EGT2 ENGINEERING TRIPOS PART IIA

Tuesday 28 April 2015 9.30 to 11

Module 3F1

SIGNALS AND SYSTEMS

Answer not more than **three** questions.

The *approximate* number of marks allocated to each part of a question is indicated in the right margin.

Answers to questions in each section should be tied together and handed in separately.

Write your candidate number <u>not</u> your name on the cover sheet.

STATIONERY REQUIREMENTS

Single-sided script paper

SPECIAL REQUIREMENTS TO BE SUPPLIED FOR THIS EXAM

CUED approved calculator allowed Engineering Data Book

10 minutes reading time is allowed for this paper.

You may not start to read the questions printed on the subsequent pages of this question paper until instructed to do so.

1 Consider the discrete-time system given by the following difference equation

$$y_{k+1} = \frac{1}{2}y_k + u_k + d_k, \quad y_0 = 0 \tag{1}$$

where y_k is the output, u_k is the input and d_k is a disturbance that we wish to attenuate. Consider also the feedback controller given by

$$u_{k+1} = au_k - \frac{1}{4}y_k, \quad u_0 = 0 \tag{2}$$

where *a* is a constant to be determined.

(a) From equation (1), find the transfer functions G(z) and P(z) in Y(z) = G(z)U(z) + P(z)D(z). [20%]

(b) From equation (2), find the transfer function of the controller K(z) from Y(z) to U(z). [10%]

(c) Show that the closed-loop transfer function M(z) from D(z) to Y(z) is given by

$$M(z) = \frac{z-a}{(z-\frac{1}{2})(z-a) + \frac{1}{4}}$$
[20%]

(d) Assume that the disturbance d_k is a step. Find the value of the constant *a* that minimises the effect of the disturbance of the closed-loop system in steady-state. [30%]

(e) Let a = 0 and assume now that the disturbance is given by $d_k = \cos(k)$. Determine the behaviour of y_k as k becomes large. [20%]

2 (a) (i) Consider the four frequency plots in Fig. 1. Indicate which one corresponds to the transfer function

$$G(z) = \frac{0.5}{(z - 0.5)z}$$

Justify your answer.

(ii) Sketch the frequency plot (magnitude and phase) of $G(z)^{10}$. [20%]

(b) A random variable Y is to be generated from a random variable X using the monotonic increasing function Y = g(X).

(i) Show that $f_Y(y)$, the probability density function (pdf) of Y, is related to $f_X(x)$, the pdf of X, by

$$f_Y(y) = \frac{f_X(x)}{g'(x)}$$

where y = g(x) and $\frac{dy}{dx} = g'(x)$.

(ii) Let X be uniformly distributed over $\left(-\frac{\pi}{2}, \frac{\pi}{2}\right)$. Determine g(x) such that Y has a Cauchy pdf

$$f_Y(y) = \frac{1}{\pi(1+y^2)}$$
[Hint: $\frac{d\tan x}{dx} = 1 + \tan^2 x$.] [25%]

[30%]

[25%]

Version JS/3



Fig. 1

3 Two independent random variables X_1 and X_2 have probability density functions (pdfs) $f_1(x)$ and $f_2(x)$.

(a) A new process Y is formed from the sum of X_1 and X_2 . Show that the conditional pdf of Y, given that $X_1 = x_1$, is given by

$$f(y|x_1) = f_2(y - x_1)$$

and show that the pdf of Y, $f_Y(y)$, is given by the convolution of f_1 with f_2 . [25%]

(b) The characteristic function of a random variable X is given by

$$\Phi_X(u) = E[e^{juX}]$$

where E[.] is the expectation operator. For $Y = X_1 + X_2$, derive an expression for $\Phi_Y(u)$ in terms of $\Phi_{X_1}(u)$ and $\Phi_{X_2}(u)$. [25%]

(c) Suppose there are *N* mutually independent random variables X_i , i = 1, ..., N. Each X_i has pdf $f_i(x)$ and characteristic function $\Phi_{X_i}(u)$. Derive an expression for $\Phi_Y(u)$, where $Y = \sum_{i=1}^N X_i$. [15%]

(d) A binary valued random variable X has the Bernoulli distribution

$$P_X(x) = \begin{cases} 1-p & x=0\\ p & x=1 \end{cases}$$

for $0 . Derive an expression for the characteristic function <math>\Phi_X(u)$. [10%]

(e) An experimenter conducts N independent tests, each of which succeeds with probability p and fails with probability 1 - p. The random variable Y counts the number of successes, and has the binomial distribution

$$P_Y(n) = \binom{N}{n} p^n (1-p)^{N-n} \text{ for } n = 0, \dots, N$$

Derive an expression for $\Phi_Y(u)$ and explain its relationship to the characteristic function of the Bernoulli distribution. [25%]

4 (a) For which of the following collections of lengths does there exist a binary prefix-free code? Justify your answer.

- (i) (1,2,3,4,5)
- (ii) (1,2,3,3,4)
- (iii) (2,2,2,2,2)
- (iv) (2,2,3,3,3)

[15%]

[15%]

(b) A discrete random variable X over the alphabet $\{A, B, C, D, E\}$ has the probability mass function

x	Α	В	С	D	E
$P_X(x)$	0.8	0.07	0.06	0.02	0.05

(i) Calculate the entropy of X in nats and in bits.

(ii) Design a Huffman code for *X* and calculate the resulting expected codeword length. [15%]

(iii) Consider a discrete random process $X_1, X_2, X_3, ...$ consisting of independent and identically distributed random variables, each with the same probability mass function as X. State an upper bound on the expected codeword length per symbol attainable by Huffman coding for blocks of 1, 2 and 10 symbols. [20%]

(c) Let l_1, l_2, l_3, l_4, l_5 be the lengths of the codewords of the Huffman code for a random variable *X* with probability mass function $(p_1, p_2, p_3, p_4, p_5)$ such that $p_1 \ge p_2 \ge p_3 \ge p_4 \ge p_5$.

- (i) Show that $l_1 \le l_2 \le l_3 \le l_4 \le l_5$. [15%]
- (ii) A random variable X' has probability mass function

$$\left(p_1, p_2, p_3, p_4, \frac{p_5}{2}, \frac{p_5}{2}\right)$$

How do the lengths $l'_1, l'_2, l'_3, l'_4, l'_5, l'_6$ of the Huffman code for X' relate to the lengths l_1, l_2, l_3, l_4, l_5 of the Huffman code for X? [20%]

END OF PAPER

Numerical Answers:

- 1. (d) a = 1, with stable poles at $z = 0.75 \pm i0.433$
- (e) Stable system with steady state output $y_k = 1.5267 \cos(k 1.2997)$
- 2. (a) (i) C
 - (ii) Same plot with y axes rescaled by a factor of 10 (both magnitude and phase).
- (b) (ii) g(x) = tan(x).
- 4. (a) yes, no, no, yes
- (b) (i) 0.76 nats, 1.10 bits
 - (ii) E[L] = 1.4 binary symbols per codeword
 - (iii) upper bounds 2.1, 1.6 and 1.2 for K = 1, 2, 10, respectively.