EGT3 / EGT2
ENGINEERING TRIPOS PART IIB / ENGINEERING TRIPOS PART IIA

Wednesday 22 April $2015 \quad 2.00$ to 3.30

Module 4M12
PARTIAL DIFFERENTIAL EQUATIONS AND VARIATIONAL METHODS

Answer not more than three questions.
All questions carry the same number of marks.
The approximate percentage of marks allocated to each part of a question is indicated in the right margin.

Write your candidate number not your name on the cover sheet.

## STATIONERY REQUIREMENTS

Single-sided script paper

## SPECIAL REQUIREMENTS TO BE SUPPLIED FOR THIS EXAM

CUED approved calculator allowed
Engineering Data Book

## 10 minutes reading time is allowed for this paper.

You may not start to read the questions printed on the subsequent pages of this question paper until instructed to do so.

Version JL/2

1 (a) Consider the Poisson equation

$$
\begin{equation*}
\nabla^{2} u=\delta \tag{1}
\end{equation*}
$$

where $\delta$ is the three-dimensional delta function which satisfies

$$
\begin{gathered}
\delta=0, \quad x \neq 0 \\
\int \delta d V=1
\end{gathered}
$$

for any volume including the origin. Show that the trial solution

$$
\begin{equation*}
u=-\frac{1}{4 \pi r}, \quad r=|x| \tag{2}
\end{equation*}
$$

satisfies $\nabla^{2} u=0$ for $\boldsymbol{x} \neq 0$ as well as the integral condition

$$
\oint_{S_{R}} \nabla u \cdot d \boldsymbol{S}=1
$$

where $S_{R}$ is a spherical control surface of radius $R$, centered at the origin. Hence confirm that the trial solution (2) is indeed the solution of (1) in an infinite domain.
(b) Let $\boldsymbol{A}$ be the vector potential of the static magnetic field $\boldsymbol{B}$, where $\boldsymbol{B}=\nabla \times \boldsymbol{A}$ and $\nabla \cdot \boldsymbol{A}=0$. The distribution of $\boldsymbol{B}$ is governed by Ampère's law,

$$
\nabla \times \boldsymbol{B}=\mu_{0} \boldsymbol{J}
$$

where $\mu_{0}$ is the permeability of free space and $\boldsymbol{J}$ the current density. Confirm that

$$
\begin{equation*}
\nabla^{2} \boldsymbol{A}=-\mu_{0} \boldsymbol{J} \tag{3}
\end{equation*}
$$

and use the result of (a), along with superposition, to derive the Green's function solution to (3) :

$$
A(\boldsymbol{x})=\frac{\mu_{0}}{4 \pi} \int \frac{\boldsymbol{J}\left(x^{\prime}\right)}{\left|\boldsymbol{x}-\boldsymbol{x}^{\prime}\right|} d V^{\prime}
$$

(c) Now show that this Green's function solution is equivalent to the Biot-Savart law

$$
\boldsymbol{B}=-\frac{\mu_{0}}{4 \pi} \int \frac{\boldsymbol{r} \times \boldsymbol{J}\left(x^{\prime}\right)}{|\boldsymbol{r}|^{3}} d V^{\prime}, \quad \boldsymbol{r}=\boldsymbol{x}-\boldsymbol{x}^{\prime}
$$

You may use the identity

$$
\nabla \times\left[\frac{\boldsymbol{J}\left(\boldsymbol{x}^{\prime}\right)}{\left|\boldsymbol{x}-\boldsymbol{x}^{\prime}\right|}\right]=\nabla\left[\frac{1}{\left|\boldsymbol{x}-\boldsymbol{x}^{\prime}\right|}\right] \times \boldsymbol{J}\left(\boldsymbol{x}^{\prime}\right) .
$$

where $\nabla$ operates on $\boldsymbol{x}$, not on $\boldsymbol{x}^{\prime}$.

## Version JL/2

2 (a) Consider a beam of flexural rigidity $E I$ and mass per unit length $\rho A$. It sits on an elastic foundation which exerts a restoring force per unit length of $S \eta$, where $S$ is a constant, and $\eta(x, t)$ the vertical displacement of the beam. The equation of motion is

$$
E I \frac{\partial^{4} \eta}{\partial x^{4}}+S \eta+\rho A \frac{\partial^{2} \eta}{\partial t^{2}}=0
$$

which supports flexural vibrations. By considering a solution of the form

$$
\eta=\exp [i(k x-\omega t)],
$$

show that the ratio of the group velocity $c_{g}$ to phase speed $c_{p}$ is

$$
\frac{c_{g}}{c_{p}}=\frac{2 E I k^{4}}{E I k^{4}+S} .
$$

(b) Show that the group velocity of a wave packet is equal to the phase speed when the dominant wavelength satisfies

$$
k_{0}=(S / E I)^{1 / 4} .
$$

A beam of infinite length is subject to a localised initial displacement of dominant wavenumber $k$. Describe the resulting wave pattern distinguishing between the speed of the wave crests and that of the overall wave packets. Consider both the case $k>k_{0}$ and $k<k_{0}$.
(c) A flat plate of flexural rigidity $D$ sits on an elastic foundation of stiffness $S$ and its transverse displacement $\eta(x, y, t)$ is governed by

$$
D \nabla^{4} \eta+S \eta+\rho A \frac{\partial^{2} \eta}{\partial t^{2}}=0
$$

where $\nabla^{4}$ is the biharmonic operator

$$
\nabla^{4}=\left(\frac{\partial^{2}}{\partial x^{2}}+\frac{\partial^{2}}{\partial y^{2}}\right)^{2}
$$

Show that the ratio of the group velocity to phase speed is now

$$
\frac{\boldsymbol{c}_{g}}{c_{p}}=\frac{2 D k^{3} \boldsymbol{k}}{D k^{4}+S}, \quad k=|k|
$$

where $\boldsymbol{k}$ is the wavevector. In what way is the direction of wave energy propagation fundamentally different to that of inertial waves in a rapidly-rotating fluid or internal gravity waves in a stratified fluid?

## Version JL/2

3 We wish to determine the stationary function $u(x)$ for

$$
I(u)=\int_{0}^{1}\left(u^{\prime}\right)^{2} d x, u(0)=0,
$$

subject to the constraint

$$
\int_{0}^{1} u^{2} d x=1
$$

using the Lagrangian multiplier method. Note that $u(1)$ is not specified, but rather $u(1)$ is to be determined along with the stationary function.
(a) Write down the augmented integrand of the constrained functional.
(b) Deduce the Euler equation for the augmented functional.
(c) What is the boundary condition for $u(x)$ at $x=1$ ?
(d) Deduce the stationary function $u(x)$ of this question.

Version JL/2

4 Consider the differential equation

$$
\begin{equation*}
\frac{d}{d x}\left(x \frac{d u}{d x}\right)=-1 \tag{4}
\end{equation*}
$$

with boundary conditions

$$
u(1)=0, \quad u(2)=-1
$$

Suppose the interval [1,2] is partitioned in $n$ uniform cells $x_{0}=1<x_{1}<\ldots<x_{i}<\ldots<$ $x_{n}=2$ such that $x_{i+1}-x_{i}=h$ is constant. The piecewise linear 'hat-like' function $\phi_{i}$ is defined as $\phi_{i}\left(x_{j}\right)=\delta_{i j}$, where $\delta_{i j}$ is Kronecker delta, and $i, j=0, \cdots, n$.
(a) Deduce the weak form of Eqn. (4).
(b) Deduce the equivalent variational form of Eqn. (4).
(c) For $i, j=0, \cdots, n$, calculate

$$
K_{i j}=\int_{1}^{2} x \frac{d \phi_{i}}{d x} \frac{d \phi_{j}}{d x} d x
$$

(d) Suppose $n=2$. Calculate the approximate solution for $u(x)$ using the Galerkin method with the trial function

$$
\bar{u}=c_{0} \phi_{0}+c_{1} \phi_{1}+c_{2} \phi_{2},
$$

where $c_{0}, c_{1}$ and $c_{2}$ are constants to be determined.
(e) Compare the above approximate solution with the exact solution of Eqn. (4) and explain your result.

## END OF PAPER

Version JL/2

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Module 4M12: Partial differential equations and variational methods, 2015 Numeric value of Q4, (e) : $u_{1}=0, u_{1}=-1 / 2, u_{2}=-1$.

