

Answers

- 2 (d) For $\omega \ll N$, $\mathbf{c}_g \rightarrow \frac{N}{k} \frac{\mathbf{k}_\perp}{k_\perp}$
For $\omega = N$, $\mathbf{c}_g \rightarrow 0$
- 3 (c) Condition is that κ is constant, not a function of position.
- (d) Condition is $\mathbf{a} = 0$; functional is $J = \frac{1}{2} \int \nabla \phi \cdot \nabla \phi \, dV$
- 4 (a)(i) $\nabla^2 u + f = 0$; $\lambda + \alpha f = 0$; $\nabla^2 \lambda + u - u_{\text{obs}} = 0$
- (a)(ii) Functional minimised is $J = \frac{1}{2} \int \left[(u - u_{\text{obs}})^2 + \alpha f^2 \right] dV$
- (b)(ii) First two equations as in (a)(i);
plus $\nabla^2 \lambda + u - u_{\text{obs}} + \mu = 0$; $\mu \left[\int u \, dV - \beta V \right] = 0$ (can't localise this one)

① (i) $T(x,t) = \frac{1}{2\sqrt{\pi\alpha t}} \exp[-x^2/4\alpha t]$

$$\frac{\partial T}{\partial t} = -\frac{1}{2} \frac{T}{t} + \frac{x^2}{4\alpha t^2} T$$

$$\frac{\partial T}{\partial x} = -\frac{x}{2\alpha t} T \Rightarrow \frac{\partial^2 T}{\partial x^2} = -\frac{1}{2\alpha t} T + \frac{x^2}{4\alpha^2 t^2} T$$

$$\Rightarrow \alpha \frac{\partial^2 T}{\partial x^2} = -\frac{1}{2t} T + \frac{x^2}{4\alpha t} T = \frac{\partial T}{\partial t} \quad \checkmark$$

For $x = 0$, $T(0, t \rightarrow 0) \rightarrow \infty$

For $x \neq 0$, $T(x, t \rightarrow 0) \sim \frac{1}{\sqrt{t}} \exp[-\frac{1}{t}] \rightarrow 0$

$$\int_{-\infty}^{\infty} T dx = \frac{1}{2\sqrt{\pi\alpha t}} \int_{-\infty}^{\infty} \exp[-\frac{x^2}{4\alpha t}] dx = \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} e^{-z^2} dz = 1$$

$$(z = x/2\sqrt{\alpha t})$$

So $T(t \rightarrow 0)$ is a δ -function. (35%)

(ii) Solution for δ -function of strength T_0 located at $x=x'$

$$T(x,t) = \frac{T_0}{2\sqrt{\pi\alpha t}} \exp\left[-\frac{(x-x')^2}{4\alpha t}\right]$$

By superposition, solution to initial condition $T_0(x')$ is then

$$T(x,t) = \int_{-\infty}^{\infty} \frac{T_0(x')}{2\sqrt{\pi\alpha t}} \exp\left[-\frac{(x-x')^2}{4\alpha t}\right] dx' \quad (30\%)$$

(iii) $T(x,t) = \hat{T} \int_0^{\infty} \frac{1}{2\sqrt{\pi\alpha t}} \exp\left[-\frac{(x-x')^2}{4\alpha t}\right] dx'$

$$\text{Let } z = x / 2\sqrt{\alpha t}$$

$$T(x, t) = \frac{T_0}{\sqrt{\pi}} \int_0^{\infty} e^{-(z-z')^2} dz'$$

$$= \frac{T_0}{\sqrt{\pi}} \int_{-z}^{\infty} e^{-p^2} dp \quad p = z' - z$$

$$= \frac{T_0}{\sqrt{\pi}} \int_0^{\infty} e^{-p^2} dp + \frac{T_0}{\sqrt{\pi}} \int_0^z e^{-p^2} dp$$

$$= \frac{T_0}{\sqrt{\pi}} \frac{\sqrt{\pi}}{2} + \frac{T_0}{2} \operatorname{erf} z$$

$$= \frac{T_0}{2} [1 + \operatorname{erf} z]$$

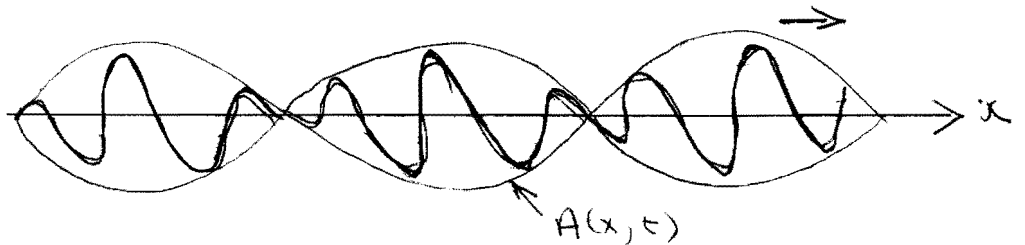
$$= \underline{\underline{\frac{T_0}{2} [1 + \operatorname{erf}(x/2\sqrt{\alpha t})]}} \quad (35\%)$$

$$\begin{aligned}
 \textcircled{2} \text{ (i)} \quad \eta &= A_0 \cos(k_1 x - \omega_1 t) + A_0 \cos(k_2 x - \omega_2 t) \\
 &= A_0 2 \cos\left(\frac{1}{2}(k_1 + k_2)x - \frac{1}{2}(\omega_1 + \omega_2)t\right) \cos(\delta k x - \delta \omega t) \\
 &= 2A_0 \cos(\bar{k}x - \bar{\omega}t) \cos(\delta k x - \delta \omega t) \\
 \bar{k} &= \frac{1}{2}(k_1 + k_2), \quad \bar{\omega} = \frac{1}{2}(\omega_1 + \omega_2)
 \end{aligned}$$

Rewrite as

$$\eta = A(x, t) \cos(\bar{k}x - \bar{\omega}t)$$

$$A = 2 \cos(\delta k x - \delta \omega t) = 2 \cos(\delta k(x - c_g t))$$



Amplitude propagates in the x -direction at speed

$$c_g = \delta \omega / \delta k$$

(20%)

$$\textcircled{2} \text{ (ii)} \quad \frac{\partial^2}{\partial t^2} \hat{u}_z + N^2 \nabla_{\perp}^2 \hat{u}_z = 0$$

$$\Rightarrow (-\omega^2)(-k^2) \hat{u}_z + N^2 (-k_{\perp}^2) \hat{u}_z = 0$$

$$\Rightarrow \omega^2 = \frac{N^2 k_{\perp}^2}{k^2}$$

$$\Rightarrow \underline{\underline{\omega = N k_{\perp} / k}}$$

$$\begin{aligned}
 c_{\omega, x} &= \frac{\partial \omega}{\partial k_x} = \frac{N}{R} \frac{\partial R_L}{\partial k_x} + N k_L \frac{\partial}{\partial k_x} \left(\frac{1}{R} \right) \\
 &= \frac{N}{R} \frac{k_x}{k_L} + N k_L \left(-\frac{k_x}{R^3} \right) \\
 &= \frac{N k_x}{R^3 k_L} (k^2 - k_L^2) \\
 &= \frac{N k_x k_z^2}{R^3 k_L} \quad (\text{similar for } c_{\omega, y})
 \end{aligned}$$

$$c_{\omega, z} = \frac{\partial \omega}{\partial k_z} = N k_L \frac{\partial}{\partial k_z} \left(\frac{1}{R} \right) = N k_L \left(-\frac{k_z}{R^3} \right) = -\frac{N k_z k_L^2}{R^3 k_L}$$

$$\Rightarrow \vec{c}_{\omega} = \frac{N}{R^3 k_L} (k_x k_z^2, k_y k_z^2, -k_z k_L^2)$$

Compare,

$$\vec{c}_{\omega} = \frac{N}{R^3 k_L} (k_{||}^2 k_{\perp}^2 - k_{\perp}^2 k_{||}^2) = \frac{N}{R^3 k_L} (k_z^2 k_x, k_z^2 k_y, -k_L^2 k_z)$$

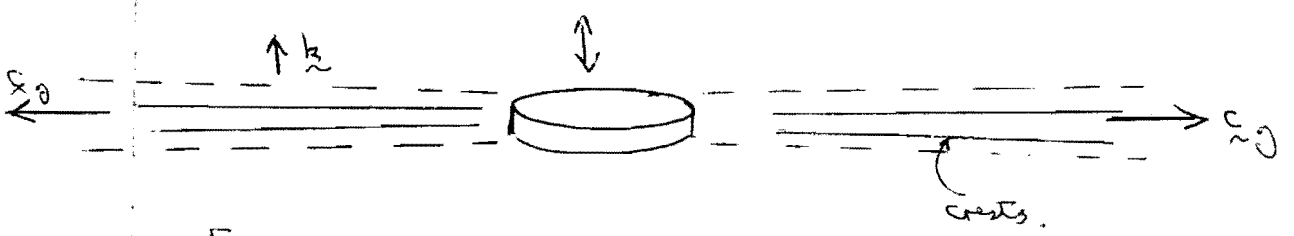
Phase velocity is \parallel to \vec{k} ,

$$\vec{c}_{\omega} \cdot \vec{k} = \frac{N}{R^3 k_L} (k_{||}^2 \underbrace{k_{\perp} \cdot \vec{k}}_{k_{\perp}^2} - k_{\perp}^2 \underbrace{k_{||} \cdot \vec{k}}_{k_{||}^2}) = 0 \quad (45\%)$$

(iii)

For $\omega \rightarrow 0$, $k_L \rightarrow 0$ and $k \rightarrow k_z$

$$\Rightarrow \vec{k} \approx k_{||} \hat{z}, \quad \vec{c}_{\omega} \approx \frac{N k_L}{R k_L} = \frac{N}{R} \cdot \frac{k_L}{k_L}$$

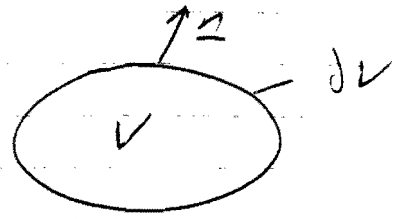


For $\omega \rightarrow \infty$, $k_z \rightarrow 0 \Rightarrow \vec{c}_{\omega} = 0$, No dispersion of energy (35%)

3.

a)

5

Conservation of ϕ :

$$\frac{d}{dt} \int_V \phi dV = - \int_{\partial V} (\phi \underline{u}) \cdot \underline{n} dS$$

↑
rate of increase of ϕ
in V

↑ rate at which
 ϕ enters domain
(-ve sign because \underline{n}
points outward)

Apply divergence theorem:

$$\frac{d}{dt} \int_V \phi dV = - \int_V \nabla \cdot (\phi \underline{u}) dV$$

Must also hold for an arbitrary sub-volume
 $V_s \subset V$, hence can localise:

$$\frac{d\phi}{dt} + \nabla \cdot (\phi \underline{u}) = 0$$

- Expand,

$$\frac{d\phi}{dt} + \nabla \phi \cdot \underline{u} + \phi \nabla \cdot \underline{u} = 0$$

Since $\nabla \cdot \underline{u} = 0$ (incompressible),

$$\frac{d\phi}{dt} + \underline{u} \cdot \nabla \phi = 0 \quad (30\%)$$

(6)

$$3b. \quad \frac{d\phi}{dt} + \underline{a} \cdot \frac{\partial \phi}{\partial \underline{x}_i} = 0 \quad (10\%)$$

$$c) \quad \underline{g} = \phi \underline{a} - k \nabla \phi$$

Balance:

$$\frac{d}{dt} \int_V \phi \, dV = - \int_{\partial V} (\phi \underline{a} + k \nabla \phi) \cdot \underline{n} \, dS$$

Diverg. theorem:

$$\frac{d}{dt} \int_V \phi \, dV = - \int_{\partial V} \nabla \cdot (\phi \underline{a}) + \nabla \cdot (k \nabla \phi) \, dS$$

$$\rightarrow \frac{d\phi}{dt} + \nabla \cdot (\phi \underline{a}) - \nabla \cdot (k \nabla \phi) = 0$$

Expand

$$\frac{d\phi}{dt} + \nabla \phi \cdot \underline{a} + \phi \nabla \cdot \underline{a} - \nabla k \cdot \nabla \phi - k \nabla^2 \phi = 0$$

\rightarrow k must be constant. (30%)

$$d) \text{ Steady state: } \underline{a} \cdot \nabla \phi - k \nabla^2 \phi = 0$$

Multiply by w & integrate

$$a(w, w) = \int_V w \underline{a} \cdot \nabla \phi \, dV - \int_V w k \nabla^2 \phi \, dV = 0$$

Int by parts last term:

$$a(w, w) = \int_V w \underline{a} \cdot \nabla \phi \, dV + \int_V \nabla w \cdot (k \nabla \phi) - \int_{\partial V} w k \nabla \phi \cdot \underline{n} \, dS$$

⑦

d) cont. Bilinear form a D symmetric
when $\underline{a} = \underline{0}$

→ Correspond to Poisson problem:

$$J = \frac{1}{2} \int \nabla \phi \cdot \nabla \phi \, dV \quad \rightarrow \quad \int \phi \quad (30\%)$$

8

4

a) i) Unknown are λ , u & f .
Take derivative (variation) w.r.t.
each unknown & set equal to zero.

$$DF_{\lambda} = \int_V \bar{\lambda} (\nabla^2 \bar{u} + f) dV = 0 \quad (1)$$

$$DF_{\bar{u}} = \int_V \bar{\lambda} (\nabla^2 \bar{u}) + (u - u_{obs}) \bar{u} dV = 0 \quad (2)$$

$$DF_f = \int_V \bar{\lambda} \bar{f} + \alpha \bar{f} \bar{f} dV = 0 \quad (3)$$

Follow usual process to ~~isolate~~ ^{isolate} \bar{u} ,

$$(1) \quad \nabla^2 \bar{u} + f = 0$$

(2) Integrate by parts twice

$$-\int_V \nabla \bar{\lambda} \cdot \nabla \bar{u} + (u - u_{obs}) \bar{u} dV + \int_S \bar{\lambda} \nabla \bar{u} \cdot n dS$$

Again $\int_V \nabla^2 \bar{\lambda} \bar{u} + (u - u_{obs}) \bar{u} dV + \int_S \bar{\lambda} \nabla \bar{u} \cdot n dS$

$$\rightarrow \nabla^2 \bar{\lambda} + (u - u_{obs}) = 0 \quad - \int_S \nabla \bar{\lambda} \cdot n \bar{u} dS \quad (30\%)$$

from here.

$$(3) \quad \lambda + \alpha f = 0$$

$$(ii) \quad J = \int_V \frac{1}{2} (u - u_{obs})^2 + \frac{\alpha}{2} f^2 dV \quad (10\%)$$

(9)

b) i) Need to add extra constraint: $\int_V u dV - \beta = 0$
 \rightarrow add extra Lagrange multiplier:

$$F^{\text{mod}} = \int_V \lambda_1 (\nabla^2 u + f) + \frac{1}{2} (u - u_{\text{cons}})^2 + \frac{\alpha}{2} f^2$$

$$+ \lambda_2 \left[\int_V u dV - \beta \right]$$

\downarrow does not depend on position (20%)

ii) Compute directional derivative wrt λ_1, λ_2, u & f

$$DF_{\lambda_1} = \int_V \lambda_1 (\nabla^2 u + f) dV = 0$$

$$\rightarrow \nabla^2 u + f = 0$$

$$DF_{\lambda_2} = \lambda_2 \left[\int_V u dV - \beta \right] = 0$$

(cannot localize this expression)

$$DF_u = \int_V \lambda_1 (\nabla^2 \bar{u}) + (u - u_{\text{cons}}) \bar{u} dV$$

$$+ \lambda_2 \int_V \bar{u} dV = 0$$

$$\rightarrow \int_V \nabla^2 \lambda_1 \bar{u} + (u - u_{\text{cons}}) \bar{u} + \lambda_2 \bar{u} dV = 0$$

$$\rightarrow \nabla^2 \lambda_1 + u - u_{\text{cons}} + \lambda_2 = 0$$

$$DF_f = \int_V \lambda_1 \bar{f} + \alpha f \bar{f} dV$$

$$\rightarrow \lambda_1 + \alpha f = 0 \quad (40\%)$$

Note: ~~Method problem~~ To solve numerically, use Galerkin method set