(z + i) = 0$ at
 $z = n \pi - 1$, where n is an integer. => $f(z)$ has simple poles of $z = n\pi-1$. Residue at the pole Z= n m-1 is $\left(\wedge \pi - 1\right)^{1/5} \left(-1\right)^{n}$ $I(t)$ Calculate
 $f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{i\omega t} \frac{\omega + 1}{(\omega - 2i)^2} d\omega = i$ Consider the integrand $\tau(\omega) = \frac{\omega + 1}{(\omega - 2i)} e^{i\omega t}$
This has a pole of order 2 at $\omega = 2i$.

 $\left(\mathcal{L}\right)$ $\frac{1}{16}$ contrd. Crib for paper 4 M13 what is the residue of $\pi(\omega)$ at $\omega = 2$: ?
To determine this, expand the top line of
 $\pi(\omega)$ by a Tay lor Series Expansion, to Write $g(\omega) = (\omega + 1) e^{i\omega t}$ Then near $\omega = 2i$
we have $g(\omega)$ = $g(k!)$ + $(\omega - 2i)$ $g'(2i)$ + ---- $\frac{N_{0}\omega}{\int_{0}^{1}(\omega)}$, $\frac{1}{\int_{0}^{1}(\omega)} = e^{i\omega t} + (\omega + i) i t e^{i\omega t}$ and $q'(\omega = z_i) = e^{-2t} + (2i + 1) i t e^{-2t}$ S_{0} , g(w) = $(1+i)^{e^{-2t}} + (w-i)(e^{-2t}+k+i)^{t}e^{-2t}$ and the residue of I (w) is Res = $e^{-2t} + (2i+1) ite^{-2t}$ $= e^{-2t} [1 + i t (2i + 1)]$ Back to the integral $\frac{1}{2\pi}\int_{0}^{\infty}\frac{\mathcal{I}(\omega)}{d\omega}d\omega$ $t \le 0$ f(t) = 0 - close the
integral in the LHP by Jordon's Lemma
with no poler in the LHP

 $\frac{y+px+4y+1}{y+px+4y+3}$ $\overline{4}$ $contd.$ $\overline{\mathbf{(b)}}$ $\overline{\mathsf{L}}$ $t > 0$ $\boldsymbol{\omega}$ 2^{\cdot} , - ~"'~ '"' ,.~<>---< -~ ~~ ..-.-.----.-""~-~-. ~~ """"----.. ~--~~ "-.~ ~- ~-.,- the محامل the contour $U H P$ \overline{b} $\overline{\mathbf{o}}$ $\overline{\mathbf{w}}$ Jordans invoke L_{∞} Λ o contribution \sim the ℓ : integral ঠি \mathcal{L} $\mathbf{c} \wedge$ Se $-c$ \cdots ω 大っ at P d w \equiv $\mathcal{I}(\bm{\omega})$ سدل $\ddot{=}$ $\boldsymbol{\mathcal{I}}\left(\boldsymbol{\omega}\right)$ $2 - \pi$ \overline{C} ودرطسع S $\frac{1}{\pi}$ $\frac{1}{\pi}$ $\frac{x}{2\pi}$ 2.7 .. I $i \not \in$ $2i + 1$ $1 +$ e -- Granuner's comments: A popular and straightforward question, well-answered by most candidates. Several candidates struggled with part l(a)(iii) which had both poles and branch points. Most made appropriate use of Jordan's Lemma and shoed a good overall understanding of how to classify singularities and perform contour integration.

 C_{16} for 4 m 13 $f(z) = h z$
(z-1) QZ $\overline{a)}$ Write g(Z) = biz and expand about the $9(2) \times 9(2) + (2 - 2) - 9(2) + (2 - 2) - 9(2)$. Here, $z_0 = 1$ => $g(z_0) = g(1) = k_0(1) = 0$ $g'(z) = 1$ => $g'(1) = 1$ $g''(z) = -1$ => $g''(1) = -1$ => $q(z) \approx (z-1) + (z-1)^{2}(-1) + \cdots$ \Rightarrow $f(z)$ \approx $\frac{1}{z-1}$ \approx $\frac{1}{z-1}$ => Residue of $f(z)$ is 1 at $z=1$. Note f (z) has a simple pole
at z=1, not a pole of order 2.

 $\left(6\right)$ Crib for 4 Mis $\begin{array}{rcl}\n\text{21} & \text{22} & \text{21} \\
\hline\n\text{23} & \text{24} & \text{25} \\
\hline\n\text{24} & \text{260} & \text{260} \\
\hline\n\text{25} & \text{27} & \text{280} \\
\hline\n\text{260} & \text{27} & \text{280} \\
\hline\n\text{27} & \text{280} & \text{280} \\
\hline\n\text{280} & \text{280} & \text{280} \\
\hline\n\text{29} & \text{280} & \text{280} \\
\hline$ $\frac{1}{2}$ (b) integrand is singular at $\cos t = 1/e$
 $\frac{\cos t}{\sin t} = \frac{\pi}{3}, \frac{5\pi}{3}$ Note: $\frac{1}{2}$ The contour of integration s_o , the integrand has simple poles poth Hence, the need for defining Nou change variables: z=e^{it} \Rightarrow $dz = i \cdot dt$ As tincreases from 0 to 27, 2 moves
around the unit circle in the 2-plane. As $cot = \frac{1}{2}(e^{i\theta} + e^{-i\theta}) = \frac{1}{2}(z + \frac{1}{z})$ \Rightarrow $\tau = \frac{\rho \sqrt{2}}{i \epsilon} \frac{2}{(\epsilon + \frac{1}{2} - 1)} d \tau$

(子) $G1b$ for 4 $M13$ $\frac{2}{2}$ (b) contd. $\tau = \frac{9y}{1} \frac{2}{y} \oint_{C} \frac{1}{z^{2} - z + 1} dz$ $\frac{1}{\pi}\sqrt{\frac{1}{2}-\frac{1}{\pi}}$ (2²-2+1) as (2-x)(2-3) where $\alpha = 1 + i\sqrt{3}$ $\beta = 1 - i\sqrt{3}$ => \pm = $P.V.$ $\oint_C f(z) dz$ where $f(z) = z$ 1
i $(z-\alpha)(z-1)$ $\overline{\bigodot}$ $\frac{1}{\frac{1}{\sqrt{1-\frac{1}{2}}}}$ Contoir C is wit circle $I = \frac{\pi i}{\eta} \times sum$ of residues of $f(z)$
not $2\pi i$ on path of integration. Residue of $f(z)$ at $z = \alpha$ is $z = \frac{1}{\alpha - \beta} = -\frac{2}{\sqrt{3}}$ Residue of $f(z)$ at $z = \beta$ is $z = \frac{1}{\beta} = \frac{2}{\sqrt{3}}$ \Rightarrow Sum of residues = 0 $I = 0$

Grammer's comment

A popular question. Almost all know how to determine a Laurent Series and residues. Most understood the main ideas of Principal Values but many did not realize that the singularities were not on the contour of integration. Most struggled to evaluate the residues in part (b) correctly.

Question 3

 $L^2 = h^2 + \left(\frac{s}{2}\right)^2$ (a) From Fig. I:

$$
\therefore L^2 = 1^2 + \left(\frac{1.5}{2}\right)^2 = 1.5625 \implies L = 1.25 \text{ m}
$$

Also from Fig. 1:

$$
\sin \beta = \frac{h}{L} = \frac{1}{1.25} = 0.8
$$

 $\cos \beta = \frac{s}{2L} = \frac{1.5}{2 \times 1.25} = 0.6$

$$
P(x, y) = \frac{EA}{2L} \Big[\Big(x \cos \beta + y \sin \beta \Big)^2 + \Big(-x \cos \beta + y \sin \beta \Big)^2 \Big] - W \Big[x \cos \theta + y \sin \theta \Big]
$$

\n
$$
\therefore P(x, y) = \frac{EA}{2L} \Big[2x^2 \cos^2 \beta + 2y^2 \sin^2 \beta \Big] - W \Big[x \cos \theta + y \sin \theta \Big]
$$

\n
$$
\therefore P(x, y) = \frac{200 \times 10^9 \times 10^{-5}}{2 \times 1.25} \Big[2x^2 \times 0.6^2 + 2y^2 \times 0.8^2 \Big] - 10^4 \Big[x \cos 30 + y \sin 30 \Big]
$$

\n
$$
\therefore P(x, y) = 5.76 \times 10^5 x^2 + 1.024 \times 10^6 y^2 - 8.66 \times 10^3 x - 5 \times 10^3 y \Big]
$$
 [15%]

(b) The common scaling factor of $10³$ can be eliminated without changing the nature of the problem:

$$
\therefore P(x, y) = 576x^2 + 1024y^2 - 8.66x - 5y
$$

$$
\therefore \frac{\partial P}{\partial x} = 1152x - 8.66 \tag{1}
$$

$$
\therefore \quad \frac{\partial^2 P}{\partial x^2} = 1152 \tag{2}
$$

$$
\therefore \quad \frac{\partial P}{\partial y} = 2048y - 5 \tag{3}
$$

$$
\therefore \quad \frac{\partial^2 P}{\partial y^2} = 2048 \tag{4}
$$

$$
\therefore \quad \frac{\partial^2 P}{\partial x \partial y} = 0 \tag{5}
$$

From (1): $\frac{\partial P}{\partial t} = 1152x - 8.66 = 0 \implies x = \frac{8.66}{1152} = 7.52 \times 10^{-3}$ m ∂x 1152

From (3): $\frac{\partial P}{\partial y} = 2048y - 5 = 0 \Rightarrow y = \frac{5}{2048} = 2.44 \times 10^{-3} \text{ m}$

From (2), (4) and (5) the Hessian: $H = \begin{bmatrix} 1152 & 0 \\ 0 & 2019 \end{bmatrix}$ o 2048

By inspection H is positive definite, so this solution is a minimum. [20%]

(c) Let
$$
\mathbf{x}_{k+1} = \mathbf{x}_k + \alpha_k \mathbf{d}_k
$$

$$
f(\mathbf{x}_{k+1}) = f(\mathbf{x}_k + \alpha_k \mathbf{d}_k) = f(\mathbf{x}_k) + \alpha_k \nabla f(\mathbf{x}_k)^T \mathbf{d}_k + \frac{{\alpha_k}^2}{2} {\mathbf{d}_k}^T \mathbf{H}(\mathbf{x}_k) \mathbf{d}_k + R
$$

Neglecting *R* and differentiating with respect to α_k :

$$
\frac{\partial f}{\partial \alpha_k}(\mathbf{x}_k + \alpha_k \mathbf{d}_k) = \nabla f(\mathbf{x}_k)^T \mathbf{d}_k + \alpha_k \mathbf{d}_k^T \mathbf{H}(\mathbf{x}_k) \mathbf{d}_k
$$

For a minimum:

$$
\frac{\partial f}{\partial \alpha_k}(\mathbf{x}_k + \alpha_k \mathbf{d}_k) = \nabla f(\mathbf{x}_k)^T \mathbf{d}_k + \alpha_k \mathbf{d}_k^T \mathbf{H}(\mathbf{x}_k) \mathbf{d}_k = 0
$$
\n
$$
\therefore \quad \alpha_k = -\frac{\nabla f(\mathbf{x}_k)^T \mathbf{d}_k}{\mathbf{d}_k^T \mathbf{H}(\mathbf{x}_k) \mathbf{d}_k} \tag{15\%}
$$

 $\bar{\mathcal{A}}$

 $\label{eq:2.1} \frac{1}{\sqrt{2\pi}}\int_{\mathbb{R}^3}\frac{1}{\sqrt{2\pi}}\left(\frac{1}{\sqrt{2\pi}}\right)^2\frac{1}{\sqrt{2\pi}}\int_{\mathbb{R}^3}\frac{1}{\sqrt{2\pi}}\frac{1}{\sqrt{2\pi}}\frac{1}{\sqrt{2\pi}}\frac{1}{\sqrt{2\pi}}\frac{1}{\sqrt{2\pi}}\frac{1}{\sqrt{2\pi}}\frac{1}{\sqrt{2\pi}}\frac{1}{\sqrt{2\pi}}\frac{1}{\sqrt{2\pi}}\frac{1}{\sqrt{2\pi}}\frac{1}{\sqrt{2\pi}}\frac{$

(d) From (b):
\n
$$
\nabla f(x, y) = \begin{bmatrix} 1152x - 8.66 \\ 2048y - 5 \end{bmatrix}
$$
\nFor the SDM:
\n
$$
\mathbf{d} = -\nabla f = \begin{bmatrix} 8.66 - 1152x \\ 5 - 2048y \end{bmatrix}
$$
\n
$$
\therefore \alpha_t = \frac{\mathbf{d}_k^T \mathbf{d}_k}{}
$$

From (b):
\n
$$
\mathbf{H} = \begin{bmatrix} 1152 & 0 \\ 0 & 2048 \end{bmatrix}
$$
\nIf $\mathbf{x}_1 = (0,0)$:
\n
$$
\mathbf{H} = \begin{bmatrix} 1152 & 0 \\ 0 & 2048 \end{bmatrix}
$$

$$
\mathbf{d}_1 = \begin{bmatrix} \mathbf{x}_1 = (0,0); & \mathbf{d}_1 = \begin{bmatrix} 0.00\\ 5 \end{bmatrix} \\\\ \therefore \quad \alpha_1 = \frac{8.66^2 + 5^2}{\begin{bmatrix} 1152 & 0 \end{bmatrix} 8.66} \end{bmatrix}
$$

$$
\begin{bmatrix} 8.66 & 5 \end{bmatrix} \begin{bmatrix} 11.52 & 0 & 0.00 \\ 0 & 2048 & 5 \end{bmatrix} = 0.00
$$

\n
$$
\therefore \alpha_1 = \frac{8.66^2 + 5^2}{1152 \times 8.66^2 + 2048 \times 5^2} = 7.267 \times 10^{-4}
$$

\n
$$
\therefore \mathbf{x}_2 = \mathbf{x}_1 + \alpha_1 \mathbf{d}_1 = \begin{bmatrix} 0 \\ 0 \end{bmatrix} + 7.267 \times 10^{-4} \begin{bmatrix} 8.66 \\ 5 \end{bmatrix} = \begin{bmatrix} 6.294 \times 10^{-3} \\ 3.634 \times 10^{-3} \end{bmatrix}
$$

\n
$$
\therefore \mathbf{d}_2 = \begin{bmatrix} 8.66 - 1152 \times 6.294 \times 10^{-3} \\ 5 - 2048 \times 3.634 \times 10^{-3} \end{bmatrix} = \begin{bmatrix} 1.409 \\ -2.442 \end{bmatrix}
$$

\n
$$
\therefore \alpha_2 = \frac{1.409^2 + (-2.442)^2}{[1.409 - 2.442] \begin{bmatrix} 1152 & 0 \\ 0 & 2048 \end{bmatrix} \begin{bmatrix} 1.409 \\ -2.442 \end{bmatrix}
$$

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$$
\therefore \quad \alpha_2 = \frac{1.409^2 + 2.442^2}{1152 \times 1.409^2 + 2048 \times 2.442^2} = 5.482 \times 10^{-4}
$$
\n
$$
\therefore \quad \mathbf{x}_3 = \mathbf{x}_2 + \alpha_2 \mathbf{d}_2 = \begin{bmatrix} 6.294 \times 10^{-3} \\ 3.634 \times 10^{-3} \end{bmatrix} + 5.482 \times 10^{-4} \begin{bmatrix} 1.409 \\ -2.442 \end{bmatrix} = \begin{bmatrix} 7.066 \times 10^{-3} \\ 2.295 \times 10^{-3} \end{bmatrix}
$$
\n[35%]

(e) The Steepest Descent Method is making good progress towards the minimum. By inspection the eigenvalues of the Hessian are 1152 and 2048. Therefore the convergence ratio β is bounded by:

$$
\beta \le \left[\frac{A-a}{A+a}\right]^2 = \left[\frac{2048 - 1152}{2048 + 1152}\right]^2 = 0.0784
$$

This comparatively small value of β explains the good convergence.

The problem is quadratic so Newton's Method will converge in one iteration, and the Conjugate Gradient Method will converge in a number of iterations equal to the number of control variables, i.e. two iterations in this case. [15%]

Ganine's comment:

 \bullet .

A very popular question that was well done by many candidates. The most common sources of error were: a failure to check the second-order optimality conditions in part (b); and numerical slips in executing the Steepest Descent Method (SDM). Part (c), which asked for a standard derivation, was done surprisingly badly. Not many candidates recognised that they could straightforwardly calculate the upper bound on the SDM convergence ratio in part (e) to explain its performance.

Question 4

(a) The total cost of installation to be minimized is:

$$
f(D, L) = 150D^{2}L + 25D^{2.5}L + 20DL
$$

$$
T = 15D^{2}L \ge 100
$$

$$
\therefore g_{1} = 100 - 15D^{2}L \le 0
$$

In principle, there are non-negativity bounds on D and L , but it is obvious that they cannot be active if g_1 is to be satisfied, and can therefore be omitted. [10%]

(b) Assuming the constraint on *T* is active, the problem is:

Minimize $f(D, L) = 150D^2L + 25D^{2.5}L + 20DL$

subject to

subject to

The Lagrangian is $1 = 150D^2L + 25D^{2.5}L + 20DL + \lambda(100 - 15D^2L)$ $h_1 = 100 - 15D^2L = 0$

$$
\therefore \quad \frac{\partial}{\partial D} = 300DL + 62.5D^{1.5}L + 20L - 30\lambda DL = 0 \tag{1}
$$

$$
\frac{\partial}{\partial L} = 150D^2 + 25D^{2.5} + 20D - 15D^2\lambda = 0\tag{2}
$$

$$
100 - 15D^2 L = 0 \tag{3}
$$

From (1)
$$
300D + 62.5D^{1.5} + 20 - 30\lambda D = 0
$$
 (4)

From (2)
$$
15D^2 \lambda = 150D^2 + 25D^{2.5} + 20D
$$

$$
\therefore 30\lambda D = 300D + 50D^{1.5} + 40
$$

Substituting in (4)
$$
300D + 62.5D^{1.5} + 20 - 300D - 50D^{1.5} - 40 = 0
$$

$$
+20-300D-30D-40D-40
$$

$$
\therefore 12.5D^{1.5} = 20 \Rightarrow D = 1.368 \text{ m}
$$

From (3)

$$
L = \frac{100}{15D^2}
$$

$$
\therefore L = \frac{100}{15D^2} = \frac{100}{15(1.368)^2} = 3.562 \text{ m}
$$
 [40%]

(c) With the introduction of the new constraint we can no longer assume that the constraint on T is active, therefore we have now have a problem with two inequality constraints:

The Lagrangian is now:

$$
1 = 150D^2L + 25D^{2.5}L + 20DL + \mu_1(100 - 15D^2L) + \mu_2(DL - 4)
$$

 $\circled{3}$ 4M13 20

$$
\therefore \quad \frac{\partial}{\partial D} = 300DL + 62.5D^{1.5}L + 20L - 30\mu_1 DL + \mu_2 L = 0 \tag{1}
$$

$$
\frac{\partial}{\partial L} = 150D^2 + 25D^{2.5} + 20D - 15D^2\mu_1 + \mu_2 D = 0
$$
 (2)

$$
\mu_1 \big(100 - 15D^2 L \big) = 0 \tag{3}
$$

$$
\mu_2(DL-4)=0\tag{4}
$$

Case (i) $\mu_1 = 0$ and $\mu_2 = 0$

 $(2) \Rightarrow 150D^2 + 25D^{2.5} + 20D = 0$ \therefore $D = 0$ (impossible)

or $150D + 25D^{1.5} + 20 = 0 \implies$ no real non-negative solution for *D*

:. impossible

Case (ii) $\mu_1 = 0$ and $\mu_2 > 0$ $(2) \Rightarrow 150D^2 + 25D^{2.5} + 20D + \mu_2 D = 0$

 \therefore $D = 0$ (impossible)

or $\mu_2 = -150D - 25D^{1.5} - 20 \implies \mu_2 < 0$

:. not a minimum

Case (iii) $\mu_1 > 0$ and $\mu_2 = 0$

This is equivalent to the case solved in part (b) where the constraint on T is active and the constraint on A is inactive (in (b) it did not apply).

For this case we know that $D = 1.368$ m and $L = 3.562$ m.

We need to check that $g_2 = DL - 4 \le 0$ is not violated:

 $g_2 = 1.368 \times 3.562 - 4 = 0.873$:. g_2 is violated

:. impossible

Case (iv) $\mu_1 > 0$ and $\mu_2 > 0$

(3) ⇒ 100-15D²L = 0
\n∴ 15D²L = 100
\n(4) ⇒ DL-4=0 ⇒ L=
$$
\frac{4}{D}
$$

\n∴ 15D² $\frac{4}{D}$ = 100 ⇒ D= $\frac{5}{3}$ m ⇒ L=4× $\frac{3}{5}$ = 2.4 m
\n(1) ⇒ 300DL +62.5D^{1.5}L + 20L-30 μ_1 DL + μ_2 L = 0
\n∴ 300D + 62.5D^{1.5} + 20-30 μ_1 D + μ_2 = 0

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$$
300\left(\frac{5}{3}\right) + 62.5\left(\frac{5}{3}\right)^{1.5} + 20 - 30\mu_1\left(\frac{5}{3}\right) + \mu_2 = 0
$$

\n
$$
654.48 - 50\mu_1 + \mu_2 = 0
$$

\n
$$
(2) \Rightarrow 150D^2 + 25D^{2.5} + 20D - 15D^2\mu_1 + \mu_2D = 0
$$

\n
$$
150D + 25D^{1.5} + 20 - 15D\mu_1 + \mu_2 = 0
$$

\n
$$
150\left(\frac{5}{3}\right) + 25\left(\frac{5}{3}\right)^{1.5} + 20 - 15\left(\frac{5}{3}\right)\mu_1 + \mu_2 = 0
$$

\n
$$
323.79 - 25\mu_1 + \mu_2 = 0
$$

\n
$$
(5) - (6) \Rightarrow 330.69 - 25\mu_1 = 0 \Rightarrow \mu_1 = 13.228
$$

\n
$$
\therefore \mu_2 = 6.9
$$

\nAs $\mu_1 > 0$ and $\mu_2 > 0$ \therefore a minimum
\nThus, the new optimal design is $D = 1.667$ m and $L = 2.4$ m. [50%]

GCONINET'S COMMENTY:

Another very popular question, but not done as well as Q3. The average mark was also dragged down by the fact that the question that attracted a few very scratchy partial attempts. Most candidates showed that they had a good idea of how the Lagrange and Kuhn-Tucker Multiplier methods work. Algebraic mistakes were the most common cause of failure to answer part (b) (about Lagrange Multipliers). A number of candidates claimed dishonestly that the quoted solution solved their incorrect equations. This was penalised more harshly than answers where the candidate admitted that something must have gone wrong. Common problems in answering part (c) (about Kuhn-Tucker multipliers) were: not testing that the multipliers were positive at potential optima; not recognising that the solution to part (b) corresponded to one ofthe cases that needed testing; and failing to spot when cases could not correspond to a minimum because a multiplier would inevitably be negative for any physically plausible (i.e. non-negative) values of the control variables.